



ESA Sea Level CCI

D2.8 INPUT OUTPUT DATA DOCUMENT (IODD)

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Applicable documents

AD 1 Sea level CCI project Management Plan
CLS-DOS-NT-10-013

Reference documents

RD 1 Manuel du processus Documentation
CLS-DOC

RD 2 PVSAR: Selection Meeting Report
CLS-DOC-NT-12-125

RD 3 Algorithm Theoretical Basis Document (ATBDv1)
CLS-DOC-NT-11-009

RD 4 ALGORITHM DEFINITION, ACCURACY AND SPECIFICATION - BIBLI_ALTI : ALTIMETER
LEVEL 2 PROCESSING: SALP-ST-BA-EA-15598-CN

RD 5 ALGORITHM DEFINITION, ACCURACY AND SPECIFICATION - SSALTO-DUACS :
ALTIMETER LEVEL 3 and 4 PROCESSING: CLS-DOC-NT-10-128



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1. Introduction

1.1. Purpose and scope

This document is the input output data document (IODD) for the Sea Level ECV project. It describes the sets of data, which are inputs to, or outputs from the components of the sea Level processing system for the ESA Climate Change Initiative (CCI). The Sea Level processing system will be used to generate and continuously update the Sea Level FCDR and ECV products.

Most of the data defined in this document have already been described in detail in the frame of SSALTO programme. Therefore most of the data sets named in this document are briefly described, with references to the original defining document. For input or output data sets not described elsewhere, a detailed description is given.

1.2. Document structure

After this formal introduction,

- section 2 provides an overview of the Sea Level CCI processing chain and the data required for input and produced as output
- section 3 lists and describes the Level 2 data used in the Sea Level CCI processing system
- section 4 lists and describes the Level 3 data used in the Sea Level CCI processing system
- section 5 lists and describes the Level 4 data used in the Sea Level CCI processing system
- section 6 lists and describes the Level 5 data used in the Sea Level CCI processing system
- section 6 lists and describes the auxiliary data used in the Sea Level CCI processing system

2. The sea level processing chain and its products

This chapter intends to present an overview of the different processing steps activated to produce the Sea-Level CCI ECV products.

The following figure gives an overview of Sea-Level CCI system based on the CNES SSALTO/DUACS ground segment, where processing sequences can be divided into 8 main steps:

- Acquire Data
- Pre process data
- Perform input checks and Quality Control
- Generate Products
- Performs output checks and Quality Control
- Do measures and built indicators
- Store the built product datasets
- Archive / Retrieve a "Product Dataset"

The product generation is divided into three sub-steps:



- Inter calibrate & Unify
- Generate along track product
- Generate merged product

Each step has its sequence of algorithms that can be activated to generate Sea-Level CCI ECV products.

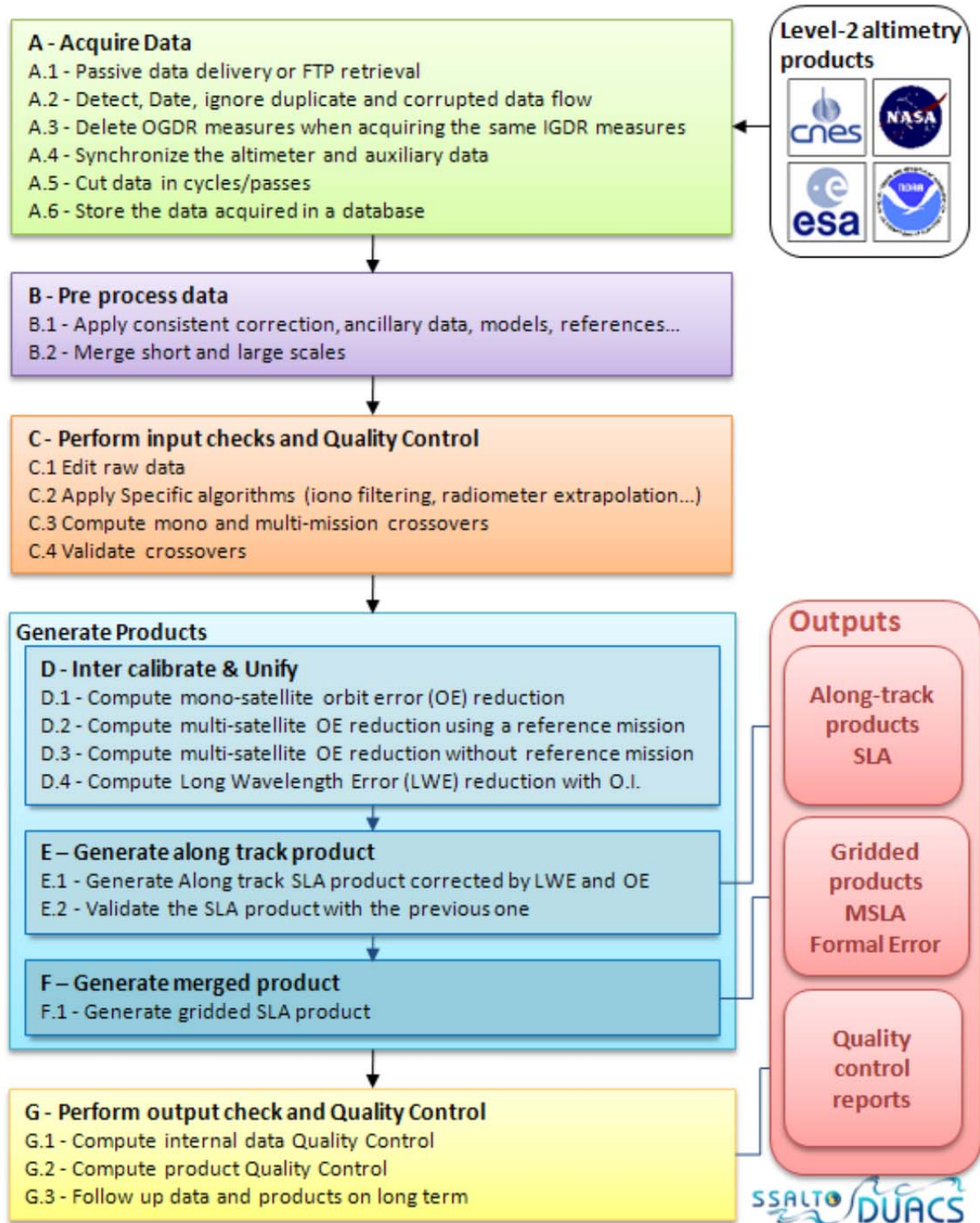


Figure 1: Main components of the Sea-Level CCI system, based on the CNES SSALTO/DUACS



3. Level 2 data

3.1. Topex-Poseidon data

3.1.1. Filenaming convention

The nomenclature of GDR-M CYCLE HEADER FILE is:

MGxccc.HDR

where:

- M is for the AVISO Merged product.
- G is for the GDR data type(1).
- x is the generation letter (A to Z) (1). [At the date of edition 3, x = C.]
- ccc is the cycle number(2) .
- HDR is for a header file.

The nomenclature of GDR-M PASS-FILES is:

MGxccc.ppp

where:

- M is for the AVISO merged product.
- G is for the GDR data type(1).
- x is the generation letter (A to Z)(1). [At the date of edition 3, x = C.]
- ccc is the cycle number(2).
- ppp is the pass-file number (001 to 254).

3.1.2. Product data format

3.1.2.1. MGDR_cycle_header

id	field name	Definition
0	EDU_label	ascii string size: 20 CCSDS EDU Label fixed value: "CCSD3ZF0000100000001" hidden: true
1	white_space_1	ascii string size: 58 white space fixed value: " "



		hidden: true
2	cr_newline_1	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
3	Header_label	ascii string <i>size: 20</i> CCSDS Header Label fixed value: "CCSD3KS00006CYCLEHDR" hidden: true
4	white_space_2	ascii string <i>size: 58</i> white space fixed value: " " hidden: true
5	cr_newline_2	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
6	Producer_Agency_Name_label	ascii string <i>size: 23</i> Producer_Agency_Name = fixed value: "Producer_Agency_Name = " hidden: true
7	Producer_Agency_Name	ascii string <i>size: 4</i> The name of the government agency in charge of this product
8	semicolon_mark_1	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true



9	white_space_3	ascii string <i>size: 50</i> white space fixed value: " " hidden: true
10	cr_newline_3	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
11	Producer_Institution_Name_label	ascii string <i>size: 28</i> Producer_Institution_Name = fixed value: "Producer_Institution_Name = " hidden: true
12	Producer_Institution_Name	ascii string <i>size: 5</i> The name of the institution producing the file
13	semicolon_mark_2	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
14	white_space_4	ascii string <i>size: 44</i> white space fixed value: " " hidden: true
15	cr_newline_4	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
16	source_label	ascii string <i>size: 14</i> Source_Name =



		fixed value: "Source_Name = " hidden: true
17	source	ascii string <i>size: 14</i> Name of the project
18	semicolon_mark_3	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
19	white_space_5	ascii string <i>size: 49</i> white space fixed value: " " hidden: true
20	cr_newline_5	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
21	Sensor_Name_label	ascii string <i>size: 14</i> Sensor_Name = fixed value: "Sensor_Name = " hidden: true
22	Sensor_Name	ascii string <i>size: 14</i> Main sensors used to acquire the data
23	semicolon_mark_4	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
24	white_space_6	ascii string <i>size: 49</i>



		white space fixed value: " " hidden: true
25	cr_newline_6	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
26	Data_Handbook_Reference_label	ascii string <i>size: 26</i> Data_Handbook_Reference = fixed value: "Data_Handbook_Reference = " hidden: true
27	Data_Handbook_Reference	ascii string <i>size: 21</i> Reference to the AVISO CD-ROM User Manual: Merged TOPEX/POSEIDON Products
28	semicolon_mark_5	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
29	white_space_7	ascii string <i>size: 30</i> white space fixed value: " " hidden: true
30	cr_newline_7	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
31	Product_Create_Start_Time_label	ascii string <i>size: 28</i> Product_Create_Start_Time =



		fixed value: "Product_Create_Start_Time = " hidden: true
32	Product_Create_Start_Time	ascii time <i>size: 17</i> Local time when the file started to be produced unit: "s since 2000-01-01" ascii string <i>size: 17</i> CCSDS ASCII datetime "YYYY-DDDThh:mm:ss".
33	semicolon_mark_6	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
34	white_space_8	ascii string <i>size: 32</i> white <i>space</i> fixed value: " " hidden: true
35	cr_newline_8	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
36	Product_Create_End_Time_label	ascii string <i>size: 26</i> Product_Create_End_Time = fixed value: "Product_Create_End_Time = " hidden: true
37	creation_end_time	ascii time <i>size: 17</i> Local time of the end of the production of the file unit: "s since 2000-01-01" ascii string <i>size: 17</i>



		CCSDS ASCII datetime "YYYY-DDDThh:mm:ss".
38	semicolon_mark_7	ascii char <i>size</i> : 1 semicolon fixed value: ";" hidden: true
39	white_space_9	ascii string <i>size</i> : 34 white space fixed value: " " hidden: true
40	cr_newline_9	ascii string <i>size</i> : 2 carriage return + newline fixed value: "\r\n" hidden: true
41	Generating_Software_Name_label	ascii string <i>size</i> : 27 Generating_Software_Name = fixed value: "Generating_Software_Name = " hidden: true
42	Generating_Software_Name	ascii string <i>size</i> : 50 Name of the software generating the file. The format is "TS_XXX_PROD_PRINCIPAL", where XXX being a 3-character ASCII string indentifying the generating product. "XXX" = "GDM" for GDR-M files (cycle header file and passfiles), "XXX" = "CRO" for the crossover point file, "XXX" = "EPH" for the orbit files
43	semicolon_mark_8	ascii char <i>size</i> : 1 semicolon fixed value: ";" hidden: true
44	cr_newline_10	ascii string <i>size</i> : 2 carriage return + newline



		fixed value: "\r\n" hidden: true
45	Build_Id_label	ascii string <i>size: 11</i> Build_Id = fixed value: "Build_Id = " hidden: true
46	Build_Id	ascii string <i>size: 21</i> Reference of the document describing the software used to product this file. The format is "AVI_XX_XXXXX_XXXX_XXX" which is an AVISO project document reference
47	semicolon_mark_9	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
48	white_space_11	ascii string <i>size: 45</i> white space fixed value: " " hidden: true
49	cr_newline_11	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
50	Pass_File_Data_Type_label	ascii string <i>size: 22</i> Pass_File_Data_Type = fixed value: "Pass_File_Data_Type = " hidden: true
51	Pass_File_Data_Type	ascii string <i>size: 6</i> Type of data used to produce the file. Valid types are "IGDR-M" during the verification pahse, "GDR-M" during the



		operational phase
52	semicolon_mark_10	ascii char <i>size</i> : 1 semicolon fixed value: ";" hidden: true
53	white_space_12	ascii string <i>size</i> : 49 white space fixed value: " " hidden: true
54	cr_newline_12	ascii string <i>size</i> : 2 carriage return + newline fixed value: "\r\n" hidden: true
55	Cycle_Number_label	ascii string <i>size</i> : 15 Cycle_Number = fixed value: "Cycle_Number = " hidden: true
56	Cycle_Number	ascii uint16 <i>size</i> : 3 The ten-day repeat cycle number associated to this file
57	semicolon_mark_11	ascii char <i>size</i> : 1 semicolon fixed value: ";" hidden: true
58	white_space_13	ascii string <i>size</i> : 59 white space fixed value: " " hidden: true



59	cr_newline_13	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
60	Package_Data_Start_Time_label	ascii string <i>size: 26</i> Package_Data_Start_Time = fixed value: "Package_Data_Start_Time = " hidden: true
61	Package_Data_Start_Time	ascii time <i>size: 24</i> UTC date and time of the first data record unit: "s since 2000-01-01" ascii string <i>size: 24</i> CCSDS ASCII datetime "YYYY-DDDThh:mm:ss.uuuuuu". Microseconds can be written using less digits (1-6 digits): e.g.: "YYYY-DDDThh:mm:ss.u "
62	semicolon_mark_12	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
63	white_space_14	ascii string <i>size: 27</i> white space fixed value: " " hidden: true
64	cr_newline_14	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
65	Package_Data_End_Time_label	ascii string <i>size: 24</i> Package_Data_End_Time =



		fixed value: "Package_Data_End_Time = " hidden: true
66	Package_Data_End_Time	ascii time <i>size: 24</i> UTC date and time of the last data record unit: "s since 2000-01-01" ascii string <i>size: 24</i> CCSDS ASCII datetime "YYYY-DDDThh:mm:ss.uuuuuu". Microseconds can be written using less digits (1-6 digits): e.g.: "YYYY-DDDThh:mm:ss.u "
67	semicolon_mark_13	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
68	white_space_15	ascii string <i>size: 29</i> white space fixed value: " " hidden: true
69	cr_newline_15	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
70	Start_Pass_Number_label	ascii string <i>size: 20</i> Start_Pass_Number = fixed value: "Start_Pass_Number = " hidden: true
71	Start_Pass_Number	ascii uint16 <i>size: 3</i> Pass number of the first non empty pass-file within the current ten-day repeat cycle
72	semicolon_mark_14	ascii char <i>size: 1</i>



		semicolon fixed value: ";" hidden: true
73	white_space_16	ascii string <i>size: 54</i> white space fixed value: " " hidden: true
74	cr_newline_16	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
75	End_Pass_Number_label	ascii string <i>size: 18</i> End_Pass_Number = fixed value: "End_Pass_Number = " hidden: true
76	End_Pass_Number	ascii uint16 <i>size: 3</i> Pass number of the last non empty pass-file within the current ten-day repeat cycle
77	semicolon_mark_15	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
78	white_space_17	ascii string <i>size: 56</i> white space fixed value: " " hidden: true
79	cr_newline_17	ascii string <i>size: 2</i> carriage return + newline



		fixed value: "\r\n" hidden: true
80	Pass_Count_label	ascii string <i>size: 13</i> Pass_Count = fixed value: "Pass_Count = " hidden: true
81	Pass_Count	ascii uint16 <i>size: 3</i> Total number of non empty pass-files within the current ten-day repeat cycle
82	semicolon_mark_16	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
83	white_space_18	ascii string <i>size: 61</i> white space fixed value: " "
84	cr_newline_18	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
85	CCSDS_marker_1	ascii string <i>size: 20</i> CCSDS marker fixed value: "CCSD\$MARKERCYCLEHDR" hidden: true
86	white_space_19	ascii string <i>size: 58</i> white space



		fixed value: " "	"
		hidden: true	
87	cr_newline_19	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
88	References_label	ascii string <i>size: 20</i> CCSDS References label fixed value: "CCSD3RF0000300000001" hidden: true	
89	white_space_20	ascii string <i>size: 58</i> white space fixed value: " " hidden: true	
90	cr_newline_20	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
91	Pass_File_Protocol_label	ascii string <i>size: 21</i> Pass_File_Protocol = fixed value: "Pass_File_Protocol = " hidden: true	
92	Pass_File_Protocol	ascii string <i>size: 4</i> The protocol of te pass-files. The value NONE indicates a non CCSDS protocol	
93	semicolon_mark_17	ascii char <i>size: 1</i> semicolon fixed value: ";"	



		hidden: true
94	white_space_21	ascii string <i>size: 52</i> white space fixed value: " " hidden: true
95	cr_newline_21	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
96	Pass_File_Delimiter_label	ascii string <i>size: 22</i> Pass_File_Delimiter = fixed value: "Pass_File_Delimiter = " hidden: true
97	Pass_File_Delimiter	ascii string <i>size: 3</i> File delimiter of the pass-files
98	semicolon_mark_18	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
99	white_space_22	ascii string <i>size: 52</i> white space fixed value: " " hidden: true
100	cr_newline_22	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true



101	Type_label	<p>ascii string <i>size: 7</i></p> <p>Type =</p> <p>fixed value: "Type = "</p> <p>hidden: true</p>								
102	Type	<p>ascii string <i>size: 50</i></p> <p>Type of data used to generate the merged products. Valid types are "IGDR" for IGDR-M products (verification phase), or "GDR" for GDR-M products (operational and extended phase)</p>								
103	semicolon_mark_19	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>								
104	white_space_23	<p>ascii string <i>size: 20</i></p> <p>white space</p> <p>fixed value: " "</p> <p>hidden: true</p>								
105	cr_newline_23	<p>ascii string <i>size: 2</i></p> <p>carriage return + newline</p> <p>fixed value: "\r\n"</p> <p>hidden: true</p>								
106	Pass_file	<p>ascii array[<i>dim_0</i>]</p> <p>Pass-file names.</p> <p>dim_0: int(..../Pass_Count)</p> <p>ascii record <i>size: 80</i></p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 5%;">i</th> <th style="width: 45%;">d</th> <th style="width: 50%;">field name</th> <th style="width: 40%;">definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td></td> <td>name_label</td> <td> <p>ascii string <i>size: 12</i></p> <p>Reference =</p> <p>fixed value: "Reference = "</p> </td> </tr> </tbody> </table>	i	d	field name	definition	0		name_label	<p>ascii string <i>size: 12</i></p> <p>Reference =</p> <p>fixed value: "Reference = "</p>
i	d	field name	definition							
0		name_label	<p>ascii string <i>size: 12</i></p> <p>Reference =</p> <p>fixed value: "Reference = "</p>							



			hidden: true
1	name	ascii string	size: 10 Pass-file name. The name is an ASCII file name in accordance with VAX/VMS. The format for this element is "MXccc.ppp" where: X = the data type (G for GDR products), x = the generation letter, ccc = the cycle number, ppp = the pass number
2	semicolon_mark	ascii char	size: 1 semicolon fixed value: ";" hidden: true
3	white_space	ascii string	size: 55 white space fixed value: " " hidden: true
4	cr_newline	ascii string	size: 2 carriage return + newline fixed value: "\r\n" hidden: true

3.1.2.2. MGDR_pass_file_header

ascii record "[MGDR_pass_file_header](#)"

size: 7524

id	field name	definition
0	EDU_label	ascii string size: 20 CCSDS EDU Label fixed value: "CCSD3ZF0000100000001"



		hidden: true	
1	white_space_1	ascii string white fixed value: " " hidden: true	size: 206 space
2	cr_newline_1	ascii string carriage return + newline fixed value: "\r\n" hidden: true	size: 2
3	Header_label	ascii string CCSDS Header Label fixed value: "CCSD3KS00006PASSFILE" hidden: true	size: 20
4	white_space_2	ascii string white fixed value: " " hidden: true	size: 206 space
5	cr_newline_2	ascii string carriage return + newline fixed value: "\r\n" hidden: true	size: 2
6	Producer_Agency_Name_label	ascii string Producer_Agency_Name = fixed value: "Producer_Agency_Name = " hidden: true	size: 23



7	Producer_Agency_Name	ascii string The name of the government agency in charge of this product <i>size: 4</i>
8	semicolon_mark_1	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
9	white_space_3	ascii string white fixed value: " " hidden: true <i>size: 198</i> space
10	cr_newline_3	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
11	Producer_Institution_Name_label	ascii string <i>size: 28</i> Producer_Institution_Name = fixed value: "Producer_Institution_Name = " hidden: true
12	Producer_Institution_Name	ascii string <i>size: 5</i> The name of the institution producing the file
13	semicolon_mark_2	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
14	white_space_4	ascii string white fixed value: <i>size: 192</i> space



		" "	
		hidden: true	
15	cr_newline_4	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
16	Source_Name_label	ascii string <i>size: 14</i> Source_Name = fixed value: "Source_Name = " hidden: true	
17	Source_Name	ascii string <i>size: 14</i> Name of the project	
18	semicolon_mark_3	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
19	white_space_5	ascii string <i>size: 197</i> white fixed value: " " hidden: true	space
20	cr_newline_5	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
21	Sensor_Name_label	ascii string <i>size: 14</i> Sensor_Name =	



		fixed value: "Sensor_Name = " hidden: true	
22	Sensor_Name	ascii string <i>size: 14</i> Main sensors used to acquire the data	
23	semicolon_mark_4	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
24	white_space_6	ascii string <i>size: 197</i> white fixed value: " " hidden: true	space
25	cr_newline_6	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
26	Data_Handbook_Reference_label	ascii string <i>size: 26</i> Data_Handbook_Reference = fixed value: "Data_Handbook_Reference = " hidden: true	
27	Data_Handbook_Reference	ascii string <i>size: 21</i> Reference to the AVISO CD-ROM User Manual: Merged TOPEX/POSEIDON Products	
28	semicolon_mark_5	ascii char <i>size: 1</i> semicolon fixed value: ";"	



		hidden: true	
29	white_space_7	ascii string white fixed value: " " hidden: true	size: 178 space
30	cr_newline_7	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true	
31	Product_Create_Start_Time_label	ascii string size: 28 Product_Create_Start_Time = fixed value: "Product_Create_Start_Time = " hidden: true	
32	Product_Create_Start_Time	ascii time size: 17 unit: "s since 2000-01-01" ascii string size: 17 CCSDS ASCII datetime "YYYY-DDDThh:mm:ss".	
33	semicolon_mark_6	ascii char size: 1 semicolon fixed value: ";" hidden: true	
34	white_space_8	ascii string white fixed value: " " hidden: true	size: 180 space
35	cr_newline_8	ascii string size: 2	



		carriage return + newline fixed value: "\r\n" hidden: true	
36	Product_Create_End_Time_label	ascii string <i>size: 26</i> Product_Create_End_Time = fixed value: "Product_Create_End_Time = " hidden: true	
37	Product_Create_End_Time	ascii time <i>size: 17</i> Local time of the end of the production of the file unit: "s since 2000-01-01" ascii string <i>size: 17</i> CCSDS ASCII datetime "YYYY-DDDThh:mm:ss".	
38	semicolon_mark_7	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
39	white_space_9	ascii string <i>size: 182</i> white fixed value: " " hidden: true	space
40	cr_newline_9	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
41	Generating_Software_Name_label	ascii string <i>size: 27</i> Generating_Software_Name = fixed value: "Generating_Software_Name = "	



		hidden: true	
42	Generating_Software_Name	ascii string Name of the software generating the file. The format is "TS_XXX_PROD_PRINCIPAL", where XXX being a 3-character ASCII string indentifying the generating product. "XXX" = "GDM" for GDR-M files (cycle header file and passfiles), "XXX" = "CRO" for the crossover point file, "XXX" = "EPH" for the orbit files	size: 50
43	semicolon_mark_8	ascii char size: 1 semicolon fixed value: ";" hidden: true	
44	white_space_10	ascii string white fixed value: " " hidden: true	size: 148 space
45	cr_newline_10	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true	
46	Build_Id_label	ascii string size: 11 Build_Id = fixed value: "Build_Id = " hidden: true	
47	Build_Id	ascii string Reference of the document describing the software used to produce this file. The format is "AVI_XX_XXXXX_XXXX_XXX" which is an AVISO project document reference	size: 21
48	semicolon_mark_9	ascii char size: 1 semicolon	



		fixed value: ";" hidden: true	
49	white_space_11	ascii string white fixed value: " " hidden: true	size: 193 space
50	cr_newline_11	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true	
51	Pass_File_Data_Type_Label	ascii string size: 22 Pass_File_Data_Type = fixed value: "Pass_File_Data_Type = " hidden: true	
52	Pass_File_Data_Type	ascii string Type of data used to produce the file. Valid types are "IGDR-M" during the verification pahse, "GDR-M" during the operational phase	size: 6
53	semicolon_mark_10	ascii char size: 1 semicolon fixed value: ";" hidden: true	
54	white_space_12	ascii string white fixed value: " " hidden: true	size: 197 space
55	cr_newline_12	ascii string size: 2	



		carriage return + newline fixed value: "\r\n" hidden: true	
56	Poseidon_Range_Bias_Label	ascii string <i>size: 22</i> Poseidon_Range_Bias = fixed value: "Poseidon_Range_Bias = " hidden: true	
57	Poseidon_Range_Bias	ascii float <i>size: 5</i>	
58	Poseidon_Range_Bias_unit	ascii string <i>size: 3</i> cm fixed value: " cm" hidden: true	
59	semicolon_mark_11	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
60	white_space_13	ascii string <i>size: 195</i> white fixed value: " " hidden: true	space
61	cr_newline_13	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
62	Topex_Range_Bias_Label	ascii string <i>size: 19</i> Topex_Range_Bias =	



		fixed value: "Topex_Range_Bias = " hidden: true	
63	Topex_Range_Bias	ascii float <i>size: 5</i>	
64	Topex_Range_Bias_unit	ascii string <i>size: 3</i> cm fixed value: " cm" hidden: true	
65	semicolon_mark_12	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
66	white_space_14	ascii string white fixed value: " " hidden: true	<i>size: 198</i> space
67	cr_newline_14	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
68	TP_sigma0_offset_label	ascii string <i>size: 20</i> T/P_sigma0_offset = fixed value: "T/P_sigma0_offset = " hidden: true	
69	TP_sigma0_offset	ascii float <i>size: 5</i>	
70	TP_sigma0_offset_unit	ascii string <i>size: 3</i> dB	



		fixed value: " dB" hidden: true	
71	semicolon_mark_13	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
72	white_space_15	ascii string white fixed value: " " hidden: true	<i>size: 197</i> space
73	cr_newline_15	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
74	NASA_Orbit_Filename_label	ascii string <i>size: 22</i> NASA_Orbit_Filename = fixed value: "NASA_Orbit_Filename = " hidden: true	
75	NASA_Orbit_Filename	ascii string <i>size: 38</i>	
76	semicolon_mark_14	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
77	white_space_16	ascii string white fixed value: "	<i>size: 165</i> space



		"	
		hidden: true	
78	cr_newline_16	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
79	Orbit_Qual_NASA_label	ascii string <i>size: 18</i> Orbit_Qual_NASA = fixed value: "Orbit_Qual_NASA = " hidden: true	
80	Orbit_Qual_NASA	ascii string <i>size: 11</i>	
81	semicolon_mark_15	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
82	white_space_17	ascii string <i>size: 196</i> white fixed value: " " hidden: true	space
83	cr_newline_17	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
84	CNES_Orbit_Filename_label	ascii string <i>size: 22</i> CNES_Orbit_Filename = fixed value: "CNES_Orbit_Filename = "	



		hidden: true	
85	CNES_Orbit_Filename	ascii string <i>size: 38</i>	
86	semicolon_mark_16	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
87	white_space_18	ascii string white fixed value: " " hidden: true	<i>size: 165</i> space
88	cr_newline_18	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
89	Orbit_Qual_CNES_label	ascii string <i>size: 18</i> Orbit_Qual_CNES = fixed value: "Orbit_Qual_CNES = " hidden: true	
90	Orbit_Qual_CNES	ascii string <i>size: 1</i>	
91	semicolon_mark_17	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
92	white_space_19	ascii string white fixed value:	<i>size: 206</i> space



		" "	
		hidden: true	
93	cr_newline_19	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
94	Topex_Pass_File_Id_label	ascii string <i>size: 21</i> Topex_Pass_File_Id = fixed value: "Topex_Pass_File_Id = " hidden: true	
95	Topex_Pass_File_Id	ascii string <i>size: 38</i>	
96	semicolon_mark_18	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
97	white_space_20	ascii string <i>size: 166</i> white fixed value: " " hidden: true	space
98	cr_newline_20	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
99	Poseidon_Pass_File_Id_label	ascii string <i>size: 24</i> Poseidon_Pass_File_Id =	



		fixed value: "Poseidon_Pass_File_Id = " hidden: true	
100	Poseidon_Pass_File_Id	ascii string size: 38	
101	semicolon_mark_19	ascii char size: 1 semicolon fixed value: ";" hidden: true	
102	white_space_21	ascii string white fixed value: " " hidden: true	size: 163 space
103	cr_newline_21	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true	
104	CORIOTROP_File_Id_label	ascii string size: 20 CORIOTROP_File_Id = fixed value: "CORIOTROP_File_Id = " hidden: true	
105	CORIOTROP_File_Id	ascii string size: 38	
106	semicolon_mark_20	ascii char size: 1 semicolon fixed value: ";" hidden: true	
107	white_space_22	ascii string white	size: 167 space



		fixed value: " " hidden: true
108	cr_newline_22	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true
109	Cycle_Number_label	ascii string size: 15 Cycle_Number = fixed value: "Cycle_Number = " hidden: true
110	Cycle_Number	ascii uint16 size: 3 The ten-day repeat cycle number associated to this file
111	semicolon_mark_21	ascii char size: 1 semicolon fixed value: ";" hidden: true
112	white_space_23	ascii string size: 207 white space fixed value: " " hidden: true
113	cr_newline_23	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true
114	Pass_Number_label	ascii string size: 14



		Pass_Number = fixed value: "Pass_Number = " hidden: true	
115	Pass_Number	ascii uint16 size: 3	
116	semicolon_mark_22	ascii char size: 1 semicolon fixed value: ";" hidden: true	
117	white_space_24	ascii string white fixed value: " " hidden: true	size: 208 space
118	cr_newline_24	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true	
119	Pass_Data_Count_label	ascii string size: 18 Pass_Data_Count = fixed value: "Pass_Data_Count = " hidden: true	
120	Pass_Data_Count	ascii uint16 size: 4	
121	semicolon_mark_23	ascii char size: 1 semicolon fixed value: ";" hidden: true	
122	white_space_25	ascii string	size: 203



		white fixed value: " " hidden: true	space
123	cr_newline_25	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true	
124	Rev_Number_label	ascii string size: 13 Rev_Number = fixed value: "Rev_Number = " hidden: true	
125	Rev_Number	ascii uint16 size: 5	
126	semicolon_mark_24	ascii char size: 1 semicolon fixed value: ";" hidden: true	
127	white_space_26	ascii string white fixed value: " " hidden: true	size: 207 space
128	cr_newline_26	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true	
129	Equator_Longitude_label	ascii string size: 20	



		Equator_Longitude = fixed value: "Equator_Longitude = " hidden: true	
130	Equator_Longitude	ascii float <i>size: 10</i>	
131	semicolon_mark_25	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
132	white_space_27	ascii string white fixed value: " " hidden: true	<i>size: 195</i> space
133	cr_newline_27	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
134	Equator_Time_label	ascii string <i>size: 15</i> Equator_Time = fixed value: "Equator_Time = " hidden: true	
135	Equator_Time	ascii time unit: "s since 2000-01-01" ascii string CCSDS ASCII datetime "YYYY-DDDThh:mm:ss.uuuuuu". Microseconds can be written using less digits (1-6 digits): e.g.: "YYYY-DDDThh:mm:ss.u "	<i>size: 24</i> <i>size: 24</i>
136	semicolon_mark_26	ascii char <i>size: 1</i> semicolon	



		fixed value: ";" hidden: true	
137	white_space_28	ascii string white fixed value: " " hidden: true	size: 186 space
138	cr_newline_28	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true	
139	Time_First_Pt_label	ascii string size: 16 Time_First_Pt = fixed value: "Time_First_Pt = " hidden: true	
140	Time_First_Pt	ascii time unit: "s since 2000-01-01" ascii string CCSDS ASCII datetime "YYYY-DDDThh:mm:ss.uuuuuu". Microseconds can be written using less digits (1-6 digits): e.g.: "YYYY-DDDThh:mm:ss.u "	size: 24 size: 24
141	semicolon_mark_27	ascii char size: 1 semicolon fixed value: ";" hidden: true	
142	white_space_29	ascii string white fixed value: " "	size: 185 space



		hidden: true	
143	cr_newline_29	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
144	Time_Last_Pt_label	ascii string <i>size: 15</i> Time_Last_Pt = fixed value: "Time_Last_Pt = " hidden: true	
145	Time_Last_Pt	ascii time <i>size: 24</i> unit: "s since 2000-01-01" ascii string <i>size: 24</i> CCSDS ASCII datetime "YYYY-DDDThh:mm:ss.uuuuuu". Microseconds can be written using less digits (1-6 digits): e.g.: "YYYY-DDDThh:mm:ss.u "	
146	semicolon_mark_28	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true	
147	white_space_30	ascii string <i>size: 186</i> white fixed value: " " hidden: true	space
148	cr_newline_30	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
149	Time_Epoch_label	ascii string <i>size: 13</i> Time_Epoch =	



		fixed value: "Time_Epoch = " hidden: true	
150	Time_Epoch	ascii time unit: "s since 2000-01-01" ascii string CCSDS ASCII datetime "YYYY-DDDThh:mm:ss.uuuuu". Microseconds can be written using less digits (1-6 digits): e.g.: "YYYY-DDDThh:mm:ss.u "	size: 24 size: 24
151	semicolon_mark_29	ascii char size: 1 semicolon fixed value: ";" hidden: true	
152	white_space_31	ascii string white fixed value: " " hidden: true	size: 188 space
153	cr_newline_31	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true	
154	CCSDS_marker_1	ascii string size: 20 CCSDS marker fixed value: "CCSD\$MARKERPASSFILE" hidden: true	
155	white_space_32	ascii string white fixed value: " "	size: 206 space



		hidden: true	
156	cr_newline_32	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	
157	Data_label	ascii string <i>size: 20</i> CCSDS Data label fixed value: "NJPL3IF0004700000001" hidden: true	
158	white_space_33	ascii string <i>size: 206</i> white fixed value: " " hidden: true	space
159	cr_newline_33	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true	

3.1.2.3. MGDR_pass_file_data_record

binary record "[MGDR_pass_file_data_record](#)"

size: 228

id	field name	definition
0	Tim_Moy_1	binary int16 <i>size: 2</i> Time, day part unit: "days since 1958-01-01" endianness: little endian
1	Tim_Moy_2	binary int32 <i>size: 4</i>



		Time, millisecond part unit: "1e-3 s" endianness: little endian
2	Tim_Moy_3	binary int16 <i>size: 2</i> Time, microsecond part unit: "1e-6 s" endianness: little endian
3	Dtim_Mil	binary int32 <i>size: 4</i> Time shift midframe unit: "1e-6 s" endianness: little endian
4	Dtim_Bias	binary int32 <i>size: 4</i> Net time tag correction unit: "1e-6 s" endianness: little endian
5	Dtim_Pac	binary int32 <i>size: 4</i> 10 per second timing unit: "1e-6 s" endianness: little endian
6	Lat_Tra	binary int32 (double) <i>size: 4</i> Latitude unit: "1e-6 degrees_north" converted unit: "degrees_north" (multiply by 1/1e+006) endianness: little endian
7	Lon_Tra	binary int32 (double) <i>size: 4</i> Longitude unit: "1e-6 degrees_north" converted unit: "degrees_north" (multiply by 1/1e+006) endianness: little endian



8	Sat_Alt	<p>binary int32 <i>size: 4</i></p> <p>Altitude above the reference elipsoid (NASA)</p> <p>unit: "1e-3 m"</p> <p>endianness: little endian</p>
9	HP_Sat	<p>binary int32 <i>size: 4</i></p> <p>Altitude above the reference elipsoid (CNES)</p> <p>unit: "1e-3 m"</p> <p>endianness: little endian</p>
10	Sat_Alt_Hi_Rate	<p>binary array[10] <i>size: 20</i></p> <p>Differences of satellite altitudes from sat_alt</p> <p>binary int16 <i>size: 2</i></p> <p>unit: "1e-3 m"</p> <p>endianness: little endian</p>
11	HP_Sat_Hi_Rate	<p>binary array[10] <i>size: 20</i></p> <p>Differences of satellite altitudes from hp_alt</p> <p>binary int16 <i>size: 2</i></p> <p>unit: "1e-3 m"</p> <p>endianness: little endian</p>
12	Att_Wvf	<p>binary uint8 <i>size: 1</i></p> <p>Waveform attitude</p> <p>unit: "1e-2 degrees"</p> <p>endianness: little endian</p>
13	Att_Ptf	<p>binary uint8 <i>size: 1</i></p> <p>Platform attitude</p> <p>unit: "1e-2 degrees"</p> <p>endianness: little endian</p>
14	H_Alt	<p>binary int32 <i>size: 4</i></p> <p>One per second altimeter range</p> <p>unit: "1e-3 m"</p>



		endianness: little endian
15	H_Alt_SME	<p>binary array[10] <i>size: 20</i></p> <p>Differences of altimeter range from h_alt</p> <p>binary int16 <i>size: 2</i></p> <p>unit: "1e-3 m"</p> <p>endianness: little endian</p>
16	Nval_H_Alt	<p>binary int8 <i>size: 1</i></p> <p>Number of valid points for 1 second altitude</p> <p>endianness: little endian</p>
17	RMS_H_Alt	<p>binary int16 <i>size: 2</i></p> <p>Root mean square of range</p> <p>unit: "1e-3 m"</p> <p>endianness: little endian</p>
18	Net_Instr_R_Corr_K	<p>binary int16 <i>size: 2</i></p> <p>Net instrument correction to range (Ku)</p> <p>unit: "1e-3 m"</p> <p>endianness: little endian</p>
19	Net_Instr_R_Corr_C	<p>binary int16 <i>size: 2</i></p> <p>Net instrument correction to range (C)</p> <p>unit: "1e-3 m"</p> <p>endianness: little endian</p>
20	CG_Range_Corr	<p>binary int8 <i>size: 1</i></p> <p>Center of gravity movement correction to range</p> <p>unit: "1e-3 m"</p> <p>endianness: little endian</p>
21	Range_Deriv	<p>binary int16 <i>size: 2</i></p> <p>Range derivative</p> <p>unit: "1e-2 m/s"</p> <p>endianness: little endian</p>



22	RMS_Range_Deriv	binary int16 <i>size: 2</i> RMS of high-rate values of range_deriv unit: "1e-2 m/s" endianness: little endian
23	Dry_Corr	binary int16 <i>size: 2</i> Dry tropospheric correction at measurement time unit: "1e-3 m" endianness: little endian
24	Dry1_Corr	binary int16 <i>size: 2</i> Dry tropospheric correction before measurement unit: "1e-3 m" endianness: little endian
25	Dry2_Corr	binary int16 <i>size: 2</i> Dry tropospheric correction after measurement unit: "1e-3 m" endianness: little endian
26	Inv_Bar	binary int16 <i>size: 2</i> Inverser barometer correction at mesaurement time unit: "1e-3 m" endianness: little endian
27	Wet_Corr	binary int16 <i>size: 2</i> Wet tropospheric correction at measurement time unit: "1e-3 m" endianness: little endian
28	Wet1_Corr	binary int16 <i>size: 2</i> Wet tropospheric correction before measurement unit: "1e-3 m" endianness: little endian
29	Wet2_Corr	binary int16 <i>size: 2</i>



		Wet tropospheric correction after measurement unit: "1e-3 m" endianness: little endian
30	Wet_H_Rad	binary int16 <i>size: 2</i> Radiometer wet tropospheric correction unit: "1e-3 m" endianness: little endian
31	Iono_Cor	binary int16 <i>size: 2</i> Topex dual-frequency ionospheric correction unit: "1e-3 m" endianness: little endian
32	Iono_Dor	binary int16 <i>size: 2</i> Ionospheric correction from DORIS unit: "1e-3 m" endianness: little endian
33	Iono_Ben	binary int16 <i>size: 2</i> Ionospheric correction from Bent model unit: "1e-3 m" endianness: little endian
34	SWH_K	binary uint16 <i>size: 2</i> Significant wave height (Ku) unit: "1e-2 m" endianness: little endian
35	SWH_C	binary uint16 <i>size: 2</i> Significant wave height (C) unit: "1e-2 m" endianness: little endian
36	SWH_RMS_K	binary uint8 <i>size: 1</i> RMS of significant wave height (Ku)



		unit: "1e-2 m" endianness: little endian
37	SWH_RMS_S	binary uint8 <i>size: 1</i> RMS of significant wave height (C) unit: "1e-2 m" endianness: little endian
38	SWH_Pts_Avg	binary int8 <i>size: 1</i> Number of valid points used to compute SWH endianness: little endian
39	Net_Instr_SWH_Corr_K	binary int8 <i>size: 1</i> Net instrument correction to SWH (Ku) unit: "1e-1 m" endianness: little endian
40	Net_Instr_SWH_Corr_C	binary int8 <i>size: 1</i> Net instrument correction to SWH (C) unit: "1e-1 m" endianness: little endian
41	DR_SWH_Att_K	binary int16 <i>size: 2</i> SWH/Attitude correction (Ku) unit: "1e-3 m" endianness: little endian
42	DR_SWH_Att_C	binary int16 <i>size: 2</i> SWH/Attitude correction (C) unit: "1e-3 m" endianness: little endian
43	SSB_Corr_K1	binary int16 <i>size: 2</i> Sea State Bias correction (Ku) (BM4) unit: "1e-3 m" endianness: little endian



44	SSB_Corr_K2	<p>binary int16 size: 2</p> <p>Sea State Bias correction (Ku) (TGS)</p> <p>unit: "1e-3 m"</p> <p>endianness: little endian</p>
45	Sigma0_K	<p>binary uint16 (double) size: 2</p> <p>Backscatter coefficient (Ku)</p> <p>unit: "1e-2 dB"</p> <p>converted unit: "dB" (multiply by 1/100)</p> <p>endianness: little endian</p>
46	Sigma0_C	<p>binary uint16 (double) size: 2</p> <p>Backscatter coefficient (C)</p> <p>unit: "1e-2 dB"</p> <p>converted unit: "dB" (multiply by 1/100)</p> <p>endianness: little endian</p>
47	AGC_K	<p>binary uint16 (double) size: 2</p> <p>Automatic gain control (Ku)</p> <p>unit: "1e-2 dB"</p> <p>converted unit: "dB" (multiply by 1/100)</p> <p>endianness: little endian</p>
48	AGC_C	<p>binary uint16 (double) size: 2</p> <p>Automatic gain control (C)</p> <p>unit: "1e-2 dB"</p> <p>converted unit: "dB" (multiply by 1/100)</p> <p>endianness: little endian</p>
49	AGC_RMS_K	<p>binary int16 (double) size: 2</p> <p>RMS of automatic gain control (Ku)</p> <p>unit: "1e-2 dB"</p> <p>converted unit: "dB" (multiply by 1/100)</p> <p>endianness: little endian</p>



50	AGC_RMS_C	binary uint8 (double) <i>size: 1</i> RMS of automatic gain control (C) unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100) endianness: little endian
51	Atm_Att_Sig0_Corr	binary uint8 (double) <i>size: 1</i> Atmospheric attenuation correction to sigma0 unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100) endianness: little endian
52	Net_Instr_Sig0_Corr	binary int16 (double) <i>size: 2</i> Net instrument correction to sigma0 unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100) endianness: little endian
53	Net_Instr_AGC_Corr_K	binary int16 (double) <i>size: 2</i> Net instrument correction to AGC (Ku) unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100) endianness: little endian
54	Net_Instr_AGC_Corr_C	binary int16 (double) <i>size: 2</i> Net instrument correction to AGC (C) unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100) endianness: little endian
55	AGC_Pts_Avg	binary int8 <i>size: 1</i> Number of valid points used to compute AGC endianness: little endian
56	H_MSS	binary int32 <i>size: 4</i>



		Mean sea surface height unit: "1e-3 m" endianness: little endian
57	H_Geo	binary int32 size: 4 Geoid height unit: "1e-3 m" endianness: little endian
58	H_Eot_CSR	binary int16 size: 2 Elastic ocean tide (CSR 3.0) unit: "1e-3 m" endianness: little endian
59	H_Eot_FES	binary int16 size: 2 Elastic ocean tide (FES 95.2) unit: "1e-3 m" endianness: little endian
60	H_Lt_CSR	binary int16 size: 2 Tidal loading effect (CSR 3.0) unit: "1e-3 m" endianness: little endian
61	H_Set	binary int16 size: 2 Solid earth tide unit: "1e-3 m" endianness: little endian
62	H_Pol	binary int8 size: 1 Geocentric pole tide unit: "1e-3 m" endianness: little endian
63	Wind_Sp	binary uint8 size: 1 Wind intensity (from altimeter data)



		unit: "1e-1 m/s" endianness: little endian						
64	H_Ocs	binary int16 size: 2 Ocean depth unit: "m" endianness: little endian						
65	Tb_18	binary int16 (double) size: 2 Brightness temperature 18 GHz unit: "1e-2 K" converted unit: "K" (multiply by 1/100) endianness: little endian						
66	Tb_21	binary int16 (double) size: 2 Brightness temperature 21 GHz unit: "1e-2 K" converted unit: "K" (multiply by 1/100) endianness: little endian						
67	Tb_37	binary uint16 (double) size: 2 Brightness temperature 37 GHz unit: "1e-2 K" converted unit: "K" (multiply by 1/100) endianness: little endian						
68	ALTON	binary int8 size: 1 Altimeter Indicator. This element is computed for TOPEX and POSEIDON data. It indicates which altimeter is on at the time of the measurement. Value Definition: 0 = POSEIDON on, 1 = TOPEX on endianness: little endian						
69	Instr_State_TOPEX	binary record size: 1 States of Topex Altimeter. This element exists only for TOPEX measurements. A default value is given when POSEIDON is on						
		<table border="1"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td> </td> <td> </td> <td> </td> </tr> </tbody> </table>	id	field name	definition			
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		<table border="1"> <tr> <td>0</td> <td>spare</td> <td> binary bytes size: 0:4 spare hidden: true </td> </tr> <tr> <td>1</td> <td>altimeter_operating</td> <td> binary uint8 size: 0:1 0 = A, 1 = B </td> </tr> <tr> <td>2</td> <td>ku_band_status</td> <td> binary uint8 size: 0:1 0 = on, 1 = off </td> </tr> <tr> <td>3</td> <td>c_bandwidth</td> <td> binary uint8 size: 0:1 0 = 320 MHz, 1 = 100 MHz </td> </tr> <tr> <td>4</td> <td>c_band_status</td> <td> binary uint8 size: 0:1 0 = on, 1 = off </td> </tr> </table>	0	spare	binary bytes size: 0:4 spare hidden: true	1	altimeter_operating	binary uint8 size: 0:1 0 = A, 1 = B	2	ku_band_status	binary uint8 size: 0:1 0 = on, 1 = off	3	c_bandwidth	binary uint8 size: 0:1 0 = 320 MHz, 1 = 100 MHz	4	c_band_status	binary uint8 size: 0:1 0 = on, 1 = off
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70	Instr_State_TMR	binary record <i>size: 1</i> States of the TMR. This element exists for TOPEX and POSEIDON data <table border="1"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>spare_1</td> <td> binary bytes size: 0:1 spare hidden: true </td> </tr> <tr> <td>1</td> <td>TMR_21B_status</td> <td> binary uint8 size: 0:1 0 = Off, 1 = On </td> </tr> <tr> <td>2</td> <td>TMR_21A_status</td> <td> binary uint8 size: 0:1 0 = On, 1 = Off </td> </tr> <tr> <td>3</td> <td>spare_2</td> <td> binary bytes size: 0:5 spare hidden: true </td> </tr> </tbody> </table>	id	field name	definition	0	spare_1	binary bytes size: 0:1 spare hidden: true	1	TMR_21B_status	binary uint8 size: 0:1 0 = Off, 1 = On	2	TMR_21A_status	binary uint8 size: 0:1 0 = On, 1 = Off	3	spare_2	binary bytes size: 0:5 spare hidden: true
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3	spare_2	binary bytes size: 0:5 spare hidden: true															
71	Instr_State_DORIS	binary int8 <i>size: 1</i> States of Doris instrument. A default value is given when the field (i.e. CORIOTROP) is not available. Value Definition: 0 = No ionospheric correction available (DORIS or BENT), 1 = BENT correction available, 2 = BENT and DORIS correction available															



		endianness: little endian									
72	IMANV	<p>binary int8 <i>size: 1</i></p> <p>Maneuver indicator. This element exists only for POSEIDON measurements. A default value is given when TOPEX is on. Value Definition: 0 = A maneuver is occurring, 1 = Adjusted when no maneuver orbit, 2 = Extrapolated when no maneuver, 3 = Accuracy better than 2 cm rms, 4 = Accuracy below 7.5 cm rms, 5 = Accuracy below 13 cm rms, 6 = Accuracy below 20 cm rmsorbit, 7 = Accuracy worst than 20 cm rms, 8 = No Doris data available</p> <p>endianness: little endian</p>									
73	Lat_Err	<p>binary int8 <i>size: 1</i></p> <p>Quality index of the latitude. This element is computed for TOPEX and POSEIDON data. A default value is given when one of the two latitudes is not available. Value Definition: 0 = Difference below ten microdegrees, 1 = Difference over ten microdegrees</p> <p>endianness: little endian</p>									
74	Lon_Err	<p>binary int8 <i>size: 1</i></p> <p>Quality index of the longitude. This element is computed for TOPEX and POSEIDON data. A default value is given when one of the two longitudes is not available. Value Definition: 0 = Difference below ten microdegrees, 1 = Difference over ten microdegrees</p> <p>endianness: little endian</p>									
75	Val_Att_Ptf	<p>binary int8 <i>size: 1</i></p> <p>Platform attitude validity. This flag exists only for POSEIDON measurements. A default value is given when TOPEX is on. It indicates if the platform attitude is believed to be valid or not. Value Definition: 0 = OK, 1 = Possible error, 2 = Bad data</p> <p>endianness: little endian</p>									
76	Current_Mode_1	<p>binary record <i>size: 1</i></p> <p>Altimeter current mode (Topex' first frame)</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 5%; text-align: center;">id</th> <th style="width: 65%; text-align: center;">field name</th> <th style="width: 30%; text-align: center;">definition</th> </tr> </thead> <tbody> <tr> <td style="text-align: center;">0</td> <td>high_low_rate_waveform_channel_assignm ent</td> <td> binary uint <i>size: 0: 1</i> 0 = Ku / C, 1 = C / Ku </td> </tr> <tr> <td style="text-align: center;">1</td> <td>high_variability</td> <td> binary uint <i>size: 0: 1</i> </td> </tr> </tbody> </table>	id	field name	definition	0	high_low_rate_waveform_channel_assignm ent	binary uint <i>size: 0: 1</i> 0 = Ku / C, 1 = C / Ku	1	high_variability	binary uint <i>size: 0: 1</i>
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			0 = low, 1 = high												
		2 gate	<p>binary uint size: 0: 8 1</p> <p>0 = AGC gate, 1 = Primary Max / 3</p>												
		3 track	<p>binary uint size: 0: 8 1</p> <p>0 = EML, 1 = Threshold</p>												
		4 mode	<p>binary uint size: 0: 8 4</p> <p>3 = Standby, 6 = Cal I, 12 = Cal II, 9 = Coarse acquisition, 10 = Coarse track, 5 = Fine acquisition, 15 = Fine track</p>												
77	Current_Mode_2	<p>binary record size: 1</p> <p>Altimeter current mode (Topex or Poseidon' second frame)</p> <table border="1"> <thead> <tr> <th>i d</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>high_low_rate_waveform_channel_assignment</td> <td> <p>binary uint size: 0: 8 1</p> <p>This flag exists only for TOPEX measurements. A default value of 0 is given when POSEIDON is on. Value definition: 0 = Ku / C, 1 = C / Ku</p> </td> </tr> <tr> <td>1</td> <td>high_variability</td> <td> <p>binary uint size: 0: 8 1</p> <p>This flag exists only for TOPEX measurements. A default value of 0 is given when POSEIDON is on. Value definition: 0 = low, 1 = high</p> </td> </tr> <tr> <td>2</td> <td>gate</td> <td>binary uint size: 0:</td> </tr> </tbody> </table>		i d	field name	definition	0	high_low_rate_waveform_channel_assignment	<p>binary uint size: 0: 8 1</p> <p>This flag exists only for TOPEX measurements. A default value of 0 is given when POSEIDON is on. Value definition: 0 = Ku / C, 1 = C / Ku</p>	1	high_variability	<p>binary uint size: 0: 8 1</p> <p>This flag exists only for TOPEX measurements. A default value of 0 is given when POSEIDON is on. Value definition: 0 = low, 1 = high</p>	2	gate	binary uint size: 0:
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		4 mode	<p>binary uint size: 0: 8 4</p> <p>This element exists and is different for TOPEX and POSEIDON. Value definition for TOPEX: 3 = Standby, 6 = Cal I, 12 = Cal II, 9 = Coarse acquisition, 10 = Coarse track, 5 = Fine acquisition, 15 = Fine track. Value definition for POSEIDON: 1 = Acquisition mode, 2 = Low-rate tracking, 3 = High-rate tracking</p>						
78	Gate_Index	<p>binary record size: 1</p> <p>Topex gate index. This element exists only for TOPEX measurements. A default value is given when POSEIDON is on.</p> <table border="1"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>secondary_channel</td> <td> <p>binary uint8 size: 0:4</p> <p>binary representation of the gate index for the</p> </td> </tr> </tbody> </table>		id	field name	definition	0	secondary_channel	<p>binary uint8 size: 0:4</p> <p>binary representation of the gate index for the</p>
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79	Ind_Pha	<p>binary int8 <i>size: 1</i></p> <p>Poseidon indicator on tracker processing. This element exists only for POSEIDON measurements. A default value is given when TOPEX is on. Value Definition: 0 = OK, 1 = Tracking lost, 2 = Computation time too long</p> <p>endianness: little endian</p>																											
80	Rang_SME	<p>binary record <i>size: 2</i></p> <p>State of 1/10 second values. This element is computed for TOPEX and POSEIDON data</p> <table border="1"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>flag_7</td> <td>binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data</td> </tr> <tr> <td>1</td> <td>flag_6</td> <td>binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data</td> </tr> <tr> <td>2</td> <td>flag_5</td> <td>binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data</td> </tr> <tr> <td>3</td> <td>flag_4</td> <td>binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data</td> </tr> <tr> <td>4</td> <td>flag_3</td> <td>binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data</td> </tr> <tr> <td>5</td> <td>flag_2</td> <td>binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data</td> </tr> <tr> <td>6</td> <td>flag_1</td> <td>binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data</td> </tr> <tr> <td>7</td> <td>flag_0</td> <td>binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data</td> </tr> </tbody> </table>	id	field name	definition	0	flag_7	binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data	1	flag_6	binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data	2	flag_5	binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data	3	flag_4	binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data	4	flag_3	binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data	5	flag_2	binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data	6	flag_1	binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data	7	flag_0	binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Bad data
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		8	spare	binary bytes <i>size</i> : 0:6 spare hidden: true																		
		9	flag_9	binary uint8 <i>size</i> : 0:1 0 = OK , 1 = Bad data																		
		10	flag_8	binary uint8 <i>size</i> : 0:1 0 = OK , 1 = Bad data																		
81	Alt_Bad_1	<p>binary record <i>size</i>: 1</p> <p>Topex and Poseidon measurement conditions no 1. This set of flags exists and is different for TOPEX and POSEIDON data. When TOPEX is on, it indicates if a problem was detected with the altimeter sensor corrections, dual frequency ionospheric correction or in compressing high-rate measurements. When POSEIDON is on, it indicates if the one per second ranges, significant wave heights or backscatter coefficients are believed to be valid or not. Only the definition for TOPEX is used here. For POSEIDON the bits are: spare (2 bits), Backscatter coefficient: 0 = Ok, 1 = Possible error, 2 = Bad data (2 bits), Significant Wave Height: 0 = Ok, 1 = Possible error, 2 = Bad data (2 bits), Altimeter Range: 0 = Ok, 1 = Possible error, 2 = Bad data (2 bits)</p> <table border="1"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>total_altimeter_range_correction</td> <td>binary uint8 <i>size</i>: 0:1 0 = Ku and C values OK , 1 = Problem detected in Ku or (and) C value(s)</td> </tr> <tr> <td>1</td> <td>dual_frequency_ionospheric_correction</td> <td>binary uint8 <i>size</i>: 0:1 0 = OK , 1 = Too many errors reported</td> </tr> <tr> <td>2</td> <td>one_per_second_altimeter_range_quality</td> <td>binary uint8 <i>size</i>: 0:1 0 = OK , 1 = RMS > 15cm</td> </tr> <tr> <td>3</td> <td>slope_of_fit</td> <td>binary uint8 <i>size</i>: 0:1 0 = OK , 1 = Too steep</td> </tr> <tr> <td>4</td> <td>tflag</td> <td>binary uint8 <i>size</i>: 0:1 fine tracks, EML, AGC gate</td> </tr> </tbody> </table>			id	field name	definition	0	total_altimeter_range_correction	binary uint8 <i>size</i> : 0:1 0 = Ku and C values OK , 1 = Problem detected in Ku or (and) C value(s)	1	dual_frequency_ionospheric_correction	binary uint8 <i>size</i> : 0:1 0 = OK , 1 = Too many errors reported	2	one_per_second_altimeter_range_quality	binary uint8 <i>size</i> : 0:1 0 = OK , 1 = RMS > 15cm	3	slope_of_fit	binary uint8 <i>size</i> : 0:1 0 = OK , 1 = Too steep	4	tflag	binary uint8 <i>size</i> : 0:1 fine tracks, EML, AGC gate
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		5	high_rate_waveforms	binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Too many flagged																		
		6	valid_points_from_fit	binary uint8 <i>size: 0:1</i> 0 = OK , 1 = Too many invalid																		
		7	compression_used	binary uint8 <i>size: 0:1</i> 0 = Fit , 1 = Median																		
82	Alt_Bad_2	<p>binary record <i>size: 1</i></p> <p>Topex and Poseidon measurement conditions no 2. This set of flags exists and is different for TOPEX and POSEIDON data. When TOPEX is on, it indicates if any of the pointing/sea-state conditions were invalid or sigma0 was out of limits. When POSEIDON is on, it indicates if the net (summed) instrument correction to ranges, significant wave heights or backscatter coefficients are believed to be valid or not. For POSEIDON the bits are: spare (2 bits), Backscatter coefficient: 0 = Ok, 1 = Possible error, 2 = Bad data (2 bits), Significant Wave Height: 0 = Ok, 1 = Possible error, 2 = Bad data (2 bits), Altimeter Range: 0 = Ok, 1 = Possible error, 2 = Bad data (2 bits)</p> <table border="1"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>spare_1</td> <td>binary bytes <i>size: 0:1</i> spare hidden: true</td> </tr> <tr> <td>1</td> <td>ku_band_agc_correction_or_sigma0</td> <td>binary uint8 <i>size: 0:1</i> 0 = Good values, 1 = AGC correction not done or sigma0 out of limit</td> </tr> <tr> <td>2</td> <td>c_band_agc_correction_or_sigma0</td> <td>binary uint8 <i>size: 0:1</i> 0 = Good values, 1 = AGC correction not done or sigma0 out of limit</td> </tr> <tr> <td>3</td> <td>ku_swh_correction</td> <td>binary uint8 <i>size: 0:1</i> 0 = Done , 1 = Not done</td> </tr> <tr> <td>4</td> <td>c_swh_correction</td> <td>binary uint8 <i>size: 0:1</i> 0 = Done , 1 = Not done</td> </tr> </tbody> </table>			id	field name	definition	0	spare_1	binary bytes <i>size: 0:1</i> spare hidden: true	1	ku_band_agc_correction_or_sigma0	binary uint8 <i>size: 0:1</i> 0 = Good values, 1 = AGC correction not done or sigma0 out of limit	2	c_band_agc_correction_or_sigma0	binary uint8 <i>size: 0:1</i> 0 = Good values, 1 = AGC correction not done or sigma0 out of limit	3	ku_swh_correction	binary uint8 <i>size: 0:1</i> 0 = Done , 1 = Not done	4	c_swh_correction	binary uint8 <i>size: 0:1</i> 0 = Done , 1 = Not done
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1	ku_band_agc_correction_or_sigma0	binary uint8 <i>size: 0:1</i> 0 = Good values, 1 = AGC correction not done or sigma0 out of limit																				
2	c_band_agc_correction_or_sigma0	binary uint8 <i>size: 0:1</i> 0 = Good values, 1 = AGC correction not done or sigma0 out of limit																				
3	ku_swh_correction	binary uint8 <i>size: 0:1</i> 0 = Done , 1 = Not done																				
4	c_swh_correction	binary uint8 <i>size: 0:1</i> 0 = Done , 1 = Not done																				



		5	c_range_correction	binary uint8 <i>size: 0:1</i> 0 = Done , 1 = Not done
		6	ku_range_correction	binary uint8 <i>size: 0:1</i> 0 = Done , 1 = Not done
		7	spare_2	binary bytes <i>size: 0:1</i> spare hidden: true
83	FI_Att	binary int8 <i>size: 1</i> Attitude indicator. This element is computed for TOPEX and POSEIDON data. Value Definition: 0 = Att_Ptf used, 1 = Att_Wvf used. Note that for TOPEX data, the waveform estimate is always used to compute altimeter corrections involving attitude endianness: little endian		
84	Dry_Err	binary int8 <i>size: 1</i> Quality index on dry_corr. This element is computed for TOPEX and POSEIDON data. A default value is given when the field (i.e. CORIOTROP) is not available. Its value ranges from 0 to 9 with lower ranges when this element is valuable and higher ranges when it is not valuable endianness: little endian		
85	Dry1_Err	binary int8 <i>size: 1</i> Quality index on dry1_corr. This element is computed for TOPEX and POSEIDON data. A default value is given when the field (i.e. CORIOTROP) is not available. Its value ranges from 0 to 9 with lower ranges when this element is valuable and higher ranges when it is not valuable endianness: little endian		
86	Dry2_Err	binary int8 <i>size: 1</i> Quality index on dry2_corr. This element is computed for TOPEX and POSEIDON data. A default value is given when the field (i.e. CORIOTROP) is not available. Its value ranges from 0 to 9 with lower ranges when this element is valuable and higher ranges when it is not valuable endianness: little endian		
87	Wet_Flag	binary int8 <i>size: 1</i> Interpolation indicator on wet_corr, wet1_corr, and wet2_corr. This		



		<p>element is computed for TOPEX and POSEIDON data. A default value is given when CORIOTROP data are not available. Value Definition: 0 = No point over land, 1 = One point at least over land</p> <p>endianness: little endian</p>																								
88	Wet_H_Err	<p>binary int8 <i>size: 1</i></p> <p>Quality index on wet_corr, wet1_corr, and wet2_corr. This element is computed for TOPEX and POSEIDON data. A default value is given when CORIOTROP data are not available. Its value ranges from 0 to 9 with lower ranges when this element is valuable and higher ranges when it is not valuable</p> <p>endianness: little endian</p>																								
89	Iono_Bad	<p>binary record <i>size: 2</i></p> <p>Quality index on iono_cor. This element exists only for TOPEX measurements. A default value is given when POSEIDON is on. It represents a set of flags which indicates that the computed dual-frequency ionospheric correction is out of range or not computed because only one band was operating</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 5%;">id</th> <th style="width: 65%;">field name</th> <th style="width: 30%;">definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>flag_7</td> <td> <p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p> </td> </tr> <tr> <td>1</td> <td>flag_6</td> <td> <p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p> </td> </tr> <tr> <td>2</td> <td>flag_5</td> <td> <p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p> </td> </tr> <tr> <td>3</td> <td>flag_4</td> <td> <p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p> </td> </tr> <tr> <td>4</td> <td>flag_3</td> <td> <p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p> </td> </tr> <tr> <td>5</td> <td>flag_2</td> <td> <p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p> </td> </tr> <tr> <td>6</td> <td>flag_1</td> <td> <p>binary uint <i>size: 0:</i></p> </td> </tr> </tbody> </table>	id	field name	definition	0	flag_7	<p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p>	1	flag_6	<p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p>	2	flag_5	<p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p>	3	flag_4	<p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p>	4	flag_3	<p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p>	5	flag_2	<p>binary uint <i>size: 0: 8 1</i></p> <p>0 = OK , 1 = Bad data</p>	6	flag_1	<p>binary uint <i>size: 0:</i></p>
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		8	1	0 = OK , 1 = Bad data
7	flag_0	binary uint	size: 0: 8	1 0 = OK , 1 = Bad data
8	spare_1	binary byte	size: 0: 8	1 spare hidden: true
9	flag_fine_ht_c	binary uint	size: 0: 8	1 SDR Flag_Fine_Ht_C (C band)
10	flag_fine_ht_k	binary uint	size: 0: 8	1 SDR Flag_Fine_Ht_K (Ku band)
11	altimeter_science_preliminary_flags_set	binary uint	size: 0: 8	1 0 = No, 1 = Yes
12	altimeter_engineering_preliminary_flags_set	binary uint	size: 0: 8	1 0 = No, 1 = Yes
13	spare_2	binary byte	size: 0: 8	1 spare hidden: true
14	flag_9	binary uint	size: 0: 8	1 0 = OK , 1 = Bad data
15	flag_8	binary uint	size: 0: 8	1 0 = OK , 1 = Bad data



90	lono_Dor_Bad	binary int8 <i>size: 1</i> Quality index on lono_dor endianness: little endian																		
91	Geo_Bad_1	<p>binary record <i>size: 1</i></p> <p>Ocean/land/ice indicator. This element is computed for TOPEX and POSEIDON data</p> <table border="1"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>spare</td> <td>binary bytes <i>size: 0:4</i> spare hidden: true</td> </tr> <tr> <td>1</td> <td>ice_distribution</td> <td>binary uint8 <i>size: 0:1</i> 0 = No ice , 1 = Ice</td> </tr> <tr> <td>2</td> <td>sea_surface_state</td> <td>binary uint8 <i>size: 0:1</i> Sea Surface State as observed by the radiometer. 0 = Water , 1 = Land</td> </tr> <tr> <td>3</td> <td>water_land_distribution</td> <td>binary uint8 <i>size: 0:1</i> 0 = Water , 1 = Land</td> </tr> <tr> <td>4</td> <td>deep_water_state</td> <td>binary uint8 <i>size: 0:1</i> (/ 1000m). 0 = Deep Water , 1 = Shallow Water</td> </tr> </tbody> </table>	id	field name	definition	0	spare	binary bytes <i>size: 0:4</i> spare hidden: true	1	ice_distribution	binary uint8 <i>size: 0:1</i> 0 = No ice , 1 = Ice	2	sea_surface_state	binary uint8 <i>size: 0:1</i> Sea Surface State as observed by the radiometer. 0 = Water , 1 = Land	3	water_land_distribution	binary uint8 <i>size: 0:1</i> 0 = Water , 1 = Land	4	deep_water_state	binary uint8 <i>size: 0:1</i> (/ 1000m). 0 = Deep Water , 1 = Shallow Water
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92	Geo_Bad_2	<p>binary record <i>size: 1</i></p> <p>Rain/tide conditions. This element is computed for TOPEX and POSEIDON data</p> <table border="1"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>spare</td> <td>binary bytes <i>size: 0:3</i> spare hidden: true</td> </tr> <tr> <td>1</td> <td>fes_95_2_ocean_tide</td> <td>binary uint8 <i>size: 0:2</i> 0 = 4 valid points, 1 = 3 valid points, 2 = 2 valid points, 3 = less than 2 valid points</td> </tr> </tbody> </table>	id	field name	definition	0	spare	binary bytes <i>size: 0:3</i> spare hidden: true	1	fes_95_2_ocean_tide	binary uint8 <i>size: 0:2</i> 0 = 4 valid points, 1 = 3 valid points, 2 = 2 valid points, 3 = less than 2 valid points									
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1	fes_95_2_ocean_tide	binary uint8 <i>size: 0:2</i> 0 = 4 valid points, 1 = 3 valid points, 2 = 2 valid points, 3 = less than 2 valid points																		



		2	csr_3_0_ocean_tide	binary uint8 size: 0:2 0 = 4 valid points, 1 = 3 valid points, 2 = 2 valid points, 3 = less than 2 valid points
		3	rain_excess_liquid	binary uint8 size: 0:1 0 = Normal , 1 = Rain / Excess liquid detected
93	TMR_Bad	binary record size: 1 Flag for brightness temperatures. This element is computed for TOPEX and POSEIDON data		
		id	field name	definition
		0	spare	binary bytes size: 0:6 spare hidden: true
		1	brightness_temperature_flag	binary uint8 size: 0:2 0 = All channels good, 1 = One or more channels fair, 2 = One or more channels poor, 3 = One or more channels with interpolation failure (bad)
94	Ind_RTK	binary uint8 size: 1 POSEIDON ground retracking indicator. This element exists only for POSEIDON measurements. A default value is given when TOPEX is on endianness: little endian		
95	spare	binary bytes size: 1 spare hidden: true		

3.2. ERS-1/2 data

3.2.1. Filenaming convention

The nomenclature is:

OPR2-DIF-DIF-sssssseeeee.E2

OPR2-DIF-DIF-*.E2



		hidden: true
5	Pass_File_Name	ascii string <i>size: 12</i> Name of the pass-file, built from the following indicators: satellite, product type, orbit revolution number (absolute and relative number in the cycle), and pass direction (ascending or descending pass)
6	semicolon_mark_1	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
7	white_space_2	ascii string <i>size: 148</i> white space fixed value: " " hidden: true
8	cr_newline_2	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
9	Pass_Station_label	ascii string <i>size: 15</i> Pass_Station = fixed value: "Pass_Station = " hidden: true
10	Pass_Station	ascii string <i>size: 2</i> Telemetry transcription station
11	semicolon_mark_2	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true



12	white_space_3	ascii string white fixed value: " " hidden: true	size: 160 space
13	cr_newline_3	ascii string carriage return + newline fixed value: "\r\n" hidden: true	size: 2
14	Pass_Start_Date_label	ascii string Pass_Start_Date = fixed value: "Pass_Start_Date = " hidden: true	size: 18
15	Pass_Start_Date	ascii time Time of the first data record in the pass-file. BEAT time value is given in seconds since 01-JAN-2000 unit: "s since 2000-01-01" ascii string CCSDS ASCII datetime "YYYY-DDDThh:mm:ss.uuuuuu". Microseconds can be written using less digits (1-6 digits): e.g.: "YYYY-DDDThh:mm:ss.u "	size: 24 size: 24
16	semicolon_mark_3	ascii char semicolon fixed value: ";" hidden: true	size: 1
17	white_space_4	ascii string white fixed value: " " hidden: true	size: 135 space



18	cr_newline_4	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
19	Pass_Generation_Date_label	ascii string <i>size: 23</i> Pass_Generation_Date = fixed value: "Pass_Generation_Date = " hidden: true
20	Pass_Generation_Date	ascii time <i>size: 17</i> Local time when the pass-file was produced. BEAT time value is given in seconds since 01-JAN-2000 unit: "s since 2000-01-01" ascii string <i>size: 17</i> CCSDS ASCII datetime "YYYY-DDDThh:mm:ss".
21	semicolon_mark_4	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
22	white_space_5	ascii string <i>size: 137</i> white space fixed value: " " hidden: true
23	cr_newline_5	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
24	Pass_Nbmeh_label	ascii string <i>size: 13</i>



		Pass_Nbmes = fixed value: "Pass_Nbmes = " hidden: true
25	Pass_Nbmes	ascii uint16 <i>size: 4</i> Number of data records in the pass-file
26	semicolon_mark_5	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
27	white_space_6	ascii string <i>size: 160</i> white space fixed value: " " hidden: true
28	cr_newline_6	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
29	Pass_Start_End_Latitude_label	ascii string <i>size: 26</i> Pass_Start_End_Latitude = fixed value: "Pass_Start_End_Latitude = " hidden: true
30	Pass_Start_Latitude	ascii int32 (double) <i>size: 9</i> Latitude of the first data record in the pass-file unit: "1e-6 degrees_north" converted unit: "degrees_north" (multiply by 1/1e+006)
31	underscore_mark_1	ascii char <i>size: 1</i> underscore



		fixed value: "_"	
		hidden: true	
32	Pass_End_Latitude	ascii int32 (double) Latitude of the last data record in the pass-file unit: "1e-6 degrees_north" converted unit: "degrees_north" (multiply by 1/1e+006)	size: 9
33	semicolon_mark_6	ascii char size: 1 semicolon fixed value: ";" hidden: true	
34	white_space_7	ascii string white fixed value: " " hidden: true	size: 132 space
35	cr_newline_7	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true	
36	Pass_Start_End_Longitude_label	ascii string Pass_Start_End_Longitude = fixed value: "Pass_Start_End_Longitude = " hidden: true	size: 27
37	Pass_Start_Longitude	ascii uint32 (double) Longitude of the first data record in the pass-file unit: "1e-6 degrees_east" converted unit: "degrees_east" (multiply by 1/1e+006)	size: 9



38	underscore_mark_2	ascii char <i>size: 1</i> underscore fixed value: "_" hidden: true
39	Pass_End_Longitude	ascii uint32 (double) <i>size: 9</i> Longitude of the last data record in the pass-file unit: "1e-6 degrees_east" converted unit: "degrees_east" (multiply by 1/1e+006)
40	semicolon_mark_7	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
41	white_space_8	ascii string <i>size: 131</i> white space fixed value: " " hidden: true
42	cr_newline_8	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
43	Pass_Version_label	ascii string <i>size: 15</i> Pass_Version = fixed value: "Pass_Version = " hidden: true
44	OPR_Version	ascii string <i>size: 4</i> Version of OPR software used to build the pass-file



45	underscore_mark_3	ascii char <i>size: 1</i> underscore fixed value: "_" hidden: true
46	OIP_Version	ascii string <i>size: 4</i> Version of OIP software used to build the pass-file
47	underscore_mark_4	ascii char <i>size: 1</i> underscore fixed value: "_" hidden: true
48	MBT_Version	ascii string <i>size: 4</i> Version of MBT software used to build the pass-file
49	underscore_mark_5	ascii char <i>size: 1</i> underscore fixed value: "_" hidden: true
50	Orbit_Version	ascii string <i>size: 4</i> Version of orbit software used to build the pass-file
51	semicolon_mark_8	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
52	white_space_9	ascii string <i>size: 143</i> white space fixed value: " " hidden: true



53	cr_newline_9	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
54	Nbmes_Sea_Land_MBT_label	ascii string <i>size: 21</i> Nbmes_Sea_Land_MBT = fixed value: "Nbmes_Sea_Land_MBT = " hidden: true
55	Nbmes_Sea_MBT	ascii uint16 <i>size: 4</i> Number of valid radiometer measurements over the sea
56	underscore_mark_6	ascii char <i>size: 1</i> underscore fixed value: "_" hidden: true
57	Nbmes_Land_MBT	ascii uint16 <i>size: 4</i> Number of valid radiometer measurements over the land
58	semicolon_mark_9	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
59	white_space_10	ascii string <i>size: 147</i> white space fixed value: " " hidden: true
60	cr_newline_10	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n"



		hidden: true
61	Nbmes_Valid_label	ascii string <i>size: 14</i> Nbmes_Valid = fixed value: "Nbmes_Valid = " hidden: true
62	Nbmes_Valid	ascii uint16 <i>size: 4</i> Number of valid 1-Hz altimeter measurements in the pass-file
63	semicolon_mark_10	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
64	white_space_11	ascii string <i>size: 159</i> white space fixed value: " "
65	cr_newline_11	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
66	Nbmes_Valid_OIP_MBT_label	ascii string <i>size: 22</i> Nbmes_Valid_OIP_MBT = fixed value: "Nbmes_Valid_OIP_MBT = " hidden: true
67	Nbmes_Valid_OIP_MBT	ascii uint16 <i>size: 4</i> Number of simultaneous altimeter and radiometer valid measurements in the pass-file
68	semicolon_mark_11	ascii char <i>size: 1</i>



		semicolon fixed value: ";" hidden: true	
69	white_space_12	ascii string white fixed value: " " hidden: true	size: 151 space
70	cr_newline_12	ascii string carriage return + newline fixed value: "\r\n" hidden: true	size: 2
71	Type_Orbit_Height_Geo_label	ascii string Type_Orbit_Height_Geo = fixed value: "Type_Orbit_Height_Geo = " hidden: true	size: 24
72	Type_Orbit_Height	ascii string Type of orbit data used to compute the altitude of the satellite above the reference ellipsoid (DPAFL or DPAFP)	size: 5
73	underscore_mark_7	ascii char underscore fixed value: "_" hidden: true	size: 1
74	Type_Orbit_Geo	ascii string Type of orbit data used to locate measurements (MMCC, DPAFL or DPAFP)	size: 5
75	semicolon_mark_12	ascii char semicolon	size: 1



		fixed value: ";" hidden: true
76	white_space_13	ascii string <i>size: 142</i> white space fixed value: " " hidden: true
77	cr_newline_13	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
78	Min_Max_Wind_Speed_label	ascii string <i>size: 21</i> Min_Max_Wind_Speed = fixed value: "Min_Max_Wind_Speed = " hidden: true
79	Min_Wind_Speed	ascii int16 (double) <i>size: 5</i> Minimal value of wind speed estimates (Wind_Sp) in the pass-file unit: "1e-2" m/s" converted unit: "m/s" (multiply by 1/100)
80	slash_mark_1	ascii char <i>size: 1</i> slash fixed value: "/" hidden: true
81	Max_Wind_Speed	ascii int16 (double) <i>size: 5</i> Maximal value of wind speed estimates (Wind_Sp) in the pass-file unit: "1e-2" m/s" converted unit: "m/s" (multiply by 1/100)



82	semicolon_mark_13	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
83	white_space_14	ascii string <i>size: 145</i> white space fixed value: " " hidden: true
84	cr_newline_14	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
85	Min_Max_Vapour_Content_label	ascii string <i>size: 25</i> Min_Max_Vapour_Content = fixed value: "Min_Max_Vapour_Content = " hidden: true
86	Min_Vapour_Content	ascii int16 (double) <i>size: 5</i> Minimal value of water vapour content estimates (WV_Cont) in the pass-file unit: "1e-2 g/cm2" converted unit: "g/cm2" (multiply by 1/100)
87	slash_mark_2	ascii char <i>size: 1</i> slash fixed value: "/" hidden: true
88	Max_Vapour_Content	ascii int16 (double) <i>size: 5</i> Maximal value of water vapour content estimates (WV_Cont) in the pass-file



		unit: "1e-2" g/cm2" converted unit: "g/cm2" (multiply by 1/100)
89	semicolon_mark_14	ascii char size: 1 semicolon fixed value: ";" hidden: true
90	white_space_15	ascii string size: 141 white space fixed value: " " hidden: true
91	cr_newline_15	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true
92	Min_Max_Liquid_Content_label	ascii string size: 25 Min_Max_Liquid_Content = fixed value: "Min_Max_Liquid_Content = " hidden: true
93	Min_Liquid_Content	ascii int16 (double) size: 5 Minimal value of liquid water content estimates (LW_Cont) in the pass-file unit: "1e-2" kg/cm2" converted unit: "kg/cm2" (multiply by 1/100)
94	slash_mark_3	ascii char size: 1 slash fixed value: "/"



		hidden: true
95	Max_Liquid_Content	<p>ascii int16 (double) <i>size: 5</i></p> <p>Maximal value of liquid water content estimates (LW_Cont) in the pass-file</p> <p>unit: "1e-2 kg/cm2"</p> <p>converted unit: "kg/cm2" (multiply by 1/100)</p>
96	semicolon_mark_15	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
97	white_space_16	<p>ascii string <i>size: 141</i></p> <p>white space</p> <p>fixed value: "</p> <p style="text-align: center;">"</p> <p>hidden: true</p>
98	cr_newline_16	<p>ascii string <i>size: 2</i></p> <p>carriage return + newline</p> <p>fixed value: "\r\n"</p> <p>hidden: true</p>
99	Min_Max_Altitude_label	<p>ascii string <i>size: 19</i></p> <p>Min_Max_Altitude =</p> <p>fixed value: "Min_Max_Altitude = "</p> <p>hidden: true</p>
100	Min_Altitude	<p>ascii int32 (double) <i>size: 10</i></p> <p>Minimal value of altimeter range estimates (H_Alt) in the pass-file</p> <p>unit: "1e-3 m"</p> <p>converted unit: "m" (multiply by 1/1000)</p>
101	slash_mark_4	<p>ascii char <i>size: 1</i></p> <p>slash</p>



		fixed value: "/" hidden: true
10 2	Max_Altitude	ascii int32 (double) <i>size: 10</i> Maximal value of altimeter range estimates (H_Alt) in the pass-file unit: "1e-3" m" converted unit: "m" (multiply by 1/1000)
10 3	semicolon_mark_16	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
10 4	white_space_17	ascii string <i>size: 137</i> white space fixed value: " " hidden: true
10 5	cr_newline_17	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
10 6	Min_Max_Wave_Heig ht_label	ascii string <i>size: 22</i> Min_Max_Wave_Height = fixed value: "Min_Max_Wave_Height = " hidden: true
10 7	Min_Wave_Height	ascii int16 (double) <i>size: 5</i> Minimal value of significant wave height estimates (SWH) in the pass-file unit: "1e-2" m" converted unit: "m" (multiply by 1/100)



10 8	slash_mark_5	ascii char <i>size</i> : 1 slash fixed value: "/" hidden: true
10 9	Max_Wave_Height	ascii int16 (double) <i>size</i> : 5 Maximal value of significant wave height estimates (SWH) in the pass-file unit: "1e-2 m" converted unit: "m" (multiply by 1/100)
11 0	semicolon_mark_17	ascii char <i>size</i> : 1 semicolon fixed value: ";" hidden: true
11 1	white_space_18	ascii string <i>size</i> : 144 white space fixed value: " " hidden: true
11 2	cr_newline_18	ascii string <i>size</i> : 2 carriage return + newline fixed value: "\r\n" hidden: true
11 3	Min_Max_Sigma_Naught_label	ascii string <i>size</i> : 23 Min_Max_Sigma_Naught = fixed value: "Min_Max_Sigma_Naught = " hidden: true
11 4	Min_Sigma_Naught	ascii int16 (double) <i>size</i> : 5 Minimal value of backscatter coefficient estimates (Sigma0) in the pass-file



		unit: "1e-2" dB" converted unit: "dB" (multiply by 1/100)
11 5	slash_mark_6	ascii char size: 1 slash fixed value: "/" hidden: true
11 6	Max_Sigma_Naught	ascii int16 (double) size: 5 Maximal value of backscatter coefficient estimates (Sigma0) in the pass-file unit: "1e-2" dB" converted unit: "dB" (multiply by 1/100)
11 7	semicolon_mark_18	ascii char size: 1 semicolon fixed value: ";" hidden: true
11 8	white_space_19	ascii string size: 143 white space fixed value: " " hidden: true
11 9	cr_newline_19	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true
12 0	Parameters_label	ascii string size: 13 Parameters = fixed value: "Parameters = " hidden: true



12 1	R12	ascii uint8 R12 sunspot number - used to compute the ionospheric correction	size: 3
12 2	slash_mark_7	ascii char size: 1 slash fixed value: "/" hidden: true	
12 3	USO_Drift	ascii int16 (double) USO drift - the difference between the nominal 5 MHz USO frequency and the in-flight measured USO frequency (nominal - measured). It is taken into account in the computation of altimeter range (see H_Alt_Raw) unit: "1e-3 Hz" converted unit: "Hz" (multiply by 1/1000)	size: 5
12 4	slash_mark_8	ascii char size: 1 slash fixed value: "/" hidden: true	
12 5	H_Alt_COG_Cor	ascii int16 (double) Distance antenna / centre of gravity is one of the corrections added to the raw value of altimeter range to get the altimeter range corrected for instrumental effects (see H_Alt). unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)	size: 5
12 6	semicolon_mark_19	ascii char size: 1 semicolon fixed value: ";" hidden: true	
12 7	white_space_20	ascii string white fixed value: " "	size: 149 space



		"
		hidden: true
128	cr_newline_20	ascii string <i>size: 2</i> carriage return + newline fixed value: "\r\n" hidden: true
129	Calibration_Corrections_label	ascii string <i>size: 26</i> Calibration_Corrections = fixed value: "Calibration_Corrections = " hidden: true
130	H_Alt_Bias	ascii int32 (double) <i>size: 10</i> Engineering calibration correction (bias) related to altimeter range unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
131	slash_mark_9	ascii char <i>size: 1</i> slash fixed value: "/" hidden: true
132	SWH_Bias	ascii int16 (double) <i>size: 5</i> Engineering calibration correction (bias) related to significant wave height unit: "1e-2 m" converted unit: "m" (multiply by 1/100)
133	slash_mark_10	ascii char <i>size: 1</i> slash fixed value: "/" hidden: true
134	Sigma0_Bias	ascii int16 (double) <i>size: 5</i>



		Engineering calibration correction (bias) related to backscatter coefficient unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
135	semicolon_mark_20	ascii char size: 1 semicolon fixed value: ";" hidden: true
136	white_space_21	ascii string size: 129 white space fixed value: " " hidden: true
137	cr_newline_21	ascii string size: 2 carriage return + newline fixed value: "\r\n" hidden: true
138	white_space_22	ascii string size: 140 white space fixed value: " " hidden: true
139	ccsds_marker	ascii string size: 20 CCSDS marker fixed value: "CCSD\$MARKERPASSFILE" hidden: true
140	data_label	ascii string size: 20 CCSDS Data label



	fixed value: "FCST3IF0010300000001"
	hidden: true

3.2.2.2. OPR_pass_file_data_record

binary record "[OPR_pass_file_data_record](#)"

size: 180

id	field name	definition												
0	Nb	binary int32 <i>size: 4</i> Measurement number in the pass-file												
1	MCD	binary record <i>size: 4</i> This element is the Measurement Confidence Data, which regroups all the flags related to the 1-Hz altimeter measurement. 1-Hz altimeter quality flags are derived from the quality of 20-Hz ocean elementary measurements. A 1-Hz altimeter quality flag is set to "bad" if at least one of the corresponding elementary estimates is "bad" (i.e. out-of-range); otherwise it is set to "good". These engineering level flags may be considered as useful information for software validation, but their systematic use for editing data is to consider with care. <table border="1" style="margin-top: 10px;"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Valid</td> <td> binary uint8 <i>size: 0:1</i> Measurement validity (0 = Valid, 1 = Invalid). A 1-Hz measurement is valid if it contains at least one 20-Hz elementary measurement declared "ocean" in the processing; it is invalid otherwise. </td> </tr> <tr> <td>1</td> <td>Causes</td> <td> binary uint8 <i>size: 0:3</i> Cause of invalidity for invalid measurements (1 = Acquisition mode, 2 = Not acquisition mode but over land (measurements over land are provided in OPR as invalid measurements), 3 = Not acquisition mode, not over land, but not "ocean" measurement, 4 = Other operating mode (generally ice tracking mode)) </td> </tr> <tr> <td>2</td> <td>Qua_Raw</td> <td> binary uint8 <i>size: 0:1</i> Quality of range estimate (0 = Good , 1 = Bad) </td> </tr> </tbody> </table>	id	field name	definition	0	Valid	binary uint8 <i>size: 0:1</i> Measurement validity (0 = Valid, 1 = Invalid). A 1-Hz measurement is valid if it contains at least one 20-Hz elementary measurement declared "ocean" in the processing; it is invalid otherwise.	1	Causes	binary uint8 <i>size: 0:3</i> Cause of invalidity for invalid measurements (1 = Acquisition mode, 2 = Not acquisition mode but over land (measurements over land are provided in OPR as invalid measurements), 3 = Not acquisition mode, not over land, but not "ocean" measurement, 4 = Other operating mode (generally ice tracking mode))	2	Qua_Raw	binary uint8 <i>size: 0:1</i> Quality of range estimate (0 = Good , 1 = Bad)
id	field name	definition												
0	Valid	binary uint8 <i>size: 0:1</i> Measurement validity (0 = Valid, 1 = Invalid). A 1-Hz measurement is valid if it contains at least one 20-Hz elementary measurement declared "ocean" in the processing; it is invalid otherwise.												
1	Causes	binary uint8 <i>size: 0:3</i> Cause of invalidity for invalid measurements (1 = Acquisition mode, 2 = Not acquisition mode but over land (measurements over land are provided in OPR as invalid measurements), 3 = Not acquisition mode, not over land, but not "ocean" measurement, 4 = Other operating mode (generally ice tracking mode))												
2	Qua_Raw	binary uint8 <i>size: 0:1</i> Quality of range estimate (0 = Good , 1 = Bad)												



3	Qua_Tele_Param	binary uint8	size: 0:1 Quality of telemetry parameters for range computation (0 = Good , 1 = Bad)
4	Qua_Cal_Cor	binary uint8	size: 0:1 Quality of internal calibration correction to range (0 = Good , 1 = Bad)
5	Qua_SWH	binary uint8	size: 0:1 Quality of significant wave height estimate (0 = Good , 1 = Bad)
6	Qua_Sigma0	binary uint8	size: 0:1 Quality of backscatter coefficient estimate (0 = Good , 1 = Bad)
7	Qua_Tele_Sigma0	binary uint8	size: 0:1 Quality of telemetry parameters for backscatter coefficient computation (0 = Good , 1 = Bad)
8	Qua_Sigma0_Cal_Cor	binary uint8	size: 0:1 Quality of internal calibration correction to backscatter coefficient (0 = Good , 1 = Bad)
9	Qua_Deriv	binary uint8	size: 0:1 Quality of range derivative estimate (0 = Good , 1 = Bad)
10	Typ_Alt_Cal_Cor	binary uint8	size: 0:1 Type of internal calibration for range correction (0 = Single Point Target Response, 1 = Invalid)
11	Typ_Sigma0_Cal_Cor	binary uint8	size: 0:1 Type of internal calibration for backscatter coefficient correction (0 = Single Point Target Response, 1 = Invalid)
12	Typ_Ocean_T	binary uint8	size: 0:1 Type of ocean tracking (0 = Nominal, 1 = Preset)



13	Sig_Wind_Sp	binary uint8	size: 0:1
		Backscatter coefficient value for wind speed computation (0 = Nominal, 1 = Out-of-range)	
14	Corr_Tide	binary uint8	size: 0:1
		Presence / Absence of tide corrections (0 = Presence, 1 = Absence)	
15	Sim_Radio	binary uint8	size: 0:1
		Presence / Absence of a simultaneous radiometer data (0 = Presence, 1 = Absence)	
16	Corr_TB_23	binary uint8	size: 0:1
		23.8 GHz brightness temperature value (TB_23) for altimetric correction (0 = Nominal, 1 = Out-of-range)	
17	Corr_TB_36	binary uint8	size: 0:1
		36.5 GHz brightness temperature value (TB_36) for altimetric correction (0 = Nominal, 1 = Out-of-range)	
18	OL_Flag	binary uint8	size: 0:1
		Ocean / Land flag for the radiometer (0 = ocean, 1 = land)	
19	Corr_Tropos	binary uint8	size: 0:1
		Presence / Absence of meteorological wet tropospheric correction (0 = Presence, 1 = Absence)	
20	MSS_DPAF	binary uint8	size: 0:1
		Presence / Absence of DPAF mean sea surface (0 = Presence, 1 = Absence (the four MSS nearby grid points over land))	
21	Manoeuvre	binary uint8	size: 0:1
		Orbit quality - manoeuvre (0 = Nominal, 1 = Manoeuvre). Set to 1 when the orbit quality is affected by a satellite manoeuvre. The corresponding orbit altitude H_Sat is computed, but is wrong.	



		22	MSS_OSU	binary uint8	size: 0:1
				Presence / Absence of OSU mean sea surface (0 = Presence, 1 = Absence (the four MSS nearby grid points over land))	
		23	Inv_Rad_Orb	binary uint8	size: 0:2
				Cause of invalidity of radial orbit correction (1 = radial orbit correction exceeds 60 cm, 2 = altimeter data on land, 3 = no OPR1 altimeter data available)	
		24	Unused	binary bytes	size: 0:5
				Spare	
				hidden: true	
2	Tim_1			binary int32	size: 4
				time stamp 1 (UTC time, in seconds, elapsed between the reference epoch (January 01, 1990 0 h.) and the time of the 1-Hz altimeter measurement, corresponding to the centre of the footprint).	
				unit: "s since 1990-01-01"	
3	Tim_2			binary int32	size: 4
				time stamp 2 (number of microseconds elapsed since the rounded second given in tim_1).	
				unit: "1e-6 s"	
4	Lat			binary int32 (double)	size: 4
				latitude	
				unit: "1e-6 degrees_north"	
				converted unit: "degrees_north" (multiply by 1/1e+006)	
5	Lon			binary int32 (double)	size: 4
				longitude	
				unit: "1e-6 degrees_east"	
				converted unit: "degrees_east" (multiply by 1/1e+006)	
6	Nval			binary int32	size: 4
				number of averaged 20-Hz measurements	



7	H_Alt_Raw	binary int32 (double) <i>size: 4</i> Range: raw value unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
8	Std_H_Alt	binary int32 (double) <i>size: 4</i> Standard deviation on range unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
9	H_Alt_SME	binary array[10] <i>size: 20</i> Difference of the i-th 10-Hz range from H_Alt_Raw (i=1,10) binary int16 (double) <i>size: 2</i> unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
10	Tim_SME	binary array[10] <i>size: 20</i> Difference of the i-th 10-Hz time from Tim_1, Tim_2 binary int16 (double) <i>size: 2</i> unit: "1e-4 s" converted unit: "s" (multiply by 1/10000)
11	H_Alt	binary int32 (double) <i>size: 4</i> Range corrected fro instrumental effects unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
12	H_Alt_LUT_Cor	binary int16 (double) <i>size: 2</i> Look-up table correction to range unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
13	H_Alt_Dop_Cor	binary int16 (double) <i>size: 2</i> Doppler correction to range unit: "1e-3 m"



		converted unit: "m" (multiply by 1/1000)
14	H_Alt_Cal_Cor_1	<p>binary int32 (double) <i>size: 4</i></p> <p>Internal calibration correction to range</p> <p>unit: "1e-3 m"</p> <p>converted unit: "m" (multiply by 1/1000)</p>
15	H_Alt_Cal_Cor_2	<p>binary int32 (double) <i>size: 4</i></p> <p>Initial setting for internal calibration correction to range</p> <p>unit: "1e-3 m"</p> <p>converted unit: "m" (multiply by 1/1000)</p>
16	Range_Deriv	<p>binary int16 (double) <i>size: 2</i></p> <p>Range first derivative</p> <p>unit: "1e-2 m/s"</p> <p>converted unit: "m/s" (multiply by 1/100)</p>
17	Dry_Cor	<p>binary int16 (double) <i>size: 2</i></p> <p>Dry tropospheric correction to range</p> <p>unit: "1e-3 m"</p> <p>converted unit: "m" (multiply by 1/1000)</p>
18	Wet_Cor	<p>binary int16 (double) <i>size: 2</i></p> <p>Meteorological wet tropospheric correction to range</p> <p>unit: "1e-3 m"</p> <p>converted unit: "m" (multiply by 1/1000)</p>
19	Pres_Err	<p>binary int16 (double) <i>size: 2</i></p> <p>Pressure field error</p> <p>unit: "1e2 Pa"</p> <p>converted unit: "Pa" (multiply by 100/1)</p>
20	Wet_H_Rad	<p>binary int16 (double) <i>size: 2</i></p> <p>Radiometer wet tropospheric correction to range</p> <p>unit: "1e-3 m"</p> <p>converted unit: "m" (multiply by 1/1000)</p>



21	Iono_Cor	binary int16 (double) <i>size: 2</i> Ionospheric correction to range unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
22	SSB_Cor	binary int16 (double) <i>size: 2</i> Sea state bias correction to range unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
23	H_Eot	binary int16 (double) <i>size: 2</i> Elastic ocean tide unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
24	H_Lt	binary int16 (double) <i>size: 2</i> Tidal loading effect unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
25	H_Set	binary int16 (double) <i>size: 2</i> Solid earth tide unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
26	H_Geo	binary int32 (double) <i>size: 4</i> Geoid height unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
27	H_MSS_DPAF	binary int32 (double) <i>size: 4</i> Mean sea surface height unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
28	H_Sat	binary int32 (double) <i>size: 4</i>



		Altitude above the reference ellipsoid unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
29	Orb_Err	binary int32 (double) size: 4 Orbit error unit: "1e-3 m" converted unit: "m" (multiply by 1/1000)
30	SWH_Raw	binary int16 (double) size: 2 Significant wave height - raw value unit: "1e-2 m" converted unit: "m" (multiply by 1/100)
31	Std_SWH	binary int16 (double) size: 2 Standard deviation on significant wave height unit: "1e-2 m" converted unit: "m" (multiply by 1/100)
32	SWH	binary int16 (double) size: 2 Significant wave height corrected for instrumental effects unit: "1e-2 m" converted unit: "m" (multiply by 1/100)
33	SWH_Lut_Cor	binary int16 (double) size: 2 Look-up table correction to significant wave height unit: "1e-2 m" converted unit: "m" (multiply by 1/100)
34	Sigma0_Raw	binary int16 (double) size: 2 Backscatter coefficient - raw value unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
35	Std_Sigma0	binary int16 (double) size: 2 Standard deviation on backscatter coefficient



		unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
36	Sigma0	binary int16 (double) <i>size: 2</i> Backscatter coefficient corrected for instrumental effects unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
37	Sigma0_LUT_Cor	binary int16 (double) <i>size: 2</i> Look-up table correction to backscatter coefficient unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
38	Sigma0_Cal_Cor	binary int16 (double) <i>size: 2</i> Internal calibration correction to backscatter coefficient unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
39	Sigma0_LW	binary int16 (double) <i>size: 2</i> Sigma0 corrected for cloud liquid water path attenuation unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
40	Wind_Sp	binary int16 (double) <i>size: 2</i> Wind speed unit: "1e-2 m/s" converted unit: "m/s" (multiply by 1/100)
41	Wind_Sp_LW	binary int16 (double) <i>size: 2</i> Wind speed corrected for cloud liquid water path attenuation unit: "1e-2 m/s" converted unit: "m/s" (multiply by 1/100)
42	TB_23	binary int16 (double) <i>size: 2</i> 23.8 GHz brightness temperature unit: "1e-1 K"



		converted unit: "K" (multiply by 1/10)
43	TB_36	<p>binary int16 (double) <i>size: 2</i></p> <p>36.5 GHz brightness temperature</p> <p>unit: "1e-1 K"</p> <p>converted unit: "K" (multiply by 1/10)</p>
44	WV_Cont	<p>binary int16 (double) <i>size: 2</i></p> <p>Water vapour content</p> <p>unit: "1e-2 g/cm2"</p> <p>converted unit: "g/cm2" (multiply by 1/100)</p>
45	WV_Cont_WS	<p>binary int16 (double) <i>size: 2</i></p> <p>Precise water vapour content (wind speed included)</p> <p>unit: "1e-2 g/cm2"</p> <p>converted unit: "g/cm2" (multiply by 1/100)</p>
46	LW_Cont	<p>binary int16 (double) <i>size: 2</i></p> <p>Liquid water content</p> <p>unit: "1e-2 kg/cm2"</p> <p>converted unit: "kg/cm2" (multiply by 1/100)</p>
47	LW_Cont_WS	<p>binary int16 (double) <i>size: 2</i></p> <p>Precise liquid water content (wind speed included)</p> <p>unit: "1e-2 kg/cm2"</p> <p>converted unit: "kg/cm2" (multiply by 1/100)</p>
48	H_MSS_OSU	<p>binary int32 (double) <i>size: 4</i></p> <p>OSU Mean sea surface height</p> <p>unit: "1e-3 m"</p> <p>converted unit: "m" (multiply by 1/1000)</p>
49	Square_Off_Nad	<p>binary int32 (double) <i>size: 4</i></p> <p>Waveform-derived square of the off-nadir angle (1-Hz estimate)</p> <p>unit: "1e-6 degrees2"</p> <p>converted unit: "degrees2" (multiply by 1/1e+006)</p>



50	Square_Off_Nad_Smoothed	binary int32 (double) <i>size: 4</i> Waveform-derived square of the off-nadir angle (smoothed estimate) unit: "1e-6" degrees2" converted unit: "degrees2" (multiply by 1/1e+006)
51	Spare	binary bytes <i>size: 4</i> Spare hidden: true

3.3. GFO data

3.3.1. Filenaming convention

The nomenclature is:

gfo_cCCC_pPPP.gdr

where:

- "CCC" identifies the 17-day repeat cycle number
- "PPP" identifies the pass (half-revolution) number of the GDR

3.3.2. Product data format

3.3.2.1. GDR_HEADER

ascii record "[GDR_HEADER](#)"

id	field name	definition
0	PASS_BEGIN_TIME_label	ascii string <i>size: 18</i> PASS_BEGIN_TIME = fixed value: "PASS_BEGIN_TIME = " hidden: true
1	PASS_BEGIN_TIME	ascii double UTC time, in seconds since 1/1/1985, of the first data record in the file. This time corresponds to the midframe time of the 1-Hz average of the first record



		unit: "s since 1985-01-01"
2	semicolon_1	<p>ascii string <i>size</i>: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
3	newline_1	<p>ascii string <i>size</i>: 1</p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
4	EQ_CROSSING_TIME_LON_label	<p>ascii string <i>size</i>: 23</p> <p>EQ_CROSSING_TIME_LON =</p> <p>fixed value: "EQ_CROSSING_TIME_LON = "</p> <p>hidden: true</p>
5	EQ_CROSSING_TIME	<p>ascii double</p> <p>time of the equator crossing point for this pass. The value is generated from the once per minute ephemeris data, interpolated to the equator crossing</p> <p>unit: "s since 1985-01-01"</p>
6	EQ_CROSSING_LON	<p>ascii double</p> <p>longitude of the equator crossing point for this pass. The value is generated from the once per minute ephemeris data, interpolated to the equator crossing</p> <p>unit: "degrees_east"</p>
7	semicolon_2	<p>ascii string <i>size</i>: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
8	newline_2	<p>ascii string <i>size</i>: 1</p>



		newline fixed value: "\n" hidden: true
9	CYCLE_NUMBER_label	ascii string size: 15 CYCLE_NUMBER = fixed value: "CYCLE_NUMBER = " hidden: true
10	CYCLE_NUMBER	ascii uint32 determined from the equator crossing table, with cycle "zero" defined as the first (partial) 17-day cycle after the satellite attained its exact repeat orbit on 4/20/1998. With this definition, cycle number one, pass number one, has an equator crossing time of ~ 22:11 UTC on 5/3/1998. The first SDR data were generated during cycle one, beginning on 5/10/1998
11	semicolon_3	ascii string size: 1 semicolon fixed value: ";" hidden: true
12	newline_3	ascii string size: 1 newline fixed value: "\n" hidden: true
13	PASS_NUMBER_label	ascii string size: 14 PASS_NUMBER = fixed value: "PASS_NUMBER = " hidden: true
14	PASS_NUMBER	ascii uint16 the number of half revolutions since the beginning of the current cycle, ranging from 1 to 488. These are in order of increasing equator crossing time, with all ascending passes odd-numbered, and all



		descending passes even-numbered. Pass number one is defined as the pass whose equator crossing longitude is the smallest east longitude in the range 0-360 degrees. This pass had an average equator crossing longitude of approximately 1.01 E. Subsequent pass numbers have equator crossing times roughly 50 minutes later than the previous pass
15	semicolon_4	<p>ascii string <i>size</i>: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
16	newline_4	<p>ascii string <i>size</i>: 1</p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
17	PROCESSING_TIME_label	<p>ascii string <i>size</i>: 18</p> <p>PROCESSING_TIME =</p> <p>fixed value: "PROCESSING_TIME = "</p> <p>hidden: true</p>
18	PROCESSING_TIME	<p>ascii string <i>size</i>: 24</p> <p>the time at which the GDR was created from the input SDRs. It is comprised of a 24-byte UNIX date and time stamp, e.g. "Mon Jun 10 14:30:00 2002"</p>
19	semicolon_5	<p>ascii string <i>size</i>: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
20	newline_5	<p>ascii string <i>size</i>: 1</p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>



21	PROCESSING_CENTER_label	ascii string <i>size: 20</i> PROCESSING_CENTER = fixed value: "PROCESSING_CENTER = " hidden: true
22	PROCESSING_CENTER	ascii string [line] processing center where the GDR was created, e.g. "NOAA LSA"
23	newline_6	ascii string <i>size: 1</i> newline fixed value: "\n" hidden: true
24	SOFTWARE_VERSION_label	ascii string <i>size: 19</i> SOFTWARE_VERSION = fixed value: "SOFTWARE_VERSION = " hidden: true
25	SOFTWARE_VERSION	ascii string [line] current version of the GDR processing software
26	newline_7	ascii string <i>size: 1</i> newline fixed value: "\n" hidden: true
27	SATELLITE_ID_label	ascii string <i>size: 15</i> SATELLITE_ID = fixed value: "SATELLITE_ID = " hidden: true
28	SATELLITE_ID	ascii string [line] satellite that was processed, e.g. "GFO"
29	newline_8	ascii string <i>size: 1</i>



		<p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
30	DATA_RECORD_LENGTH_label	<p>ascii string <i>size: 21</i></p> <p>DATA_RECORD_LENGTH =</p> <p>fixed value: "DATA_RECORD_LENGTH = "</p> <p>hidden: true</p>
31	DATA_RECORD_LENGTH	<p>ascii uint16</p> <p>length in bytes of the total GDR Data Record. This is currently 184 bytes for the GFO GDRs</p>
32	semicolon_9	<p>ascii string <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
33	newline_9	<p>ascii string <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
34	BASIC_GDR_LENGTH_label	<p>ascii string <i>size: 19</i></p> <p>BASIC_GDR_LENGTH =</p> <p>fixed value: "BASIC_GDR_LENGTH = "</p> <p>hidden: true</p>
35	BASIC_GDR_LENGTH	<p>ascii uint16</p> <p>length in bytes of the portion of the GDR Data Record which is common between all GDR files for different satellites. This is currently 98 bytes, as defined by NAVO data processing conventions</p>
36	semicolon_10	<p>ascii string <i>size: 1</i></p> <p>semicolon</p>



		fixed value: ";" hidden: true
37	newline_10	ascii string <i>size: 1</i> newline fixed value: "\n" hidden: true
38	HEIGHT_CALIBRATION_BIAS_label	ascii string <i>size: 26</i> HEIGHT_CALIBRATION_BIAS = fixed value: "HEIGHT_CALIBRATION_BIAS = " hidden: true
39	HEIGHT_CALIBRATION_BIAS	ascii double equal to the "Height Calibration Bias" in the SDR Header unit: "mm"
40	semicolon_11	ascii string <i>size: 1</i> semicolon fixed value: ";" hidden: true
41	newline_11	ascii string <i>size: 1</i> newline fixed value: "\n" hidden: true
42	ALTITUDE_BIAS_INITIAL_label	ascii string <i>size: 24</i> ALTITUDE_BIAS_INITIAL = fixed value: "ALTITUDE_BIAS_INITIAL = " hidden: true
43	ALTITUDE_BIAS_INITIAL	ascii double equal to the "Altitude Bias (Initial)" in the SDR



		Header unit: "km"
44	semicolon_12	ascii string <i>size: 1</i> semicolon fixed value: ";" hidden: true
45	newline_12	ascii string <i>size: 1</i> newline fixed value: "\n" hidden: true
46	ALTITUDE_BIAS_CENTER_OF_GRAVITY_label	ascii string <i>size: 34</i> ALTITUDE_BIAS_CENTER_OF_GRAVITY = fixed value: "ALTITUDE_BIAS_CENTER_OF_GRAVITY = " hidden: true
47	ALTITUDE_BIAS_CENTER_OF_GRAVITY	ascii double equal to the "Altitude Bias based on S/C CG" in the SDR Header unit: "mm"
48	semicolon_13	ascii string <i>size: 1</i> semicolon fixed value: ";" hidden: true
49	newline_13	ascii string <i>size: 1</i> newline fixed value: "\n" hidden: true
50	TIMING_BIAS_INITIAL_label	ascii string <i>size: 22</i> TIMING_BIAS_INITIAL =



		fixed value: "TIMING_BIAS_INITIAL = " hidden: true
51	TIMING_BIAS_INITIAL	ascii double equal to "Timing Bias (Initial)" in the SDR Header. All times in the GDRs have been computed by subtracting this quantity from the corresponding times in the SDRs unit: "ms"
52	semicolon_14	ascii string <i>size: 1</i> semicolon fixed value: ";" hidden: true
53	newline_14	ascii string <i>size: 1</i> newline fixed value: "\n" hidden: true
54	AGC_CALIBRATION_BIAS_label	ascii string <i>size: 23</i> AGC_CALIBRATION_BIAS = fixed value: "AGC_CALIBRATION_BIAS = " hidden: true
55	AGC_CALIBRATION_BIAS	ascii double equal to "AGC Calibration Bias" in the SDR Header unit: "dB"
56	semicolon_15	ascii string <i>size: 1</i> semicolon fixed value: ";" hidden: true
57	newline_15	ascii string <i>size: 1</i> newline



		fixed value: "\n" hidden: true
58	AGC_BIAS_INITIAL_label	ascii string <i>size: 19</i> AGC_BIAS_INITIAL = fixed value: "AGC_BIAS_INITIAL = " hidden: true
59	AGC_BIAS_INITIAL	ascii double equal to "AGC Bias (Initial)" in the SDR Header unit: "dB"
60	semicolon_16	ascii string <i>size: 1</i> semicolon fixed value: ";" hidden: true
61	newline_16	ascii string <i>size: 1</i> newline fixed value: "\n" hidden: true
62	ORBIT_label	ascii string <i>size: 8</i> ORBIT = fixed value: "ORBIT = " hidden: true
63	ORBIT	ascii string <i>size: 10</i> specifies the type of laser orbit ephemeris file ("moe" = medium orbit ephemeris; "poe" = precise orbit ephemeris) and the arc date string. The arc date is of the form "ZYMMDD" where Z indicates the decade ("n" for 1990; "z" for 2000); Y indicates the year within the decade (0-9); MM is the month (01-12) and DD is the day of the month (01-31)
64	semicolon_17	ascii string <i>size: 1</i>



		semicolon fixed value: ";" hidden: true
65	newline_17	ascii string <i>size: 1</i> newline fixed value: "\n" hidden: true
66	PASS_END_TIME_label	ascii string <i>size: 16</i> PASS_END_TIME = fixed value: "PASS_END_TIME = " hidden: true
67	PASS_END_TIME	ascii double et to the UTC time, in seconds since 1/1/1985, of the last data record in the file. This time corresponds to the midframe time of the 1-Hz average of the final record unit: "s since 1985-01-01"
68	semicolon_18	ascii string <i>size: 1</i> semicolon fixed value: ";" hidden: true
69	newline_18	ascii string <i>size: 1</i> newline fixed value: "\n" hidden: true
70	NUMBER_GDR_RECORDS_label	ascii string <i>size: 21</i> NUMBER_GDR_RECORDS = fixed value: "NUMBER_GDR_RECORDS = " hidden: true



71	NUMBER_GDR_RECORDS	ascii uint32 count of one-second average records within the GDR
72	semicolon_19	ascii string <i>size</i> : 1 semicolon fixed value: ";" hidden: true
73	newline_19	ascii string <i>size</i> : 1 newline fixed value: "\n" hidden: true
74	END_OF_HEADER	ascii string <i>size</i> : 13 END_OF_HEADER fixed value: "END_OF_HEADER" hidden: true
75	newline_20	ascii string <i>size</i> : 1 newline fixed value: "\n" hidden: true

3.3.2.2. GDR_DATA_RECORD

binary record "[GDR_DATA_RECORD](#)"

size: 184

id	field name	definition
0	Time_Past_Epoch	binary uint32 <i>size</i> : 4 time at the midframe expressed as the number of integer seconds since January 1, 1985, 0.0 hours UTC. Compute the actual midframe time as follows: Time_Midframe [sec] = Time_Past_Epoch [sec] + Time_Past_Epoch_Continued [microsec] * 1E-6 unit: "s since 1985-01-01"



1	Time_Past_Epoch_Continued	binary uint32 <i>size: 4</i> the fractional contribution to the total Time Past Epoch unit: "1e-6 s"
2	Latitude	binary int32 (double) <i>size: 4</i> geodetic latitude calculated at the midframe, where north is positive and south is negative. This quantity is derived from an ephemeris or Keplerian elements unit: "1e-6 degrees_north" converted unit: "degrees_north" (multiply by 1/1e+006)
3	Longitude	binary int32 (double) <i>size: 4</i> east geodetic longitude calculated at the midframe, where $0 \leq \text{longitude} < 360$. This quantity is derived from an ephemeris or Keplerian elements unit: "1e-6 degrees_east" converted unit: "degrees_east" (multiply by 1/1e+006)
4	SSHU	binary int32 <i>size: 4</i> SSH Uncorrected (SSHU) is the 1-Hz Sea Surface Height (SSH) relative to the ellipsoid, without any environmental corrections. The 1-Hz value is calculated at the midframe using the 10-Hz SSHU values. The 1-Hz value is obtained from a linear fit with iterative outlier rejection applied to the 10-Hz values. $\text{SSHU [mm]} = \text{Satellite_Altitude} - (\text{Satellite_Range} + \text{Net_Height_Correction})$, where <i>Satellite_Range</i> is the uncorrected height of the satellite above the sea surface, obtained from the SDR parameters H(1) through H(10) unit: "mm"
5	SSHC	binary int32 <i>size: 4</i> SSH Corrected (SSHC) is the 1-Hz Sea Surface Height (SSH) relative to the ellipsoid, with environmental corrections. The 1-Hz value is calculated at the midframe using the 10-Hz SSHC values. The 1-Hz value is obtained from a linear fit with iterative outlier rejection applied to the 10-Hz values. SSHC is calculated from SSHU. $\text{SSHC [mm]} = \text{SSHU} - \text{Environmental_Corrections}$, where <i>Environmental_Corrections</i> = <i>Ionosphere</i> + <i>Dry_Troposphere</i> + <i>Wet_Troposphere_MWR</i> + <i>Inverse_Barometer</i> + <i>Ocean_Water_Tide</i> + <i>Ocean_Load_Tide</i> + <i>Solid_Earth_Tide</i> + <i>Pole_Tide</i> + <i>Sea_State_Bias</i> unit: "mm"
6	Altitude	binary uint32 <i>size: 4</i> the geodetic height of the satellite above the reference



		ellipsoid, calculated at the midframe. This quantity is derived from an ephemeris or Keplerian elements unit: "mm"
7	Time_Shift_Midframe	binary int32 <i>size: 4</i> time offset between the first high-rate (10-Hz) sample in the GDR record, and the time of the 1-Hz record (Time_Past_Epoch + 1E-6 * Time_Past_Epoch_Continued). Times of SDR Data Records pertain to the first RA data sample of the high-rate data, while times of GDR Data Records pertain to the midframe, located halfway between high-rate samples five and six. All GDR times have been corrected by subtracting TIMING_BIAS_INITIAL from the SDR times. Time Shift Midframe is calculated from the "Ratio" parameter in the SDR Header as follows: Time_Shift_Midframe [microsec] = (4.5 * 0.098 * 1E6 * Ratio_SDR) unit: "1e-6 s"
8	SWH	binary uint16 (double) <i>size: 2</i> 1-Hz Significant Wave Height calculated at the midframe using the 10-Hz SWH's from the SDR. The 1-Hz value is obtained from a linear fit with iterative outlier rejection. SWH [cm] = SWH_SDR[m] * 100 unit: "1e-2 m" converted unit: "m" (multiply by 1/100)
9	Sigma0	binary uint16 (double) <i>size: 2</i> equal to the "Backscatter Coefficient" from the SDR Data Record unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
10	Wind_Speed	binary uint16 (double) <i>size: 2</i> Wind Speed [cm/sec] is calculated from Sigma0 using a modified Chelton-Wentz algorithm: Wind_Speed [cm/sec] = 100 * SUM{ a(coeff_index,i) * Sigma0**i }i=0,1,2,3,4 where coeff_index = 0 for Sigma0 < 11.4, coeff_index = 1 for 11.4 <= Sigma0 < 20.2, coeff_index = 2 for Sigma0 >= 20.2, and a(coeff_index,i) is a 3x5 array with the following values: { {58.7614523 , -13.58500361, 2.239083411, -0.188532055, 0.005438225}, {366.3919346, -81.88668532, 6.890552953, -0.257760189, 0.003607894}, {0.0 , 0.0 , 0.0 , 0.0 , 0.0 } }. Reference: Witter, D.L., and D.B. Chelton, A Geosat wind speed algorithm and a method for altimeter wind speed algorithm development. J. Geophys. Res., 96, 8853-8860, 1991



		unit: "1e-2" m/s" converted unit: "m/s" (multiply by 1/100)
11	AGC	binary uint16 <i>size: 2</i> (double) 1-Hz Automatic Gain Control calculated at the midframe using the 10-Hz AGC's from the SDR. The 1-Hz value is obtained from a linear fit with iterative outlier rejection. AGC [0.01 dB] = AGC_SDR[dB] * 100 + Net_AGC_Correction [0.01 dB] unit: "1e-2" dB" converted unit: "dB" (multiply by 1/100)
12	Dry_Troposphere	binary int16 <i>size: 2</i> Dry Troposphere [mm] is derived from the NOAA NCEP Reanalysis Project sea level pressure data set. The value is determined by bilinear interpolation in space, and linear interpolation in time, from the 6-hourly, 2.5 degree spatial grids. Dry_Troposphere [mm] = -2.273 * (1 + 0.0026 * cos (2 * Latitude[radians])) * Sea_Level_Pressure[mbar] unit: "mm"
13	Wet_Troposphere	binary int16 <i>size: 2</i> Wet Troposphere (MWR) [mm] is the wet correction measured by the onboard microwave radiometer. It is obtained from the "Path Delay" variable in SDR Data Record as follows: Wet_Troposphere_MWR [mm] = -10 * Path_Delay_SDR [cm] unit: "mm"
14	Ionosphere	binary int16 <i>size: 2</i> Ionosphere [mm] is the altimeter range correction derived from the total electron content (TEC) in the atmosphere. Ionosphere is obtained from the University of Bern (Switzerland) "CODE" Global Ionosphere Maps (GIM). Two-hourly GIM maps are bilinearly interpolated, after rotation in solar/magnetic coordinates, to provide a precise value based on GPS measurements. The TEC measurements are converted to a range correction using the square of the GFO Ku-band frequency: Ionosphere [mm] = -402.5 * TEC[1016 electrons/m2] / f2 where f = 13.495 is the radar frequency, in GHz, and "1016 electrons/m2" is commonly referred to as a "TEC unit" unit: "mm"
15	Inverse_Barometer	binary int16 <i>size: 2</i> Inverse Barometer [mm] is calculated from the NOAA NCEP Reanalysis Project sea level pressure data set as follows: Inverse_Barometer [mm] = -9.948* (Sea_Level_Pressure[mbar] -



		<p>Mean_Ocean_Pressure[mbar]), Surface_Pressure values are "local" measurements at the sub-satellite nadir location (lat/lon), determined from bilinear spatial and linear temporal interpolation of the 6-hourly, 2.5 degree grids. The Mean_Ocean_Pressure values are calculated for each 6-hourly grid by averaging all Sea_Level_Pressure values that are over ocean (and not land) gridpoints. The 6-hourly time series is then smoothed with a 2-day filter, and the resulting time series of Mean_Ocean_Pressure is linearly interpolated in time to the measurement time of the data record</p> <p>unit: "mm"</p>
16	Sea_State_Bias	<p>binary int16 <i>size: 2</i></p> <p>Sea State Bias [mm] (SSB) is calculated as 4.5% of SWH: $\text{Sea_State_Bias [mm]} = -0.045 * (\text{SWH[cm]} * 10)$ </p> <p>unit: "mm"</p>
17	Solid_Earth_Tide	<p>binary int16 <i>size: 2</i></p> <p>Solid Earth Tide [mm] is calculated as follows: Solid_Earth_Tide [mm] = $1000 * (\text{RH2} * \text{V2} + \text{RH3} * \text{V3}) / \text{GRAVITY}$, where RH2 = 0.609, RH3 = 0.291, and GRAVITY = 9.80. V2 and V3 are the second and third degree potential values (in the MKS system) from the tide-generating potential as given by Cartwright and Tayler (1971) and corrected by Cartwright and Edden (1973). Reference: Cartwright, D.E., and A.C. Edden, Corrected tables of tidal harmonics. Geophys. J. Roy. Soc., 23, 253-264, 1973</p> <p>unit: "mm"</p>
18	Ocean_Water_Tide	<p>binary int16 <i>size: 2</i></p> <p>Ocean Water Tide [mm] is calculated from the NASA Goddard Space Flight Center GOT00.2 tide model</p> <p>unit: "mm"</p>
19	Ocean_Load_Tide	<p>binary int16 <i>size: 2</i></p> <p>Ocean Load Tide [mm] is calculated from the NASA Goddard Space Flight Center GOT00.2 tide model</p> <p>unit: "mm"</p>
20	Pole_Tide	<p>binary int16 <i>size: 2</i></p> <p>Pole Tide [mm] is calculated as follows: Pole_Tide [mm] = $A * \sin(2 * \text{Latitude[radians]}) * ((\text{Polar_location_X} - \text{X_pole_avg}) * \cos(\text{Longitude[radians]}) - (\text{Polar_location_Y} - \text{Y_pole_avg}) * \sin(\text{Longitude[radians]}))$, where A = -69.435, X_pole_avg = 0.042, and Y_pole_avg = 0.293. The "Polar_location_X" and "Polar_location_Y" values are the polar motion angles (in arcsec) obtained from data in the orbit ephemeris files</p>



		unit: "mm"
21	Water_Depth	<p>binary int16 <i>size: 2</i></p> <p>Water Depth [m] is obtained from the NOAA/NGDC ETOPO2 two-minute topography/bathymetry data base, which is largely based on predicted bathymetry from satellite altimetry</p> <p>unit: "m"</p>
22	Geoid_Depth	<p>binary int32 <i>size: 4</i></p> <p>Geoid Height [mm] is obtained from the joint NASA/NIMA EGM96 database</p> <p>unit: "mm"</p>
23	Mean_Sea_Surface_I	<p>binary int32 <i>size: 4</i></p> <p>Mean Sea Surface I [mm] is obtained from the NASA Goddard Space Flight Center GSFC00.1 two-minute mean sea surface database</p> <p>unit: "mm"</p>
24	Mean_Sea_Surface_II	<p>binary int32 <i>size: 4</i></p> <p>Mean Sea Surface II [mm] is obtained from the OSUMSS95 one-sixteenth degree database</p> <p>unit: "mm"</p>
25	SSHU_STD	<p>binary uint16 <i>size: 2</i></p> <p>SSHU STD [mm] is the standard deviation from the fit applied to the 10-Hz SSHU values</p> <p>unit: "mm"</p>
26	SWH_STD	<p>binary uint16 (double) <i>size: 2</i></p> <p>SWH STD [cm] is the standard deviation from the fit applied to the 10-Hz SWH values</p> <p>unit: "1e-2 m"</p> <p>converted unit: "m" (multiply by 1/100)</p>
27	AGC_STD	<p>binary uint16 (double) <i>size: 2</i></p> <p>AGC STD [0.01 dB] is the standard deviation from the fit applied to the 10-Hz AGC values</p> <p>unit: "1e-2 dB"</p> <p>converted unit: "dB" (multiply by 1/100)</p>



28	Net_Height_Correction	<p>binary int16 <i>size: 2</i></p> <p>Net Height Correction [mm] is calculated from fields in the SDR Header and Data Record as follows: $\text{Net_Height_Correction [mm]} = \text{Attitude_Wave_Height_Bias_SDR} - \text{Height_Calibration_Bias_SDR} + \text{Altitude_Bias_Center_of_Gravity_SDR} - (1\text{E}6 * \text{Altitude_Bias_Initial_SDR} - \text{FM_Crosstalk_SDR})$</p> <p>unit: "mm"</p>
29	Net_SWH_Correction	<p>binary int16 <i>size: 2</i></p> <p>Net SWH Correction [mm] is calculated from the "SWH Bias" in the SDR Data Record as follows: $\text{Net_SWH_Correction [mm]} = \text{SWH_Bias_SDR[m]} * 1000$</p> <p>unit: "mm"</p>
30	Net_AGC_Correction	<p>binary int16 (double) <i>size: 2</i></p> <p>Net AGC Correction is calculated from fields in the SDR Header and Data Record as follows: $\text{Net_AGC_Correction [0.01 dB]} = \text{AGC_Temperature_Correction_SDR} + \text{Delta_AGC_Height_SDR} + \text{AGC_Correction_for_Attitude_SDR} - \text{AGC_Calibration_Bias_SDR}$</p> <p>unit: "1e-2 dB"</p> <p>converted unit: "dB" (multiply by 1/100)</p>
31	Time_Tag_Deviation_1_Hz	<p>binary int32 (double) <i>size: 4</i></p> <p>The 1-Hz Time-tag Deviation is the difference between the actual and nominal inter-record spacing. This quantity is a function of the SDR Header variable "Ratio", which can change within a pass, and therefore it is carried as a data variable within the GDR. The nominal value of Ratio is 0.99992E-6. The 1-Hz inter-record spacing, in seconds, is $0.98 * \text{ratio} * 1\text{E}6$. Hence the nominal value of the 1-Hz time-tag is $0.98 * 0.99992 = 0.9799216$ seconds. The actual 1-Hz time-tag spacing is computed from the current value of Ratio in the SDR header, and the difference between the actual and nominal values is stored as the time-tag deviation, in units of femtoseconds. This high-precision value allows the SDR "Ratio" parameter to be reconstructed for time-tagging adjustments and calculation of the Ultra-Stable-Oscillator (USO) height correction. The USO height correction is implicitly applied during SDR generation, and is defined as: $\text{Delta-h_USO[mm]} = \text{h_0[mm]} * \text{Delta-dt[sec]} / \text{dt[sec]}$, where "dt" is the 1-Hz time-tag spacing, and "Delta-dt" is the 1-Hz Time-tag Deviation. The order of magnitude of Delta-dt/dt is 10⁻⁷; with height values h₀ around 800 km, the Delta-h_{USO} term is on the order of 8 cm</p> <p>unit: "1e-15 s"</p> <p>converted unit: "s" (multiply by 1/1e+015)</p>



32	Attitude_Squared	<p>binary int16 <i>size: 2</i> (double)</p> <p>Attitude Squared [10-4 deg2] is computed from the SDR variable Fitted_VATT, which is directly proportional to the square of attitude: $\text{Attitude_Squared [10-4 deg2]} = b1*b1*(\text{Fitted_VATT_SDR} - b0) * 1E4$ where $b0 = 1.11$, $b1 = .8747$. This waveform-derived estimate of spacecraft attitude2 has a near-Gaussian distribution around the actual platform attitude, and hence can be negative when the true attitude is nearly zero (perfect nadir pointing). Hence it is desirable to store the square of attitude as a signed quantity, rather than truncating attitude estimates when a "negative square root" error would otherwise occur</p> <p>unit: "1e-4 degrees2" converted unit: "degrees2" (multiply by 1/10000)</p>									
33	NOAA_FLAGS	<p>binary record <i>size: 2</i></p> <table border="1" data-bbox="614 875 1391 1370"> <thead> <tr> <th data-bbox="614 875 646 927">id</th> <th data-bbox="646 875 810 927">field name</th> <th data-bbox="810 875 1391 927">definition</th> </tr> </thead> <tbody> <tr> <td data-bbox="614 927 646 1128">0</td> <td data-bbox="646 927 810 1128">Spare</td> <td data-bbox="810 927 1391 1128"> <p>binary bytes <i>size: 1:6</i> Unused hidden: true</p> </td> </tr> <tr> <td data-bbox="614 1128 646 1370">1</td> <td data-bbox="646 1128 810 1370">Land_Ocean</td> <td data-bbox="810 1128 1391 1370"> <p>binary uint8 <i>size: 0:2</i> 2-minute landmask grid, generated from the Generic Mapping Tools (GMT) shoreline database. The four possible states are: 0 = Ocean, 1 = N/A ("dry ocean"), 2 = Lake or Inland Sea, 3 = Land</p> </td> </tr> </tbody> </table>	id	field name	definition	0	Spare	<p>binary bytes <i>size: 1:6</i> Unused hidden: true</p>	1	Land_Ocean	<p>binary uint8 <i>size: 0:2</i> 2-minute landmask grid, generated from the Generic Mapping Tools (GMT) shoreline database. The four possible states are: 0 = Ocean, 1 = N/A ("dry ocean"), 2 = Lake or Inland Sea, 3 = Land</p>
id	field name	definition									
0	Spare	<p>binary bytes <i>size: 1:6</i> Unused hidden: true</p>									
1	Land_Ocean	<p>binary uint8 <i>size: 0:2</i> 2-minute landmask grid, generated from the Generic Mapping Tools (GMT) shoreline database. The four possible states are: 0 = Ocean, 1 = N/A ("dry ocean"), 2 = Lake or Inland Sea, 3 = Land</p>									
34	Wet_Troposphere_Model	<p>binary int16 <i>size: 2</i></p> <p>Wet Troposphere (Model) is derived from the NOAA NCEP Reanalysis Project total precipitable water data set. The value is determined by bilinear interpolation in space, and linear interpolation in time, from the 6-hourly, 2.5 degree spatial grids: $\text{Wet_Troposphere_Model [mm]} = -6.36 * \text{Total_Precipitable_Water [kg/m2]}$</p> <p>unit: "mm"</p>									
35	Instrument_State_Flags	<p>binary uint8 <i>size: 1</i></p> <p>Not used at this time. It will be used to verify that the instrument state has not changed</p> <p>hidden: true</p>									
36	NVals_SSHU	<p>binary int8 <i>size: 1</i></p>									



		number of high-rate values used in the calculation of the 1-Hz SSHU
37	NVals_SWH	<p>binary int8 <i>size: 1</i></p> <p>number of high-rate values used in the calculation of the 1-Hz SWH</p>
38	NVals_AGC	<p>binary int8 <i>size: 1</i></p> <p>number of high-rate values used in the calculation of the 1-Hz AGC</p>
39	SWH_High_Rate	<p>binary array[10] <i>size: 20</i></p> <p>SWH High-Rate is calculated from the "SWH" high-rate values in the SDR Data Record (fields 20 through 29) as follows: $\text{SWH_High_Rate}(i) \text{ [cm]} = \text{SWHSDR}(i) \text{ [m]} * 100 + \text{Net_SWH_Correction}, i=1, \dots, 10$</p> <p>binary uint16 (double) <i>size: 2</i></p> <p>unit: "1e-2 m"</p> <p>converted unit: "m" (multiply by 1/100)</p>
40	SSHU_High_Rate	<p>binary array[10] <i>size: 20</i></p> <p>SSHU High-Rate Differences [mm] are the differences of the high-rate SSHU values from the 1-Hz SSHU value. The original high-rate SSHU values can be reconstructed by adding them to the 1-Hz SSHU value</p> <p>binary int16 <i>size: 2</i></p> <p>unit: "mm"</p>
41	Altitude_High_Rate	<p>binary array[10] <i>size: 20</i></p> <p>Altitude High-Rate Differences [mm] are the differences of the high-rate Altitude values from the 1-Hz Altitude value. The original high-rate Altitude values can be reconstructed by adding them to the 1-Hz Altitude value</p> <p>binary int16 <i>size: 2</i></p> <p>unit: "mm"</p>
42	Brightness_Temp_22GHz	<p>binary uint16 (double) <i>size: 2</i></p> <p>22 GHz Brightness Temp is calculated from the "22 GHz Brightness Temp" in the SDR Data Record as follows: $\text{22 GHz Brightness Temp [0.01 deg K]} = \text{22 GHz Brightness Temp_SDR[deg K]} * 100$</p> <p>unit: "1e-2 K"</p>



		converted unit: "K" (multiply by 1/100)
43	Brightness_Temp_37GHz	<p>binary uint16 (double) <i>size: 2</i></p> <p>37 GHz Brightness Temp is calculated from the "37 GHz Brightness Temp" in the SDR Data Record as follows: $37 \text{ GHz Brightness Temp [0.01 deg K]} = 37 \text{ GHz Brightness Temp_SDR[deg K]} * 100$</p> <p>unit: "1e-2" "K"</p> <p>converted unit: "K" (multiply by 1/100)</p>
44	RA_Status_Mode_I	<p>binary uint16 <i>size: 2</i></p> <p>RA Status Mode I is set equal to the "RA Status Mode I" from the SDR Data Record. This is a bit field</p>
45	RA_Status_Mode_II	<p>binary uint16 <i>size: 2</i></p> <p>RA Status Mode II is set equal to the "RA Status Mode I" from the SDR Data Record. This is a bit field</p>
46	Receiver_Temperature	<p>binary int16 (double) <i>size: 2</i></p> <p>Receiver Temperature is calculated from the "Receiver Temperature" in the SDR Data Record as follows: $\text{Receiver Temperature [0.01 deg C]} = \text{Receiver TemperatureSDR[deg C]} * 100$</p> <p>unit: "1e-2" "degC"</p> <p>converted unit: "degC" (multiply by 1/100)</p>
47	Quality_Word_I	<p>binary uint32 <i>size: 4</i></p> <p>Quality Word I is set equal to the "RA Quality Test Results" from the SDR Data Record. This is a bit field</p>
48	Quality_Word_II	<p>binary uint32 <i>size: 4</i></p> <p>Quality Word II is set equal to the "WVR Quality Test Results" from the SDR Data Record. This is a bit field</p>
49	Average_VATT	<p>binary int32 (double) <i>size: 4</i></p> <p>Average VATT is calculated from the "Average VATT" in the SDR Data Record as follows: $\text{Average VATT [microvolt]} = \text{Average VATT_SDR[volt]} * 1E6$</p> <p>unit: "1e-6" "V"</p> <p>converted unit: "V" (multiply by 1/1e+006)</p>
50	Fitted_VATT	<p>binary int32 (double) <i>size: 4</i></p>



	<p>Fitted VATT is calculated from the "Fitted VATT" in the SDR Data Record as follows: Fitted VATT [microvolt] = Fitted VATT_SDR[volt] * 1E6</p> <p>unit: "1e-6 V"</p> <p>converted unit: "V" (multiply by 1/1e+006)</p>
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3.4. Envisat data

3.4.1. Filenaming convention

The naming convention for products is:

filename = RA2_GDR_2P<processing_stage_flag><originator_ID><start_day> <"_">

<start_time> <"_"> <duration> <phase> <cycle> <"_"> <relative_orbit> <"_"> <absolute_orbit>
<"_"><counter><"."> <satellite_ID> <.extension>

3.4.2. Product data format

3.4.2.1. RA2_OCEAN_DATA_FOR_LEVEL_2

binary record "[RA2_OCEAN_DATA_FOR_LEVEL_2](#)"

size: 356

Ra2 - MDS

id	field name	definition									
0	dsr_time	<p>binary time size: 12</p> <p>MDSR Time stamp. Time fields based on UTC are computed for each record and referred to the center of the averaged waveform</p> <p>unit: "s since 2000-01-01"</p> <p>binary record size: 12</p> <p>ENVISAT binary datetime</p> <table border="1" style="width: 100%; margin-top: 10px;"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>days</td> <td> <p>binary int32 size: 4</p> <p>days since January 1st, 2000 (may be negative)</p> <p>unit: "days since 2000-01-01"</p> </td> </tr> <tr> <td>1</td> <td>seconds</td> <td> <p>binary uint32 size: 4</p> </td> </tr> </tbody> </table>	id	field name	definition	0	days	<p>binary int32 size: 4</p> <p>days since January 1st, 2000 (may be negative)</p> <p>unit: "days since 2000-01-01"</p>	1	seconds	<p>binary uint32 size: 4</p>
id	field name	definition									
0	days	<p>binary int32 size: 4</p> <p>days since January 1st, 2000 (may be negative)</p> <p>unit: "days since 2000-01-01"</p>									
1	seconds	<p>binary uint32 size: 4</p>									



		<table border="1"> <tr> <td></td> <td></td> <td>seconds since start of day unit: "s"</td> </tr> <tr> <td>2</td> <td>microseconds</td> <td>binary uint32 <i>size: 4</i> microseconds since start of second unit: "1e-6 s"</td> </tr> </table>			seconds since start of day unit: "s"	2	microseconds	binary uint32 <i>size: 4</i> microseconds since start of second unit: "1e-6 s"
		seconds since start of day unit: "s"						
2	microseconds	binary uint32 <i>size: 4</i> microseconds since start of second unit: "1e-6 s"						
1	quality_flag	binary int8 <i>size: 1</i> Quality Indicator (-1 for blank MDSR, 0 otherwise)						
2	spare_1	binary bytes <i>size: 3</i> Spare hidden: true						
3	lat	binary int32 (double) <i>size: 4</i> Geodetic Latitude (positive N, negative S) unit: "1e-6 degrees_north" converted unit: "degrees_north" (multiply by 1/1e+006)						
4	lon	binary int32 (double) <i>size: 4</i> Longitude (positive E, 0 at Greenwich, negative W) unit: "1e-6 degrees_east" converted unit: "degrees_east" (multiply by 1/1e+006)						
5	src_pack_cnt	binary uint32 <i>size: 4</i> Source Packet Counter						
6	instr_mode_id_flags	binary uint32 <i>size: 4</i> Instrument Mode ID						
7	meas_conf_data_flags	binary uint32 <i>size: 4</i> Measurement Confidence Data						
8	alt_cog_ellip	binary uint32 <i>size: 4</i> Altitude of CoG above reference ellipsoid unit: "mm"						
9	instant_alt_rate	binary int16 <i>size: 2</i>						



		Instantaneous altitude rate unit: "mm"
10	spare_2	binary bytes <i>size: 6</i> Spare hidden: true
11	ku_band_ocean_range	binary uint32 <i>size: 4</i> Ku-band ocean range unit: "mm"
12	s_band_ocean_range	binary uint32 <i>size: 4</i> S-band ocean range unit: "mm"
13	sd_18hz_ku_ocean	binary uint16 <i>size: 2</i> Standard deviation of 18 Hz Ku-band ocean range unit: "mm"
14	sd_18hz_s_ocean	binary uint16 <i>size: 2</i> Standard deviation of 18 Hz S-band ocean range unit: "mm"
15	num_18hz_ku_ocean	binary uint16 <i>size: 2</i> Number of 18 Hz valid points for Ku-band ocean range
16	num_18hz_s_ocean	binary uint16 <i>size: 2</i> Number of 18 Hz valid points for S-band ocean range
17	spare_3	binary bytes <i>size: 8</i> Spare hidden: true
18	mod_dry_tropo_corr	binary int16 <i>size: 2</i> Model dry tropospheric correction unit: "mm"
19	inv_barom_corr	binary int16 <i>size: 2</i> Inverted barometer correction



		unit: "mm"
20	mod_wet_tropo_corr	binary int16 <i>size: 2</i> Model wet tropospheric correction unit: "mm"
21	mwr_wet_tropo_corr	binary int16 <i>size: 2</i> MWR derived wet tropospheric correction unit: "mm"
22	ra2_ion_corr_ku	binary int16 <i>size: 2</i> RA2 ionospheric correction on Ku-band unit: "mm"
23	ra2_ion_corr_s	binary int16 <i>size: 2</i> RA2 ionospheric correction on S-band unit: "mm"
24	ion_corr_doris_ku	binary int16 <i>size: 2</i> Ionospheric correction from DORIS on Ku-band unit: "mm"
25	ion_corr_doris_s	binary int16 <i>size: 2</i> Ionospheric correction from DORIS on S-band unit: "mm"
26	ion_corr_mod_ku	binary int16 <i>size: 2</i> Ionospheric correction from model on Ku-band unit: "mm"
27	ion_corr_mod_s	binary int16 <i>size: 2</i> Ionospheric correction from model on S-band unit: "mm"
28	sea_bias_ku	binary int16 <i>size: 2</i> Sea state bias on Ku-band unit: "mm"



29	sea_bias_s	binary int16 <i>size: 2</i> Sea state bias on S-band unit: "mm"
30	spare_4	binary bytes <i>size: 12</i> Spare hidden: true
31	square_ku_sig_wv_ht	binary int32 <i>size: 4</i> Square of Ku-band Significant wave height unit: "mm2"
32	square_s_sig_wv_ht	binary int32 <i>size: 4</i> Square of S-band Significant wave height unit: "mm2"
33	ku_sig_wv_ht	binary int16 <i>size: 2</i> Ku-band Significant wave height unit: "mm"
34	s_sig_wv_ht	binary int16 <i>size: 2</i> S-band Significant wave height unit: "mm"
35	sd_18hz_ku_swh	binary int16 <i>size: 2</i> Standard deviation of 18 Hz Ku-band SWH unit: "mm"
36	sd_18hz_s_swh	binary int16 <i>size: 2</i> Standard deviation of 18 Hz S-band SWH unit: "mm"
37	num_18hz_ku_ocean_swh	binary uint16 <i>size: 2</i> Number of 18 Hz valid points for Ku-band ocean SWH
38	num_18hz_s_ocean_swh	binary uint16 <i>size: 2</i> Number of 18 Hz valid points for S-band ocean SWH
39	ku_ocean_bscat_coeff	binary int16 (double) <i>size: 2</i>



		Ku-band corrected Ocean backscatter coefficient unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
40	s_ocean_bscat_coeff	binary int16 (double) <i>size: 2</i> S-band corrected Ocean backscatter coefficient unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
41	sd_18hz_ku_ocean_bscat	binary int16 (double) <i>size: 2</i> Standard deviation of 18 Hz Ku-band ocean backscatter coefficient unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
42	sd_18hz_s_ocean_bscat	binary int16 (double) <i>size: 2</i> Standard deviation of 18 Hz S-band ocean backscatter coefficient unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
43	num_18hz_ku_ocean_bscat	binary uint16 <i>size: 2</i> Number of 18 Hz valid points for Ku-band ocean backscatter coefficient
44	num_18hz_s_ocean_bscat	binary uint16 <i>size: 2</i> Number of 18 Hz valid points for S-band ocean backscatter coefficient
45	spare_5	binary bytes <i>size: 40</i> Spare hidden: true
46	ku_net_instr_corr_agc	binary int16 (double) <i>size: 2</i> Ku-band net instrument correction for AGC unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)



47	s_net_instr_corr_agc	binary int16 (double) <i>size: 2</i> S-band net instrument correction for AGC unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
48	ku_atm_atten_corr	binary int16 (double) <i>size: 2</i> Ku-band atmospheric attenuation correction unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
49	s_atm_atten_corr	binary int16 (double) <i>size: 2</i> S-band atmospheric attenuation correction unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
50	ku_rain_atten	binary int32 (double) <i>size: 4</i> Ku-band rain attenuation unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
51	off_nad_ang_platf	binary int16 (double) <i>size: 2</i> Square of the satellite off-nadir angle from platform data unit: "1e-4 degrees2" converted unit: "degrees2" (multiply by 1/10000)
52	off_nad_ang_wvform	binary int16 (double) <i>size: 2</i> Square of the satellite off-nadir angle from waveform data unit: "1e-4 degrees2" converted unit: "degrees2" (multiply by 1/10000)
53	m_sea_surf_ht	binary int32 <i>size: 4</i> Mean sea-surface height unit: "mm"
54	geoid_ht	binary int32 <i>size: 4</i> Geoid height



		unit: "mm"
55	ocean_depland_elev	binary int32 <i>size: 4</i> Ocean depth/land elevation unit: "mm"
56	tot_geocen_ocn_tide_ht_sol1	binary int16 <i>size: 2</i> Total geocentric ocean tide height (solution 1) unit: "mm"
57	tot_geocen_ocn_tide_ht_sol2	binary int16 <i>size: 2</i> Total geocentric ocean tide height (solution 2) unit: "mm"
58	long_period_ocn_tide_ht	binary int16 <i>size: 2</i> Long period Tide height unit: "mm"
59	tidal_load_ht_sol2	binary int16 <i>size: 2</i> Tidal loading height (solution 2) unit: "mm"
60	solid_earth_tide_ht	binary int16 <i>size: 2</i> Solid earth tide height unit: "mm"
61	geocen_pole_tide_ht	binary int16 <i>size: 2</i> Geocentric pole tide height unit: "mm"
62	mod_surf_atm_pres	binary int16 (double) <i>size: 2</i> Model surface atmospheric pressure unit: "10 Pa" converted unit: "Pa" (multiply by 10/1)
63	mwr_wvapour_cont	binary int16 (double) <i>size: 2</i> MWR water vapour content unit: "1e-2 g/cm2"



		converted unit: "g/cm2" (multiply by 1/100)
64	mwr_liq_water_cont	<p>binary int16 (double) <i>size: 2</i></p> <p>MWR liquid water content</p> <p>unit: "1e-2 g/cm2"</p> <p>converted unit: "g/cm2" (multiply by 1/100)</p>
65	ra2_elec_cont	<p>binary int16 (double) <i>size: 2</i></p> <p>RA2 Total electron content (1 TECU = 1e16 electrons / m²)</p> <p>unit: "1e15/m2"</p> <p>converted unit: "1e16/m2" (multiply by 1/10)</p>
66	ra2_wind_sp	<p>binary int16 <i>size: 2</i></p> <p>RA2 wind speed</p> <p>unit: "mm/s"</p>
67	mod_wind_sp_u	<p>binary int16 <i>size: 2</i></p> <p>u component of the model wind vector</p> <p>unit: "mm/s"</p>
68	mod_wind_sp_v	<p>binary int16 <i>size: 2</i></p> <p>v component of the model wind vector</p> <p>unit: "mm/s"</p>
69	tidal_load_ht_sol1	<p>binary int16 <i>size: 2</i></p> <p>Tidal loading height (solution 1)</p> <p>unit: "mm"</p>
70	spare_6	<p>binary bytes <i>size: 8</i></p> <p>Spare</p> <p>hidden: true</p>
71	interpole_238_temp_mwr	<p>binary int16 (double) <i>size: 2</i></p> <p>Interpolated 23.8 GHz brightness temperature from MWR</p> <p>unit: "1e-2 K"</p> <p>converted unit: "K" (multiply by 1/100)</p>



72	interpole_365_temp_mwr	<p>binary int16 (double) <i>size: 2</i></p> <p>Interpolated 36.5 GHz brightness temperature from MWR</p> <p>unit: "1e-2" K"</p> <p>converted unit: "K" (multiply by 1/100)</p>
73	interpole_sd_238_temp_mwr	<p>binary int16 (double) <i>size: 2</i></p> <p>Interpolated standard deviation of MWR 23.8 GHz brightness temperature</p> <p>unit: "1e-2" K"</p> <p>converted unit: "K" (multiply by 1/100)</p>
74	interpole_sd_365_temp_mwr	<p>binary int16 (double) <i>size: 2</i></p> <p>Interpolated standard deviation of MWR 36.5 GHz brightness temperature</p> <p>unit: "1e-2" K"</p> <p>converted unit: "K" (multiply by 1/100)</p>
75	spare_7	<p>binary bytes <i>size: 2</i></p> <p>Spare</p> <p>hidden: true</p>
76	ave_ku_chirp	<p>binary uint16 <i>size: 2</i></p> <p>Average Ku chirp band. Ku chirp band value is associated with the minimum of the 20 elementary chirp band indexes in the source packet. Possible values: 0 = there is at least one record at 320 MHz, 1 = there is at least one record at 80 MHz (and the others are at 20 MHz), 2 = all input records are at 20 MHz</p>
77	unused_bits_1	<p>binary bytes <i>size: 3</i></p> <p>Unused ku_chirp_id_flags bits</p> <p>hidden: true</p>
78	ku_chirp_id_flags	<p>binary array[20] <i>size: 5</i></p> <p>Ku chirp band identifiers. Elements are in reverse order: the last array element refers to the first data block</p> <p>binary uint8 <i>size: 0:2</i></p> <p>Possible values: 0 = 320 MHz (Ku), 1 = 80 MHz (Ku), 2 = 20 MHz (Ku). Default values (bits set to 1) are output in the event of non tracking records (records not in Tracking, Preset Tracking or Preset Loop Output), wherever the sum of all Ku</p>



		and S waveforms samples are set to 0, or if Ku AGC or Ku onboard Rx delay are out of bounds																					
79	unused_bits_2	<p>binary bytes <i>size: 1:4</i></p> <p>Unused error_flag_chirp_id_flags bits</p> <p>hidden: true</p>																					
80	error_flag_chirp_id_flags	<p>binary array[20] <i>size: 2:4</i></p> <p>Error flag for chirp band id. Elements are in reverse order: the last array element refers to the first data block</p> <p>binary uint8 <i>size: 0:1</i></p> <p>0 = valid measurement, 1 = invalid</p>																					
81	instr_flags	<p>binary record <i>size: 4</i></p> <p>Instrument flag</p> <table border="1"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>spare</td> <td> <p>binary bytes <i>size: 3</i></p> <p>spare</p> <p>hidden: true</p> </td> </tr> <tr> <td>1</td> <td>s_band_anomaly</td> <td> <p>binary uint32 <i>size: 0:1</i></p> <p>Flag for S-band anomaly</p> </td> </tr> <tr> <td>2</td> <td>flight_cal_corr_s</td> <td> <p>binary uint32 <i>size: 0:1</i></p> <p>Flag for availability of S flight calibration correction</p> </td> </tr> <tr> <td>3</td> <td>flight_cal_corr_ku</td> <td> <p>binary uint32 <i>size: 0:1</i></p> <p>Flag for availability of Ku flight calibration correction</p> </td> </tr> <tr> <td>4</td> <td>ptr_cal_band</td> <td> <p>binary uint32 <i>size: 0:3</i></p> <p>PTR calibration band identifier field</p> </td> </tr> <tr> <td>5</td> <td>decoded_redundancy_error</td> <td> <p>binary uint32 <i>size: 0:2</i></p> <p>Error flag for decoded redundancy flags</p> </td> </tr> </tbody> </table>	id	field name	definition	0	spare	<p>binary bytes <i>size: 3</i></p> <p>spare</p> <p>hidden: true</p>	1	s_band_anomaly	<p>binary uint32 <i>size: 0:1</i></p> <p>Flag for S-band anomaly</p>	2	flight_cal_corr_s	<p>binary uint32 <i>size: 0:1</i></p> <p>Flag for availability of S flight calibration correction</p>	3	flight_cal_corr_ku	<p>binary uint32 <i>size: 0:1</i></p> <p>Flag for availability of Ku flight calibration correction</p>	4	ptr_cal_band	<p>binary uint32 <i>size: 0:3</i></p> <p>PTR calibration band identifier field</p>	5	decoded_redundancy_error	<p>binary uint32 <i>size: 0:2</i></p> <p>Error flag for decoded redundancy flags</p>
id	field name	definition																					
0	spare	<p>binary bytes <i>size: 3</i></p> <p>spare</p> <p>hidden: true</p>																					
1	s_band_anomaly	<p>binary uint32 <i>size: 0:1</i></p> <p>Flag for S-band anomaly</p>																					
2	flight_cal_corr_s	<p>binary uint32 <i>size: 0:1</i></p> <p>Flag for availability of S flight calibration correction</p>																					
3	flight_cal_corr_ku	<p>binary uint32 <i>size: 0:1</i></p> <p>Flag for availability of Ku flight calibration correction</p>																					
4	ptr_cal_band	<p>binary uint32 <i>size: 0:3</i></p> <p>PTR calibration band identifier field</p>																					
5	decoded_redundancy_error	<p>binary uint32 <i>size: 0:2</i></p> <p>Error flag for decoded redundancy flags</p>																					
82	unused_bits_3	<p>binary bytes <i>size: 3</i></p>																					



		Unused fault_id_flags bits hidden: true
83	fault_id_flags	binary array[20] <i>size: 5</i> Fault indentifiers. Elements are in reverse order: the last array element refers to the first data block binary uint8 <i>size: 0:2</i> 0 = valid measurement, 1 = invalid. Unused bits are set to 1
84	spare_8	binary bytes <i>size: 8</i> Spare hidden: true
85	unused_bits_4	binary bytes <i>size: 3</i> Unused wvfrom_fault_id_flags bits hidden: true
86	wvfrom_fault_id_flags	binary array[20] <i>size: 5</i> Waveforms samples fault indentifiers. Elements are in reverse order: the last array element refers to the first data block binary uint8 <i>size: 0:2</i>
87	unused_bits_5	binary bytes <i>size: 2</i> Unused instr_id_data_level_flags bits hidden: true
88	instr_id_data_level_flags	binary array[20] <i>size: 10</i> Instrument mode ID at data block level. Elements are in reverse order: the last array element refers to the first data block binary uint8 <i>size: 0:4</i> 0 = spare, 1 = acquisition, 2 = Tracking, 3 = IF Cal, 4 = BITE RF, 5 = BITE DGT, 6 = Preset Tracking, 7 = Preset Loop Output, 8 = Alignment failed. Default values (bits set to 1) are output in the event of non tracking records (records not in Tracking, Preset Tracking or Preset Loop Output), wherever the sum of all Ku and S waveform samples are set to 0, or if Ku AGC or Ku onboard Rx delay are out of bounds
89	num_meas_ku_calibr	binary uint16 <i>size: 2</i>



		No. of measures for Ku flight calibration factor evaluation																					
90	num_meas_s_calibr	binary uint16 <i>size: 2</i> No. of measures for S flight calibration factor evaluation																					
91	mwr_instr_flags	binary record <i>size: 2</i> MWR instrument flag <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 5%;">id</th> <th style="width: 20%;">field name</th> <th style="width: 75%;">definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>tmp_flg</td> <td>binary uint8 <i>size: 0:1</i> Indicates uniformity of CEU temperature: 0 = temperature consistency, 1 = temperature inconsistency</td> </tr> <tr> <td>1</td> <td>obdh_flg</td> <td>binary uint8 <i>size: 0:1</i> flag to indicate data is missing: 0 = no error, 1 = error</td> </tr> <tr> <td>2</td> <td>red_flg</td> <td>binary uint8 <i>size: 0:1</i> Redundancy indicator ICU channel: 0 = normal channel, 1 = redundant channel</td> </tr> <tr> <td>3</td> <td>pbp_flg</td> <td>binary uint8 <i>size: 0:1</i> Power Bus Protection indicator: 0 = no protection, 1 = protection</td> </tr> <tr> <td>4</td> <td>oop_flg</td> <td>binary uint8 <i>size: 0:1</i> Overvoltage/Overload protection indicator: 0 = no protection, 1 = protection</td> </tr> <tr> <td>5</td> <td>spare</td> <td>binary bytes <i>size: 1:3</i> spare hidden: true</td> </tr> </tbody> </table>	id	field name	definition	0	tmp_flg	binary uint8 <i>size: 0:1</i> Indicates uniformity of CEU temperature: 0 = temperature consistency, 1 = temperature inconsistency	1	obdh_flg	binary uint8 <i>size: 0:1</i> flag to indicate data is missing: 0 = no error, 1 = error	2	red_flg	binary uint8 <i>size: 0:1</i> Redundancy indicator ICU channel: 0 = normal channel, 1 = redundant channel	3	pbp_flg	binary uint8 <i>size: 0:1</i> Power Bus Protection indicator: 0 = no protection, 1 = protection	4	oop_flg	binary uint8 <i>size: 0:1</i> Overvoltage/Overload protection indicator: 0 = no protection, 1 = protection	5	spare	binary bytes <i>size: 1:3</i> spare hidden: true
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5	spare	binary bytes <i>size: 1:3</i> spare hidden: true																					
92	spare_9	binary bytes <i>size: 6</i> Spare hidden: true																					
93	ku_peak	binary uint16 (double) <i>size: 2</i> 1 Hz Ku-band peakiness unit: "1e-3"																					



		converted unit: "" (multiply by 1/1000)
94	s_peak	<p>binary uint16 (double) <i>size: 2</i></p> <p>1 Hz S-band peakiness</p> <p>unit: "1e-3"</p> <p>converted unit: "" (multiply by 1/1000)</p>
95	spare_11	<p>binary bytes <i>size: 12</i></p> <p>Spare</p> <p>hidden: true</p>
96	unused_bits_6	<p>binary bytes <i>size: 1:4</i></p> <p>Unused ku_ocean_retrk_qua_flags bits</p> <p>hidden: true</p>
97	ku_ocean_retrk_qua_flags	<p>binary array[20] <i>size: 2:4</i></p> <p>Ku-band ocean retracking quality. Elements are in reverse order: the last array element refers to the first data block</p> <p>binary uint8 <i>size: 0:1</i></p> <p>0 = valid, 1 = invalid</p>
98	unused_bits_7	<p>binary bytes <i>size: 1:4</i></p> <p>Unused s_ocean_retrk_qua_flags bits</p> <p>hidden: true</p>
99	s_ocean_retrk_qua_flags	<p>binary array[20] <i>size: 2:4</i></p> <p>S-band ocean retracking quality. Elements are in reverse order: the last array element refers to the first data block</p> <p>binary uint8 <i>size: 0:1</i></p> <p>0 = valid, 1 = invalid</p>
100	altim_landocean_flag	<p>binary uint16 <i>size: 2</i></p> <p>Altimeter surface type flag. The flag is based on a land/sea mask file and has the following four meanings: 0 = oceans or semi-enclosed seas, 1 = enclosed seas or lakes, 2 = continental ice, 3 = land</p>
101	radio_landocean_flag	<p>binary uint16 <i>size: 2</i></p> <p>Radiometer land/ocean type flag. This flag has two states: 0 = Ocean, 1 = Land. In NRT, when MWR data are not available,</p>



		<p>this flag is set to its maximum value. In OFL, when MWR data are not available, this flag is set to its default value which is 1 (land)</p>																		
102	mwr_qua_interp_flag	<p>binary uint16 <i>size: 2</i></p> <p>MWR Quality interpolation flag. 0 = interpolation was OK with no gap between the two MWR measurements around the RA-2 time, 1 = interpolation was OK but there was a gap between the two selected MWR measurements, 2 = extrapolation was used, 3 = neither interpolation nor extrapolation could be used. The default value (3 in NRT, and 0 in OFL) is output when no MWR data is available</p>																		
103	rain_flag	<p>binary uint16 <i>size: 2</i></p> <p>Altimeter rain flag. 1 = rain (the expected Ku/S-band rain-free relationship minus the uncorrected Ku ocean backscattering coefficient, and if the MWR liquid water content, interpolated to RA-2 time, are bigger than certain thresholds), 0 = no rain (otherwise)</p>																		
104	interpole_flag	<p>binary record <i>size: 2</i></p> <p>interpolation flag</p> <table border="1"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>spare</td> <td> <p>binary bytes <i>size: 1:4</i></p> <p>spare</p> <p>hidden: true</p> </td> </tr> <tr> <td>1</td> <td>meteo_interp</td> <td> <p>binary uint8 <i>size: 0:1</i></p> <p>meteorological data interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)</p> </td> </tr> <tr> <td>2</td> <td>ocean_tide_sol2</td> <td> <p>binary uint8 <i>size: 0:1</i></p> <p>ocean tide solution 2 interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)</p> </td> </tr> <tr> <td>3</td> <td>ocean_tide_sol1</td> <td> <p>binary uint8 <i>size: 0:1</i></p> <p>ocean tide solution 1 interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)</p> </td> </tr> <tr> <td>4</td> <td>mss</td> <td> <p>binary uint8 <i>size: 0:1</i></p> <p>MSS interpolation flag (0 = good, 1 = bad)</p> </td> </tr> </tbody> </table>	id	field name	definition	0	spare	<p>binary bytes <i>size: 1:4</i></p> <p>spare</p> <p>hidden: true</p>	1	meteo_interp	<p>binary uint8 <i>size: 0:1</i></p> <p>meteorological data interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)</p>	2	ocean_tide_sol2	<p>binary uint8 <i>size: 0:1</i></p> <p>ocean tide solution 2 interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)</p>	3	ocean_tide_sol1	<p>binary uint8 <i>size: 0:1</i></p> <p>ocean tide solution 1 interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)</p>	4	mss	<p>binary uint8 <i>size: 0:1</i></p> <p>MSS interpolation flag (0 = good, 1 = bad)</p>
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0	spare	<p>binary bytes <i>size: 1:4</i></p> <p>spare</p> <p>hidden: true</p>																		
1	meteo_interp	<p>binary uint8 <i>size: 0:1</i></p> <p>meteorological data interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)</p>																		
2	ocean_tide_sol2	<p>binary uint8 <i>size: 0:1</i></p> <p>ocean tide solution 2 interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)</p>																		
3	ocean_tide_sol1	<p>binary uint8 <i>size: 0:1</i></p> <p>ocean tide solution 1 interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)</p>																		
4	mss	<p>binary uint8 <i>size: 0:1</i></p> <p>MSS interpolation flag (0 = good, 1 = bad)</p>																		



105	spare_12	binary bytes <i>size: 2</i> Spare hidden: true
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3.5. Jason-1

3.5.1. Filenaming convention

The product names are based on the following convention:

- JA1_GDR_2P<v><ccc>_<ppp>.CNES

With:

- <v> : product version (set to 'c', the current Jason-1 data standards)
- <ccc>: cycle number of 1st product record
- <ppp> : pass number of 1st product record (1-254)

3.5.2. Product data format

3.5.2.1. GDR_HEADER

ascii record "[GDR_HEADER](#)"

size: 3520

id	field name	definition
0	edu_label	ascii string <i>size: 20</i> CCSDS EDU Label fixed value: "CCSD3ZF0000100000001" hidden: true
1	volume_label	ascii string <i>size: 20</i> CCSDS Volume Label fixed value: "CCSD3VS00006PRODUCER" hidden: true
2	newline_char_1	ascii char <i>size: 1</i> newline fixed value: "\n"



		hidden: true
3	product_file_name_label	<p>ascii string <i>size: 20</i></p> <p>Product_File_Name =</p> <p>fixed value: "Product_File_Name = "</p> <p>hidden: true</p>
4	product_file_name	<p>ascii string <i>size: 40</i></p> <p>Name of the product (i.e. JA1_xxx_2PaPccc_ppp.CNES or JA1_xxx_2PaPccc_ppp.NASA)</p>
5	semicolon_mark_1	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
6	newline_char_2	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
7	agency_name_label	<p>ascii string <i>size: 23</i></p> <p>Producer_Agency_Name =</p> <p>fixed value: "Producer_Agency_Name = "</p> <p>hidden: true</p>
8	agency_name	<p>ascii string <i>size: 4</i></p> <p>Agency Name (CNES or NASA)</p>
9	semicolon_mark_2	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
10	newline_char_3	<p>ascii char <i>size: 1</i></p> <p>newline</p>



		fixed value: "\n" hidden: true
11	center_label	ascii string size: 20 Processing_Center = fixed value: "Processing_Center = " hidden: true
12	center	ascii string size: 6 Center (SSALTO or JSDS)
13	semicolon_mark_3	ascii char size: 1 semicolon fixed value: ";" hidden: true
14	newline_char_4	ascii char size: 1 newline fixed value: "\n" hidden: true
15	data_type_label	ascii string size: 17 File_Data_Type = fixed value: "File_Data_Type = " hidden: true
16	data_type	ascii string size: 4 Type of data (IGDR or GDR or SGDR)
17	semicolon_mark_4	ascii char size: 1 semicolon fixed value: ";" hidden: true
18	newline_char_5	ascii char size: 1



		newline fixed value: "\n" hidden: true
19	document_label	ascii string <i>size: 21</i> Reference_Document = fixed value: "Reference_Document = " hidden: true
20	document	ascii string <i>size: 50</i> ID of the document describing the product (i.e. SMM-ST-M-EA-10879-CN)
21	semicolon_mark_5	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
22	newline_char_6	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
23	software_label	ascii string <i>size: 21</i> Reference_Software = fixed value: "Reference_Software = " hidden: true
24	software	ascii string <i>size: 20</i> ID of the software used to create the product (i.e. CMA CNES Vx.x)



25	semicolon_mark_6	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
26	newline_char_7	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
27	operating_system_label	ascii string <i>size: 19</i> Operating_System = fixed value: "Operating_System = " hidden: true
28	operating_system	ascii string <i>size: 20</i> ID of the operating system (i.e. SUN/Solaris 7)
29	semicolon_mark_7	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
30	newline_char_8	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
31	creation_time_label	ascii string <i>size: 24</i> Product_Creation_Time = fixed value: "Product_Creation_Time = " hidden: true
32	creation_time	ascii time <i>size: 26</i> UTC date & time of product generation (CCSDS



		<p>format) i.e. 2000-06-21T04:20:00.000000. BEAT time value is given in seconds since 01-JAN-2000</p> <p>unit: "s since 2000-01-01"</p> <p>mapping: "0000-00-00T00:00:00.000000" - > 1.#QNANO</p> <p>ascii string <i>size: 26</i></p> <p>CCSDS ASCII datetime "YYYY-MM- DDThh:mm:ss.uuuuuu".</p>
33	semicolon_mark_8	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
34	newline_char_9	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
35	ccsds_marker_1	<p>ascii string <i>size: 20</i></p> <p>CCSDS marker</p> <p>fixed value: "CCSD\$MARKERPRODUCER"</p> <p>hidden: true</p>
36	catalog_label	<p>ascii string <i>size: 20</i></p> <p>CCSDS Catalog label</p> <p>fixed value: "CCSD3KS00006PASSFILE"</p> <p>hidden: true</p>
37	newline_char_10	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
38	mission_label	<p>ascii string <i>size: 15</i></p>



		Mission_Name = fixed value: "Mission_Name = " hidden: true
39	mission	ascii string <i>size: 7</i> Name of the mission (Jason-1) fixed value: "Jason-1"
40	semicolon_mark_9	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
41	newline_char_11	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
42	altimeter_sensor_label	ascii string <i>size: 24</i> Altimeter_Sensor_Name = fixed value: "Altimeter_Sensor_Name = " hidden: true
43	altimeter_sensor	ascii string <i>size: 10</i> Name of the altimeter sensor (POSEIDON-2) fixed value: "POSEIDON-2"
44	semicolon_mark_10	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
45	newline_char_12	ascii char <i>size: 1</i> newline



		fixed value: "\n" hidden: true
46	radiometer_sensor_label	ascii string <i>size: 25</i> Radiometer_Sensor_Name = fixed value: "Radiometer_Sensor_Name = " hidden: true
47	radiometer_sensor	ascii string <i>size: 3</i> Name of the radiometer sensor (JMR) fixed value: "JMR"
48	semicolon_mark_11	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
49	newline_char_13	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
50	doris_sensor_label	ascii string <i>size: 20</i> DORIS_Sensor_Name = fixed value: "DORIS_Sensor_Name = " hidden: true
51	doris_sensor	ascii string <i>size: 10</i> Name of the DORIS sensor (DORIS-2 GM) fixed value: "DORIS-2 GM"



52	semicolon_mark_12	ascii char <i>size</i> : 1 semicolon fixed value: ";" hidden: true
53	newline_char_14	ascii char <i>size</i> : 1 newline fixed value: "\n" hidden: true
54	acquisition_station_label	ascii string <i>size</i> : 27 Acquisition_Station_Name = fixed value: "Acquisition_Station_Name = " hidden: true
55	acquisition_station	ascii string <i>size</i> : 20 Name of the station where the raw data have been acquired (directly derived from Level1.0 product)
56	semicolon_mark_13	ascii char <i>size</i> : 1 semicolon fixed value: ";" hidden: true
57	newline_char_15	ascii char <i>size</i> : 1 newline fixed value: "\n" hidden: true
58	cycle_label	ascii string <i>size</i> : 15 Cycle_Number = fixed value: "Cycle_Number = " hidden: true
59	cycle	ascii uint32 <i>size</i> : 5



		Cycle
60	semicolon_mark_14	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
61	newline_char_16	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
62	start_abs_orbit_label	<p>ascii string <i>size: 29</i></p> <p>Absolute_Revolution_Number =</p> <p>fixed value: "Absolute_Revolution_Number = "</p> <p>hidden: true</p>
63	start_abs_orbit	<p>ascii uint32 <i>size: 5</i></p> <p>Start absolute orbit number</p>
64	semicolon_mark_15	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
65	newline_char_17	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
66	pass_number_label	<p>ascii string <i>size: 14</i></p> <p>Pass_Number =</p> <p>fixed value: "Pass_Number = "</p> <p>hidden: true</p>



67	pass_number	ascii uint32 <i>size: 3</i> Pass number within the cycle
68	semicolon_mark_16	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
69	newline_char_18	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
70	absolute_pass_number_label	ascii string <i>size: 23</i> Absolute_Pass_Number = fixed value: "Absolute_Pass_Number = " hidden: true
71	absolute_pass_number	ascii uint32 <i>size: 5</i> Start absolute pass number
72	semicolon_mark_17	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
73	newline_char_19	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true



74	equator_time_label	<p>ascii string <i>size: 15</i></p> <p>Equator_Time =</p> <p>fixed value: "Equator_Time = "</p> <p>hidden: true</p>
75	equator_time	<p>ascii time <i>size: 26</i></p> <p>UTC date & time of equator crossing (CCSDS format) for the half revolution containing the first point of the file. BEAT time value is given in seconds since 01-JAN-2000</p> <p>unit: "s since 2000-01-01"</p> <p>mapping: "0000-00-00T00:00:00.000000" -> 1.#QNANO</p> <p>ascii string <i>size: 26</i></p> <p>CCSDS ASCII datetime "YYYY-MM-DDThh:mm:ss.uuuuu".</p>
76	semicolon_mark_18	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
77	newline_char_20	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
78	equator_longitude_label	<p>ascii string <i>size: 20</i></p> <p>Equator_Longitude =</p> <p>fixed value: "Equator_Longitude = "</p> <p>hidden: true</p>
79	equator_longitude	<p>ascii float <i>size: 7</i></p> <p>Longitude in degrees of equator crossing (format +xxx.xx)</p> <p>unit: "degrees_east"</p>



80	equator_longitude_units	<p>ascii string <i>size: 5</i></p> <p><deg></p> <p>fixed value: "<deg>"</p> <p>hidden: true</p>
81	semicolon_mark_19	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
82	newline_char_21	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
83	first_measurement_time_label	<p>ascii string <i>size: 25</i></p> <p>First_Measurement_Time =</p> <p>fixed value: "First_Measurement_Time = "</p> <p>hidden: true</p>
84	first_measurement_time	<p>ascii time <i>size: 26</i></p> <p>UTC date & time of first measurement in the product (CCSDS format). BEAT time value is given in seconds since 01-JAN-2000</p> <p>unit: "s since 2000-01-01"</p> <p>mapping: "0000-00-00T00:00:00.000000" -> 1.#QNANO</p> <p>ascii string <i>size: 26</i></p> <p>CCSDS ASCII datetime "YYYY-MM-DDThh:mm:ss.uuuuuu".</p>
85	semicolon_mark_20	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>



86	newline_char_22	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
87	last_measurement_time_label	<p>ascii string <i>size: 24</i></p> <p>Last_Measurement_Time =</p> <p>fixed value: "Last_Measurement_Time = "</p> <p>hidden: true</p>
88	last_measurement_time	<p>ascii time <i>size: 26</i></p> <p>UTC date & time of last measurement in the product (CCSDS format). BEAT time value is given in seconds since 01-JAN-2000</p> <p>unit: "s" since 2000-01-01"</p> <p>mapping: "0000-00-00T00:00:00.000000" -> 1.#QNANO</p> <p>ascii string <i>size: 26</i></p> <p>CCSDS ASCII datetime "YYYY-MM-DDThh:mm:ss.ffffff".</p>
89	semicolon_mark_21	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
90	newline_char_23	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
91	first_measurement_latitude_label	<p>ascii string <i>size: 29</i></p> <p>First_Measurement_Latitude =</p> <p>fixed value: "First_Measurement_Latitude = "</p> <p>hidden: true</p>



92	first_measurement_latitude	ascii float <i>size: 6</i> Latitude in degrees of first measurement in the product (format sxx.xx) unit: "degrees_north"
93	first_measurement_latitude_units	ascii string <i>size: 5</i> <deg> fixed value: "<deg>" hidden: true
94	semicolon_mark_22	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
95	newline_char_24	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
96	last_measurement_latitude_label	ascii string <i>size: 28</i> Last_Measurement_Latitude = fixed value: "Last_Measurement_Latitude = " hidden: true
97	last_measurement_latitude	ascii float <i>size: 6</i> Latitude in degrees of last measurement in the product (format sxx.xx) unit: "degrees_north"
98	last_measurement_latitude_units	ascii string <i>size: 5</i> <deg> fixed value: "<deg>" hidden: true



99	semicolon_mark_23	<p>ascii char <i>size</i>: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
100	newline_char_25	<p>ascii char <i>size</i>: 1</p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
101	first_measurement_longitude_label	<p>ascii string <i>size</i>: 30</p> <p>First_Measurement_Longitude =</p> <p>fixed value: "First_Measurement_Longitude = "</p> <p>hidden: true</p>
102	first_measurement_longitude	<p>ascii float <i>size</i>: 7</p> <p>Longitude in degrees of first measurement in the product (format +xxx.xx)</p> <p>unit: "degrees_east"</p>
103	first_measurement_longitude_units	<p>ascii string <i>size</i>: 5</p> <p><deg></p> <p>fixed value: "<deg>"</p> <p>hidden: true</p>
104	semicolon_mark_24	<p>ascii char <i>size</i>: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
105	newline_char_26	<p>ascii char <i>size</i>: 1</p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>



106	last_measurement_longitude_label	ascii string <i>size: 29</i> Last_Measurement_Longitude = fixed value: "Last_Measurement_Longitude = " hidden: true
107	last_measurement_longitude	ascii float <i>size: 7</i> Longitude in degrees of last measurement in the product (format +xxx.xx) unit: "degrees_east"
108	last_measurement_longitude_units	ascii string <i>size: 5</i> <deg> fixed value: "<deg>" hidden: true
109	semicolon_mark_25	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
110	newline_char_27	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
111	pass_data_count_label	ascii string <i>size: 18</i> Pass_Data_Count = fixed value: "Pass_Data_Count = " hidden: true
112	pass_data_count	ascii int16 <i>size: 5</i> Number of 1 Hz measurements in the product
113	semicolon_mark_26	ascii char <i>size: 1</i> semicolon



		fixed value: ";" hidden: true
114	newline_char_28	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
115	ocean_pass_data_count_label	ascii string <i>size: 24</i> Ocean_Pass_Data_Count = fixed value: "Ocean_Pass_Data_Count = " hidden: true
116	ocean_pass_data_count	ascii int16 <i>size: 5</i> Number of 1 Hz measurements over ocean in the product
117	semicolon_mark_27	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
118	newline_char_29	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
119	ocean_pcd_label	ascii string <i>size: 12</i> Ocean_PCD = fixed value: "Ocean_PCD = " hidden: true
120	ocean_pcd	ascii int16 <i>size: 3</i> Product confidence data in percentage (ratio of the altimeter data declared OK to the total number of ocean measurements where data



		integrity is determined using the quality flag for the 1 Hz altimeter data unit: "%"
121	ocean_pcd_unit	ascii string <i>size: 3</i> <%> fixed value: "<%>" hidden: true
122	semicolon_mark_28	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
123	newline_char_30	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
124	time_epoch_label	ascii string <i>size: 13</i> Time_Epoch = fixed value: "Time_Epoch = " hidden: true
125	time_epoch	ascii time <i>size: 26</i> Reference used for measurement datation in the product (UTC value=1958-01-01T00:00:00.000000). BEAT time value is given in seconds since 01-JAN-2000 unit: "s since 2000-01-01" mapping: "0000-00-00T00:00:00.000000" -> 1.#QNANO ascii string <i>size: 26</i> CCSDS ASCII datetime "YYYY-MM-DDThh:mm:ss.uuuuu".
126	semicolon_mark_29	ascii char <i>size: 1</i>



		semicolon fixed value: ";" hidden: true
127	newline_char_31	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
128	tai_utc_difference_label	ascii string <i>size: 21</i> TAI_UTC_Difference = fixed value: "TAI_UTC_Difference = " hidden: true
129	tai_utc_difference	ascii int16 <i>size: 4</i> Increment to be applied to UTC to give TAI (dt=TAI-UTC) unit: "s"
130	semicolon_mark_30	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
131	newline_char_32	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
132	time_leap_second_label	ascii string <i>size: 22</i> Time_Of_Leap_Second = fixed value: "Time_Of_Leap_Second = " hidden: true
133	time_leap_second	ascii time <i>size: 26</i>



		<p>UTC Time at which a leap second occurred in the product. Set to 0000-00-00T00:00:00.000000 if not usefull. BEAT time value is given in seconds since 01-JAN-2000</p> <p>unit: "s since 2000-01-01"</p> <p>mapping: "0000-00-00T00:00:00.000000" -> 1.#QNANO</p> <p>ascii string size: 26</p> <p>CCSDS ASCII datetime "YYYY-MM-DDThh:mm:ss.uuuuuu".</p>
134	semicolon_mark_31	<p>ascii char size: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
135	newline_char_33	<p>ascii char size: 1</p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
136	time_shift_mid_frame_label	<p>ascii string size: 23</p> <p>Time_Shift_Mid_Frame =</p> <p>fixed value: "Time_Shift_Mid_Frame = "</p> <p>hidden: true</p>
137	time_shift_mid_frame	<p>ascii uint32 (double) size: 10</p> <p>Offset to apply to time to derive the time tag of the first 20 Hz waveform</p> <p>unit: "1e-6 s"</p> <p>converted unit: "s" (multiply by 1/1e+006)</p>
138	time_shift_mid_frame_unit	<p>ascii string size: 4</p> <p><us></p> <p>fixed value: "<us>"</p> <p>hidden: true</p>



139	semicolon_mark_32	<p>ascii char <i>size</i>: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
140	newline_char_34	<p>ascii char <i>size</i>: 1</p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
141	time_shift_interval_label	<p>ascii string <i>size</i>: 22</p> <p>Time_Shift_Interval =</p> <p>fixed value: "Time_Shift_Interval = "</p> <p>hidden: true</p>
142	time_shift_interval	<p>ascii uint32 (double) <i>size</i>: 10</p> <p>Time interval between two 20 Hz waveforms</p> <p>unit: "1e-6 s"</p> <p>converted unit: "s" (multiply by 1/1e+006)</p>
143	time_shift_interval_unit	<p>ascii string <i>size</i>: 4</p> <p><us></p> <p>fixed value: "<us>"</p> <p>hidden: true</p>
144	semicolon_mark_33	<p>ascii char <i>size</i>: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
145	newline_char_35	<p>ascii char <i>size</i>: 1</p> <p>newline</p> <p>fixed value: "\n"</p>



		hidden: true
146	range_offset_label	<p>ascii string <i>size: 15</i></p> <p>Range_Offset =</p> <p>fixed value: "Range_Offset = "</p> <p>hidden: true</p>
147	range_offset	<p>ascii uint16 <i>size: 4</i></p> <p>Offset to be added to the altitude and to the range to retrieve the absolute values of these parameters (i.e. 1300 km)</p> <p>unit: "km"</p>
148	range_offset_unit	<p>ascii string <i>size: 4</i></p> <p><km></p> <p>fixed value: "<km>"</p> <p>hidden: true</p>
149	semicolon_mark_34	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
150	newline_char_36	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
151	average_pressure_label	<p>ascii string <i>size: 19</i></p> <p>Average_Pressure =</p> <p>fixed value: "Average_Pressure = "</p> <p>hidden: true</p>
152	average_pressure	<p>ascii uint32 (double) <i>size: 5</i></p> <p>Average global pressure from meteo fields over oceans. The nearest meteorological field to the</p>



		<p>first measurement of the pass is used to compute this average pressure</p> <p>unit: "10 Pa"</p> <p>converted unit: "Pa" (multiply by 10/1)</p>
153	average_pressure_unit	<p>ascii string size: 6</p> <p><daPa></p> <p>fixed value: "<daPa>"</p> <p>hidden: true</p>
154	semicolon_mark_35	<p>ascii char size: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
155	newline_char_37	<p>ascii char size: 1</p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
156	header_padding_label	<p>ascii string size: 17</p> <p>Header_Padding =</p> <p>fixed value: "Header_Padding = "</p> <p>hidden: true</p>
157	header_padding	<p>ascii string size: 186</p> <p>hidden: true</p>
158	semicolon_mark_36	<p>ascii char size: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
159	newline_char_38	<p>ascii char size: 1</p> <p>newline</p>



		fixed value: "\n" hidden: true
160	ccsds_marker_2	ascii string <i>size: 20</i> CCSDS marker fixed value: "CCSD\$MARKERPASSFILE" hidden: true
161	supplementary_data_label_1	ascii string <i>size: 20</i> CCSDS Supplementary data label fixed value: "CCSD3SS00006MEASFILE" hidden: true
162	newline_char_39	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
163	altimeter_level1_label	ascii string <i>size: 19</i> Altimeter_Level1 = fixed value: "Altimeter_Level1 = " hidden: true
164	altimeter_level1	ascii string <i>size: 40</i> Name of the altimeter Level 1.0 input file
165	semicolon_mark_37	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
166	newline_char_40	ascii char <i>size: 1</i> newline fixed value: "\n"



		hidden: true
167	radiometer_level1_label	<p>ascii string size: 20</p> <p>Radiometer_Level1 =</p> <p>fixed value: "Radiometer_Level1 = "</p> <p>hidden: true</p>
168	radiometer_level1	<p>ascii string size: 40</p> <p>Name of the radiometer Level 1.0 input file</p>
169	semicolon_mark_38	<p>ascii char size: 1</p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
170	newline_char_41	<p>ascii char size: 1</p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
171	ccsds_marker_3	<p>ascii string size: 20</p> <p>CCSDS marker</p> <p>fixed value: "CCSD\$MARKERMEASFILE"</p> <p>hidden: true</p>
172	supplementary_data_label_2	<p>ascii string size: 20</p> <p>CCSDS Supplementary data label</p> <p>fixed value: "CCSD3SS00006AUXFILES"</p> <p>hidden: true</p>
173	newline_char_42	<p>ascii char size: 1</p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>



174	poseidon2_characterization_label	ascii string <i>size: 30</i> POSEIDON-2_Characterization = fixed value: "POSEIDON-2_Characterization = " hidden: true
175	poseidon2_characterization	ascii string <i>size: 61</i> Name of the file containing the characterization data for the POSEIDON-2 altimeter
176	semicolon_mark_39	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
177	newline_char_43	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
178	poseidon2_ltm_label	ascii string <i>size: 17</i> POSEIDON-2_LTM = fixed value: "POSEIDON-2_LTM = " hidden: true
179	poseidon2_ltm	ascii string <i>size: 61</i> Name of the file containing the Long Term Monitoring values for the POSEIDON-2 altimeter
180	semicolon_mark_40	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
181	newline_char_44	ascii char <i>size: 1</i> newline fixed value: "\n"



		hidden: true
182	jmr_main_beam_label	<p>ascii string <i>size: 16</i></p> <p>JMR_Main_Beam =</p> <p>fixed value: "JMR_Main_Beam = "</p> <p>hidden: true</p>
183	jmr_main_beam	<p>ascii string <i>size: 61</i></p> <p>Name of the file containing the main beam brightness temperature coefficients for the antenna pattern correction</p>
184	semicolon_mark_41	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
185	newline_char_45	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
186	jmr_bt_averaging_label	<p>ascii string <i>size: 19</i></p> <p>JMR_BT_Averaging =</p> <p>fixed value: "JMR_BT_Averaging = "</p> <p>hidden: true</p>
187	jmr_bt_averaging	<p>ascii string <i>size: 61</i></p> <p>Name of the file containing the main beam brightness temperature coefficients for the antenna pattern correction</p>
188	semicolon_mark_42	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>



189	newline_char_46	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
190	doris_tec_map_label	ascii string <i>size: 16</i> DORIS_TEC_Map = fixed value: "DORIS_TEC_Map = " hidden: true
191	doris_tec_map	ascii string <i>size: 61</i> Name of the file containing the Total Electronic Content calculated from DORIS measurements. (Set to 61 blank characters if the file was not available for the processing)
192	semicolon_mark_43	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
193	newline_char_47	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
194	doris_uso_label	ascii string <i>size: 12</i> DORIS_USO = fixed value: "DORIS_USO = " hidden: true
195	doris_uso	ascii string <i>size: 61</i> Name of the file containing the on-board Doris frequency shift
196	semicolon_mark_44	ascii char <i>size: 1</i> semicolon



		fixed value: ";" hidden: true
197	newline_char_48	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
198	orbit_data_label	ascii string <i>size: 13</i> Orbit_Data = fixed value: "Orbit_Data = " hidden: true
199	orbit_data	ascii string <i>size: 61</i> Name of the file containing the orbit ephemeris (MOE for IGDR, POE for GDR)
200	semicolon_mark_45	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
201	newline_char_49	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
202	pf_corrections_label	ascii string <i>size: 17</i> PF_Corrections = fixed value: "PF_Corrections = " hidden: true
203	pf_corrections	ascii string <i>size: 61</i> Name of the file containing the platform corrections (mispointing relative to the



		subsatellite point distance between antenna center of phase and center of gravity)
204	semicolon_mark_46	ascii char <i>size</i> : 1 semicolon fixed value: ";" hidden: true
205	newline_char_50	ascii char <i>size</i> : 1 newline fixed value: "\n" hidden: true
206	pole_location_label	ascii string <i>size</i> : 16 Pole_Location = fixed value: "Pole_Location = " hidden: true
207	pole_location	ascii string <i>size</i> : 61 Name of the file containing the precise pole location data
208	semicolon_mark_47	ascii char <i>size</i> : 1 semicolon fixed value: ";" hidden: true
209	newline_char_51	ascii char <i>size</i> : 1 newline fixed value: "\n" hidden: true
210	mto_fields_label	ascii string <i>size</i> : 13 MTO_Fields = fixed value: "MTO_Fields = "



		hidden: true
211	mto_fields	ascii string <i>size: 20</i> Name of the MTO model from which the meteorological parameters have been derived (Currently ECMWF_T511)
212	semicolon_mark_48	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
213	newline_char_52	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
214	orf_data_label	ascii string <i>size: 11</i> ORF_Data = fixed value: "ORF_Data = " hidden: true
215	orf_data	ascii string <i>size: 61</i> Orbit Revolution File used to create the pass file
216	semicolon_mark_49	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
217	newline_char_53	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
218	poseidon2_ob_ret_correction_tables_label	ascii string <i>size: 38</i> POSEIDON-2_OB_RET_Correction_Tables =



		fixed value: "POSEIDON-2_OB_RET_Correction_Tables = " hidden: true
219	poseidon2_ob_ret_correction_tables	ascii string <i>size: 61</i> Name of the file containing the on-board retracking coefficient corrections
220	semicolon_mark_50	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
221	newline_char_54	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
222	poseidon2_ssb_label	ascii string <i>size: 17</i> POSEIDON-2_SSB = fixed value: "POSEIDON-2_SSB = " hidden: true
223	poseidon2_ssb	ascii string <i>size: 61</i> Name of the file containing the Sea state bias coefficient for Poseidon-2
224	semicolon_mark_51	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
225	newline_char_55	ascii char <i>size: 1</i> newline fixed value: "\n"



		hidden: true
226	poseidon2_composite_ssb_label	<p>ascii string <i>size: 27</i></p> <p>POSEIDON-2_Composite_SSB =</p> <p>fixed value: "POSEIDON-2_Composite_SSB = "</p> <p>hidden: true</p>
227	poseidon2_composite_ssb	<p>ascii string <i>size: 61</i></p> <p>Name of the file containing the composite Sea state bias coefficient for Poseidon-2</p>
228	semicolon_mark_52	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
229	newline_char_56	<p>ascii char <i>size: 1</i></p> <p>newline</p> <p>fixed value: "\n"</p> <p>hidden: true</p>
230	jmr_retrieval_coefficients_label	<p>ascii string <i>size: 29</i></p> <p>JMR_Retrieval_Coefficients =</p> <p>fixed value: "JMR_Retrieval_Coefficients = "</p> <p>hidden: true</p>
231	jmr_retrieval_coefficients	<p>ascii string <i>size: 61</i></p> <p>Name of the file containing the geophysical coefficients for the JMR</p>
232	semicolon_mark_53	<p>ascii char <i>size: 1</i></p> <p>semicolon</p> <p>fixed value: ";"</p> <p>hidden: true</p>
233	newline_char_57	<p>ascii char <i>size: 1</i></p> <p>newline</p>



		fixed value: "\n" hidden: true
234	land_sea_mask_map_label	ascii string <i>size: 20</i> LAND_SEA_Mask_Map = fixed value: "LAND_SEA_Mask_Map = " hidden: true
235	land_sea_mask_map	ascii string <i>size: 61</i> Name of the file containing the Land/Sea mask map
236	semicolon_mark_54	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
237	newline_char_58	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
238	ocean_tide_sol_1_label	ascii string <i>size: 19</i> Ocean_Tide_Sol_1 = fixed value: "Ocean_Tide_Sol_1 = " hidden: true
239	ocean_tide_sol_1	ascii string <i>size: 20</i> Name of the ocean tide model #1 (currently GOT99)
240	semicolon_mark_55	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true



241	newline_char_59	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
242	ocean_tide_sol_2_label	ascii string <i>size: 19</i> Ocean_Tide_Sol_2 = fixed value: "Ocean_Tide_Sol_2 = " hidden: true
243	ocean_tide_sol_2	ascii string <i>size: 20</i> Name of the ocean tide model #2 (currently FES99)
244	semicolon_mark_56	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
245	newline_char_60	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
246	tidal_loading_sol_1_label	ascii string <i>size: 22</i> Tidal_Loading_Sol_1 = fixed value: "Tidal_Loading_Sol_1 = " hidden: true
247	tidal_loading_sol_1	ascii string <i>size: 20</i> Name of loading tide model #1 (currently GOT99)
248	semicolon_mark_57	ascii char <i>size: 1</i> semicolon fixed value: ";"



		hidden: true
249	newline_char_61	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
250	tidal_loading_sol_2_label	ascii string <i>size: 22</i> Tidal>Loading_Sol_2 = fixed value: "Tidal>Loading_Sol_2 = " hidden: true
251	tidal_loading_sol_2	ascii string <i>size: 20</i> Name of loading tide model #2 (currently FES99)
252	semicolon_mark_58	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
253	newline_char_62	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
254	solid_earth_tide_label	ascii string <i>size: 19</i> Solid_Earth_Tide = fixed value: "Solid_Earth_Tide = " hidden: true
255	solid_earth_tide	ascii string <i>size: 61</i> Name of the file containing the Cartwright and Edden tide potential amplitudes for the solid earth tide and the Equilibrium long period ocean tide height calculation
256	semicolon_mark_59	ascii char <i>size: 1</i>



		semicolon fixed value: ";" hidden: true
257	newline_char_63	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
258	neq_tide_label	ascii string <i>size: 11</i> NEQ_Tide = fixed value: "NEQ_Tide = " hidden: true
259	neq_tide	ascii string <i>size: 20</i> Name of the dynamic model fro long period tides (Currently NONE)
260	semicolon_mark_60	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
261	newline_char_64	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
262	geoid_map_label	ascii string <i>size: 12</i> Geoid_Map = fixed value: "Geoid_Map = " hidden: true
263	geoid_map	ascii string <i>size: 20</i> Name of the geoid model (currently EGM96)



264	semicolon_mark_61	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
265	newline_char_65	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
266	mss_map_label	ascii string <i>size: 10</i> MSS_Map = fixed value: "MSS_Map = " hidden: true
267	mss_map	ascii string <i>size: 20</i> Name of the Mean Sea Surface model (Currently GSF00.1)
268	semicolon_mark_62	ascii char <i>size: 1</i> semicolon fixed value: ";" hidden: true
269	newline_char_66	ascii char <i>size: 1</i> newline fixed value: "\n" hidden: true
270	bathymetry_topography_map_label	ascii string <i>size: 28</i> Bathymetry_Topography_Map = fixed value: "Bathymetry_Topography_Map = " hidden: true
271	bathymetry_topography_map	ascii string <i>size: 20</i>



		Name of the bathymetry/topography model (Currently DTM2000.1)
272	semicolon_mark_63	ascii char <i>size</i> : 1 semicolon fixed value: ";" hidden: true
273	newline_char_67	ascii char <i>size</i> : 1 newline fixed value: "\n" hidden: true
274	ccsds_marker_4	ascii string <i>size</i> : 20 CCSDS marker fixed value: "CCSD\$MARKERAUXFILES" hidden: true
275	data_label	ascii string <i>size</i> : 20 fixed value: "FCST3IF0011400000001" hidden: true

3.5.2.2. GDR_DATA_RECORD

binary record "[GDR_DATA_RECORD](#)"

size: 440

id	field name	definition
0	time_day	binary uint32 <i>size</i> : 4 time stamp 1 (number of days from reference data) unit: "days since 1958-01-01"
1	time_sec	binary uint32 <i>size</i> : 4 time stamp 2 (number of seconds within the day) unit: "s"
2	time_microsec	binary uint32 <i>size</i> : 4



		time stamp 3 (number of microseconds within the second) unit: "1e-6 s"															
3	latitude	binary int32 (double) <i>size: 4</i> latitude unit: "1e-6 degrees_north" converted unit: "degrees_north" (multiply by 1/1e+006)															
4	longitude	binary uint32 (double) <i>size: 4</i> longitude unit: "1e-6 degrees_east" converted unit: "degrees_east" (multiply by 1/1e+006)															
5	surface_type	binary uint8 <i>size: 1</i> surface type (0 = open oceans or semi-enclosed seas, 1 = enclosed seas or lakes, 2 = continental ice, 3 = land)															
6	alt_echo_type	binary uint8 <i>size: 1</i> altimeter echo type (0 = ocean-like, 1 = non ocean-like)															
7	rad_surf_type	binary uint8 <i>size: 1</i> radiometer surface type (0 = ocean, 1 = land)															
8	qual_1hz_alt_data	binary record <i>size: 1</i> quality flag for 1 Hz altimeter data <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 5%;">id</th> <th style="width: 55%;">field name</th> <th style="width: 40%;">definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>off_nadir_angle_ptf</td> <td>binary uint8 <i>size: 0:1</i> off nadir angle from platform (0 = good, 1 = bad)</td> </tr> <tr> <td>1</td> <td>off_nadir_angle_ku_wvf</td> <td>binary uint8 <i>size: 0:1</i> off nadir angle from Ku band waveform parameters (0 = good, 1 = bad)</td> </tr> <tr> <td>2</td> <td>sig0_c</td> <td>binary uint8 <i>size: 0:1</i> C band backscatter coefficient (0 = good, 1 = bad)</td> </tr> <tr> <td>3</td> <td>sig0_ku</td> <td>binary uint8 <i>size: 0:1</i></td> </tr> </tbody> </table>	id	field name	definition	0	off_nadir_angle_ptf	binary uint8 <i>size: 0:1</i> off nadir angle from platform (0 = good, 1 = bad)	1	off_nadir_angle_ku_wvf	binary uint8 <i>size: 0:1</i> off nadir angle from Ku band waveform parameters (0 = good, 1 = bad)	2	sig0_c	binary uint8 <i>size: 0:1</i> C band backscatter coefficient (0 = good, 1 = bad)	3	sig0_ku	binary uint8 <i>size: 0:1</i>
id	field name	definition															
0	off_nadir_angle_ptf	binary uint8 <i>size: 0:1</i> off nadir angle from platform (0 = good, 1 = bad)															
1	off_nadir_angle_ku_wvf	binary uint8 <i>size: 0:1</i> off nadir angle from Ku band waveform parameters (0 = good, 1 = bad)															
2	sig0_c	binary uint8 <i>size: 0:1</i> C band backscatter coefficient (0 = good, 1 = bad)															
3	sig0_ku	binary uint8 <i>size: 0:1</i>															



			Ku band backscatter coefficient (0 = good, 1 = bad)
4	swh_c	binary uint8	size: 0:1 C band SWH (0 = good, 1 = bad)
5	swh_ku	binary uint8	size: 0:1 Ku band SWH (0 = good, 1 = bad)
6	range_c	binary uint8	size: 0:1 C band range (0 = good, 1 = bad)
7	range_ku	binary uint8	size: 0:1 Ku band range (0 = good, 1 = bad)
9	qual_1hz_alt_instr_corr	binary record	size: 1 quality flag for 1 Hz altimeter data
		id	field name
			definition
0	spare	binary bytes	size: 0:2 spare hidden: true
1	sig0_c	binary uint8	size: 0:1 C band backscatter coefficient instrumental correction (0 = good, 1 = bad)
2	sig0_ku	binary uint8	size: 0:1 Ku band backscatter coefficient instrumental correction (0 = good, 1 = bad)
3	swh_c	binary uint8	size: 0:1 C band SWH instrumental correction (0 = good, 1 = bad)
4	swh_ku	binary uint8	size: 0:1 Ku band SWH instrumental correction (0 = good, 1 = bad)
5	range_c	binary uint8	size: 0:1



			C band range instrumental correction (0 = good, 1 = bad)
	6	range_ku	binary uint8 <i>size: 0:1</i> Ku band range instrumental correction (0 = good, 1 = bad)
10	qual_1hz_rad_data	binary record <i>size: 1</i> quality flag for 1 Hz radiometer data	
		id	field name definition
		0	spare binary bytes <i>size: 0:5</i> spare hidden: true
		1	tb_340 binary uint8 <i>size: 0:1</i> 34 GHz brightness temperature (0 = good, 1 = bad)
		2	tb_238 binary uint8 <i>size: 0:1</i> 23.8 GHz brightness temperature (0 = good, 1 = bad)
		3	tb_187 binary uint8 <i>size: 0:1</i> 18.7 GHz brightness temperature (0 = good, 1 = bad)
11	alt_state_flag	binary record <i>size: 1</i> altimeter state flag	
		id	field name definition
		0	status_c binary uint8 <i>size: 0:1</i> C band status (0 = on, 1 = off)
		1	status_ku binary uint8 <i>size: 0:1</i> Ku band status (0 = on, 1 = off)
		2	band_seq binary uint8 <i>size: 0:1</i> Ku/C band sequencing (0 = 3Ku-1C-3Ku, 1 = 2Ku-1C-2Ku)
		3	bandwidth_c binary uint8 <i>size: 0:1</i>



			C bandwidth (0 = 320 MHz, 1 = 100 MHz)
4	spectrum_coding	binary uint8	size: 0:1 Spectrum coding (0 = I and Q, 1 = I ² + Q ²)
5	bandwidth_inv	binary uint8	size: 0:1 reception bandwidth inversion (0 = Not reversed, 1 = reversed)
6	altimeter	binary uint8	size: 0:1 Altimeter operating (0 = side A (nominal POSEIDON-2 altimeter), 1 = side B (redundancy))
7	spare	binary bytes	size: 0:1 spare hidden: true
12	rad_state_flag	binary record	size: 1 radiometer state flag
		id	field name
			definition
0	spare	binary bytes	size: 0:4 spare hidden: true
1	channel_3	binary uint8	size: 0:1 23.8 GHz Channel 3 (0 = On, 1 = Off); if channel 2 and 3 are both on, the 23.8 GHz brightness temperature that is provided in the OSDR is taken from the nominal channel (channel 3) and the corresponding geophysical parameters are derived from the channel 3 brightness temperature
2	channel_2	binary uint8	size: 0:1 23.8 GHz Channel 2 (0 = On, 1 = Off)
3	mode1_cal_sequence	binary uint8	size: 0:1



			Mode 1 Cal Sequence (0 = Normal data taking Mode 1 or 2, 1 = Mode 1 Cal Sequence)
	4	mode	binary uint8 <i>size: 0:1</i> Mode (0 = Mode 2 (nominal), 1 = Mode 1)
13	orb_state_flag	binary uint8 <i>size: 1</i> orbit state flag. The orbit stat may range from 0 to 9: 0 = mission operations orbit that is computer during a maneuver period, 1 = adjusted mission operations orbit, 2 = extrapolated mission operations orbit, 3 = adjusted (preliminary/precise) orbit, 4 = the (preliminary/precise) orbit is estimated during a maneuver period, 5 = the (preliminary/precise) orbit is interpolated over a tracking data gap, 6 = the (preliminary/precise) orbit extrapolated for a duration less than 1 day, 7 = the (preliminary/precise) orbit is extrapolated for a duration that ranges from 1 day to 2 days, 8 = the (preliminary/precise) orbit is extrapolated for a duration larger than 2 days, or the orbit is extrapolated just after a maneuver, 9 = the DORIS DIODE navigator orbit	
14	qual_spare	binary bytes <i>size: 3</i> spare (to be aligned) hidden: true	
15	altitude	binary uint32 <i>size: 4</i> 1 Hz altitude of satellite (a reference offset is subtracted from the altitude. The reference offset can be found in the header) unit: "1e-4 m"	
16	alt_hi_rate	binary array[20] <i>size: 80</i> differences between altitudes corresponding to the elementary measurements to that of the averaged measurements binary int32 <i>size: 4</i> unit: "1e-4 m"	
17	orb_alt_rate	binary int16 <i>size: 2</i> orbital altitude rate unit: "cm/s"	
18	orb_spare	binary bytes <i>size: 2</i>	



		<p>spare (to be aligned)</p> <p>hidden: true</p>
19	range_ku	<p>binary uint32 <i>size: 4</i></p> <p>1 Hz Ku band range (a reference offset is subtracted from the range. The reference offset can be found in the header)</p> <p>unit: "1e-4 m"</p>
20	range_hi_rate_ku	<p>binary array[20] <i>size: 80</i></p> <p>20 Hz Ku band ranges (a reference offset is subtracted from the ranges. The reference offset can be found in the header)</p> <p>binary int32 <i>size: 4</i></p> <p>unit: "1e-4 m"</p>
21	range_c	<p>binary uint32 <i>size: 4</i></p> <p>1 Hz C band range (a reference offset is subtracted from the range. The reference offset can be found in the header)</p> <p>unit: "1e-4 m"</p>
22	range_hi_rate_c	<p>binary array[20] <i>size: 80</i></p> <p>20 Hz C band ranges (a reference offset is subtracted from the ranges. The reference offset can be found in the header)</p> <p>binary int32 <i>size: 4</i></p> <p>unit: "1e-4 m"</p>
23	range_rms_ku	<p>binary uint16 <i>size: 2</i></p> <p>RMS of the Ku band range</p> <p>unit: "1e-4 m"</p>
24	range_rms_c	<p>binary uint16 <i>size: 2</i></p> <p>RMS of the C band range</p> <p>unit: "1e-4 m"</p>
25	range_numval_ku	<p>binary uint8 <i>size: 1</i></p> <p>Number of valid points for Ku band range</p>
26	range_numval_c	<p>binary uint8 <i>size: 1</i></p> <p>Number of valid points for C band range</p>
27	pseudo_datation_bias_corr_ku	<p>binary int16 <i>size: 2</i></p>



		Pseudo altimeter datation bias correction (available only for version C and higher) unit: "1e-4 m"
28	range_mapvalpts_ku_spare	binary bytes <i>size: 1:4</i> spare hidden: true
29	range_mapvalpts_ku	binary array[20] <i>size: 2:4</i> map of valid points for Ku band range binary uint8 <i>size: 0:1</i> 1 = bad, 0 = good
30	range_mapvalpts_c_spare	binary bytes <i>size: 1:4</i> spare hidden: true
31	range_mapvalpts_c	binary array[20] <i>size: 2:4</i> map of valid points for C band range binary uint8 <i>size: 0:1</i> 1 = bad, 0 = good
32	net_instr_corr_ku	binary int32 <i>size: 4</i> net instrumental correction on Ku band range unit: "1e-4 m"
33	net_instr_corr_c	binary int32 <i>size: 4</i> net instrumental correction on C band range unit: "1e-4 m"
34	model_dry_tropo_corr	binary int16 <i>size: 2</i> model dry tropospheric correction unit: "1e-4 m"
35	model_wet_tropo_corr	binary int16 <i>size: 2</i> model wet tropospheric correction unit: "1e-4 m"



36	rad_wet_tropo_corr	binary int16 <i>size: 2</i> radiometer wet tropospheric correction unit: "1e-4 m"
37	iono_corr_alt_ku	binary int16 <i>size: 2</i> altimeter ionospheric correction on Ku band unit: "1e-4 m"
38	iono_corr_doris_ku	binary int16 <i>size: 2</i> DORIS iono correction on Ku band unit: "1e-4 m"
39	sea_state_bias_ku	binary int16 <i>size: 2</i> sea state bias correction in Ku-band unit: "1e-4 m"
40	sea_state_bias_c	binary int16 <i>size: 2</i> sea state bias correction in C-band unit: "1e-4 m"
41	sea_state_bias_comp	binary int16 <i>size: 2</i> composite sea state bias correction unit: "1e-4 m"
42	swh_ku	binary uint16 <i>size: 2</i> Ku band significant waveheight unit: "1e-3 m"
43	swh_c	binary uint16 <i>size: 2</i> C band significant waveheight unit: "1e-3 m"
44	swh_rms_ku	binary uint16 <i>size: 2</i> RMS of the Ku band sigmaC unit: "1e-3 m"
45	swh_rms_c	binary uint16 <i>size: 2</i> RMS of the C band sigmaC



		unit: "1e-3 m"
46	swh_numval_ku	binary uint8 <i>size: 1</i> number of valid points used to compute Ku-band significant waveheight
47	swh_numval_c	binary uint8 <i>size: 1</i> number of valid points used to compute C-band significant waveheight
48	net_instr_corr_swh_ku	binary int16 <i>size: 2</i> net instrumental correction on Ku band significant waveheight unit: "1e-3 m"
49	net_instr_corr_swh_c	binary int16 <i>size: 2</i> net instrumental correction on C band significant waveheight unit: "1e-3 m"
50	sig0_ku	binary uint16 (double) <i>size: 2</i> Ku band backscatter coefficient (corrected for atmospheric attenuations) unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
51	sig0_c	binary uint16 (double) <i>size: 2</i> C band backscatter coefficient (corrected for atmospheric attenuations) unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
52	sig0_rms_ku	binary uint16 (double) <i>size: 2</i> RMS of the Ku band backscatter coefficient (corrected for atmospheric attenuations) unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
53	sig0_rms_c	binary uint16 (double) <i>size: 2</i> RMS of the C band backscatter coefficient (corrected for atmospheric attenuations) unit: "1e-2 dB"



		converted unit: "dB" (multiply by 1/100)
54	sig0_num_val_ku	binary uint8 <i>size: 1</i> number of valid points used to compute Ku backscatter coefficient
55	sig0_num_val_c	binary uint8 <i>size: 1</i> number of valid points used to compute C backscatter coefficient
56	agc_ku	binary uint16 (double) <i>size: 2</i> Ku band AGC unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
57	agc_c	binary uint16 (double) <i>size: 2</i> C band AGC unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
58	agc_rms_ku	binary uint16 (double) <i>size: 2</i> RMS of the Ku band AGC unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
59	agc_rms_c	binary uint16 (double) <i>size: 2</i> RMS of the C band AGC unit: "1e-2 dB" converted unit: "dB" (multiply by 1/100)
60	agc_numval_ku	binary uint8 <i>size: 1</i> number of valid points used to compute Ku band AGC
61	agc_numval_c	binary uint8 <i>size: 1</i> number of valid points used to compute C band AGC
62	net_instr_sig0_corr_ku	binary int16 (double) <i>size: 2</i> net instrumental correction on Ku band backscatter coefficient unit: "1e-2 dB"



		converted unit: "dB" (multiply by 1/100)
63	net_instr_sig0_corr_c	<p>binary int16 (double) <i>size: 2</i></p> <p>net instrumental correction on C band backscatter coefficient</p> <p>unit: "1e-2 dB"</p> <p>converted unit: "dB" (multiply by 1/100)</p>
64	atmos_sig0_corr_ku	<p>binary int16 (double) <i>size: 2</i></p> <p>atmospheric attenuation correction on Ku band backscatter coefficient</p> <p>unit: "1e-2 dB"</p> <p>converted unit: "dB" (multiply by 1/100)</p>
65	atmos_sig0_corr_c	<p>binary int16 (double) <i>size: 2</i></p> <p>atmospheric attenuation correction on C band backscatter coefficient</p> <p>unit: "1e-2 dB"</p> <p>converted unit: "dB" (multiply by 1/100)</p>
66	off_nadir_angle_ku_wvf	<p>binary int16 (double) <i>size: 2</i></p> <p>Square of the off nadir angle computed from Ku waveforms</p> <p>unit: "1e-4 degrees2"</p> <p>converted unit: "degrees2" (multiply by 1/1000)</p>
67	off_nadir_angle_ptf	<p>binary int16 (double) <i>size: 2</i></p> <p>Square of the off nadir angle computed from platform data</p> <p>unit: "1e-4 degrees2"</p> <p>converted unit: "degrees2" (multiply by 1/1000)</p>
68	tb_187	<p>binary uint16 (double) <i>size: 2</i></p> <p>18.7 GHz brightness temperature (along track averaging has not been performed)</p> <p>unit: "1e-2 K"</p> <p>converted unit: "K" (multiply by 1/100)</p>
69	tb_238	<p>binary uint16 (double) <i>size: 2</i></p> <p>23.8 GHz brightness temperature (along track averaging has not been performed)</p>



		unit: "1e-2" K" converted unit: "K" (multiply by 1/100)
70	tb_340	binary uint16 (double) <i>size: 2</i> 34 GHz brightness temperature (along track averaging has not been performed) unit: "1e-2" K" converted unit: "K" (multiply by 1/100)
71	mss	binary int32 <i>size: 4</i> mean sea surface height unit: "1e-4 m"
72	mss_tp_along_trk	binary int32 <i>size: 4</i> TP along-track mean sea surface unit: "1e-4 m"
73	geoid	binary int32 <i>size: 4</i> geoid height unit: "1e-4 m"
74	bathymetry	binary int16 <i>size: 2</i> ocean depth/land elevation unit: "m"
75	inv_bar_corr	binary int16 <i>size: 2</i> inverted barometer height correction unit: "1e-4 m"
76	hf_fluctuations_corr	binary int16 <i>size: 2</i> High frequency fluctuations of the sea surface topography unit: "1e-4 m"
77	mdt	binary int16 <i>size: 2</i> mean dynamic topography (available only for version C and higher) unit: "1e-4 m"



78	ocean_tide_sol1	binary int32 <i>size: 4</i> geocentric ocean tide height (solution 1) unit: "1e-4 m"
79	ocean_tide_sol2	binary int32 <i>size: 4</i> geocentric ocean tide height (solution 2) unit: "1e-4 m"
80	ocean_tide_equil	binary int16 <i>size: 2</i> equilibrium long-period ocean tide height unit: "1e-4 m"
81	ocean_tide_non_equil	binary int16 <i>size: 2</i> non-equilibrium long-period ocean tide height unit: "1e-4 m"
82	load_tide_sol1	binary int16 <i>size: 2</i> loading tide height for geocentric ocean tide solution 1 unit: "1e-4 m"
83	load_tide_sol2	binary int16 <i>size: 2</i> loading tide height for geocentric ocean tide solution 2 unit: "1e-4 m"
84	solid_earth_tide	binary int16 <i>size: 2</i> solid earth tide height unit: "1e-4 m"
85	pole_tide	binary int16 <i>size: 2</i> geocentric pole tide height unit: "1e-4 m"
86	wind_speed_model_u	binary int16 <i>size: 2</i> U component of the model wind vector unit: "cm/s"
87	wind_speed_model_v	binary int16 <i>size: 2</i> V component of the model wind vector



		unit: "cm/s"						
88	wind_speed_alt	binary uint16 <i>size: 2</i> altimeter wind speed unit: "cm/s"						
89	wind_speed_rad	binary uint16 <i>size: 2</i> radiometer wind speed unit: "cm/s"						
90	rad_water_vapour	binary int16 <i>size: 2</i> radiometer water vapour content unit: "1e-2 g/cm2"						
91	rad_liquid_water	binary int16 <i>size: 2</i> radiometer liquid water unit: "1e-2 kg/cm2"						
92	ecmwf_meteo_map_avail	binary uint8 <i>size: 1</i> ECMWF meteorological map availability (0 = 2 maps nominal, 1 = 2 maps degraded, 2 = 1 map, 3 = no map). Given the latest definition of the meteorological field processing algorithms, this flag will in fact always be set to 0. Consequently, it does not bring any useful information; the flag may thus be removed from the product once the verification phase is completed						
93	tb_interp_flag	binary uint8 <i>size: 1</i> radiometer brightness temperatures interpolation flag (0 = good (no gap between JMR data), 1 = interp (gap between JMR data), 2 = extrap (extrapolation used), 3 = fail (extrapolation and interpolation failed))						
94	rain_flag	binary uint8 <i>size: 1</i> rain flag (0 = OK, 1 = rain)						
95	ice_flag	binary uint8 <i>size: 1</i> ice flag (0 = OK, 1 = ice)						
96	interp_flag	binary record <i>size: 1</i> interpolation flag						
		<table border="1"> <thead> <tr> <th>id</th> <th>field name</th> <th>definition</th> </tr> </thead> <tbody> <tr> <td></td> <td></td> <td></td> </tr> </tbody> </table>	id	field name	definition			
id	field name	definition						



	0	spare	binary bytes <i>size: 0:4</i> spare hidden: true
	1	meteo_interp	binary uint8 <i>size: 0:1</i> meteorological data interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)
	2	ocean_tide_sol2	binary uint8 <i>size: 0:1</i> ocean tide solution 2 interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)
	3	ocean_tide_sol1	binary uint8 <i>size: 0:1</i> ocean tide solution 1 interpolation flag (0 = 4 points over ocean, 1 = less than 4 points)
	4	mss	binary uint8 <i>size: 0:1</i> MSS interpolation flag (0 = good, 1 = bad)
97	flag_spare		binary bytes <i>size: 3</i> spare (to be aligned) hidden: true

3.6. Jason-2 data

3.6.1. Filenaming convention

The product names are based on the following convention:

- JA2_<O/I/G>P<N/R/S>_2P<v><S/P><ccc>_<ppp>_<yyyymmdd_hhnnss>_<yyyymmdd_hhnnss>.n
c

With:

- <O/I/G> : product family (O : OGDR, I : IGDR, G: GDR)
- <N/R/S> : product type (N : native, R: reduced, S : sensor)
- <v> : product version (set to 'T' during CalVal phases, set to 'c', the current Jason-1 data standards, for the first delivery of OSTM/Jason-2 products to users, set to 'd' for the reprocessed delivery)
- <S/P> : product duration (S : segment for OGDR, P : pass for I/GDR)
- <ccc>: cycle number of 1st product record



- <ppp> : pass number of 1st product record (1-254)
- <yyyymmdd_hhnnss> : date of 1st product record
- <yyyymmdd_hhnnss> : date of last product record

3.6.2. Product data format

```
netcdf JA2_GPR_2PdP007_002_20080909_140728_20080909_150340 {
```

```
dimensions:
```

```
    time = 3307 ;
```

```
variables:
```

```
    double time(time) ;
```

```
        time:long_name = "time (sec. since 2000-01-01)" ;
```

```
        time:standard_name = "time" ;
```

```
        time:calendar = "gregorian" ;
```

```
        time:tai_utc_difference = -33. ;
```

```
        time:leap_second = "0000-00-00 00:00:00" ;
```

```
        time:units = "seconds since 2000-01-01 00:00:00.0" ;
```

```
        time:comment = "[tai_utc_difference] is the difference between T
AI and UTC reference time (seconds) for the first measurement of the data set. [
leap_second] is the UTC time at which a leap second occurs in the data set, if a
ny. After this UTC time, the [tai_utc_difference] is increased by 1 second" ;
```

```
    int lat(time) ;
```

```
        lat:long_name = "latitude" ;
```

```
        lat:standard_name = "latitude" ;
```

```
        lat:units = "degrees_north" ;
```

```
        lat:scale_factor = 1.e-06 ;
```

```
        lat:comment = "Positive latitude is North latitude, negative lat
itude is South latitude. See Jason-2 User Handbook. Associated quality flag is o
rb_state_flag_diode for the OGDR products, orb_state_flag_rest for the IGDR and and
GDR products" ;
```

```
    int lon(time) ;
```

```
        lon:long_name = "longitude" ;
```

```
        lon:standard_name = "longitude" ;
```

```
        lon:units = "degrees_east" ;
```

```
        lon:scale_factor = 1.e-06 ;
```

```
        lon:comment = "East longitude relative to Greenwich meridian. Se
e Jason-2 User Handbook. Associated quality flag is orb_state_flag_diode for the
```




OGDR products, orb_state_flag_rest for the IGDR and GDR products" ;

byte surface_type(time) ;

surface_type:_FillValue = 127b ;

surface_type:long_name = "surface type" ;

surface_type:flag_values = 0b, 1b, 2b, 3b ;

surface_type:flag_meanings = "ocean lake_enclosed_sea ice land"

;

surface_type:coordinates = "lon lat" ;

surface_type:comment = "Computed using a DTM2000 file: 0 = open oceans or semi-enclosed seas; 1 = enclosed seas or lakes; 2 = continental ice; 3 = land. See Jason-2 User Handbook" ;

byte alt_echo_type(time) ;

alt_echo_type:_FillValue = 127b ;

alt_echo_type:long_name = "altimeter echo type" ;

alt_echo_type:flag_values = 0b, 1b ;

alt_echo_type:flag_meanings = "ocean_like non_ocean_like" ;

alt_echo_type:coordinates = "lon lat" ;

alt_echo_type:comment = "The altimeter echo type is determined by testing the rms of the high rate range measurements against a threshold as well as the number of valid high rate range measurements against a minimum value" ;

byte rad_surf_type(time) ;

rad_surf_type:_FillValue = 127b ;

rad_surf_type:long_name = "radiometer surface type" ;

rad_surf_type:flag_values = 0b, 1b, 2b ;

rad_surf_type:flag_meanings = "open_ocean near_coast land" ;

rad_surf_type:coordinates = "lon lat" ;

rad_surf_type:comment = "The radiometer surface type flag is applicable to the radiometer wet troposphere path delays provided by rad_wet_tropo_corr. A value of 0 indicates that open ocean processing is used to compute the path delay, 1 indicates coastal processing is used, and 2 indicates the path delay is invalid due to land" ;

byte alt_quality_flag(time) ;

alt_quality_flag:_FillValue = 127b ;

alt_quality_flag:long_name = "altimeter quality flag" ;

alt_quality_flag:flag_values = 0b, 1b ;

alt_quality_flag:flag_meanings = "good bad" ;

alt_quality_flag:coordinates = "lon lat" ;

alt_quality_flag:comment = "Compilation of all altimeter flags e



```

except altimeter echo type : Set to default in the current issue" ;
    byte rad_quality_flag(time) ;
        rad_quality_flag:_FillValue = 127b ;
        rad_quality_flag:long_name = "radiometer quality flag" ;
        rad_quality_flag:flag_values = 0b, 1b ;
        rad_quality_flag:flag_meanings = "good bad" ;
        rad_quality_flag:coordinates = "lon lat" ;
        rad_quality_flag:comment = "Compilation of all radiometer flags
except radiometer surface type : Set to default in the current issue" ;
    byte geophysical_quality_flag(time) ;
        geophysical_quality_flag:_FillValue = 127b ;
        geophysical_quality_flag:long_name = "geophysical quality flag"
;

        geophysical_quality_flag:flag_values = 0b, 1b ;
        geophysical_quality_flag:flag_meanings = "good bad" ;
        geophysical_quality_flag:coordinates = "lon lat" ;
        geophysical_quality_flag:comment = "Check on validity of all geo
physical fields : Set to default in the current issue" ;
    byte ecmwf_meteo_map_avail(time) ;
        ecmwf_meteo_map_avail:_FillValue = 127b ;
        ecmwf_meteo_map_avail:long_name = "ECMWF meteorological map availability" ;
        ecmwf_meteo_map_avail:flag_values = 0b, 1b, 2b, 3b ;
        ecmwf_meteo_map_avail:flag_meanings = "2_maps_nominal 2_maps_deg
rated 1_map_extropolated no_map" ;
        ecmwf_meteo_map_avail:coordinates = "lon lat" ;
        ecmwf_meteo_map_avail:comment = "Possible values are: 0 meaning
\'2 maps, nominal\' (six hours apart), 1 meaning \'2 maps, degraded\' (more than
six hours apart), 2 meaning \'1 map, extrapolation used\', 3 meaning \'no map\'
" ;

    byte rain_flag(time) ;
        rain_flag:_FillValue = 127b ;
        rain_flag:long_name = "rain flag" ;
        rain_flag:flag_values = 0b, 1b ;
        rain_flag:flag_meanings = "no_rain rain" ;
        rain_flag:coordinates = "lon lat" ;
        rain_flag:comment = "See Jason-2 User Handbook" ;
    byte rad_rain_flag(time) ;
        rad_rain_flag:_FillValue = 127b ;

```



```

rad_rain_flag:long_name = "radiometer rain flag" ;
rad_rain_flag:flag_values = 0b, 1b ;
rad_rain_flag:flag_meanings = "no_rain rain" ;
rad_rain_flag:coordinates = "lon lat" ;
rad_rain_flag:comment = "See Jason-2 User Handbook. The radiomet
er rain flag indicates where the radiometer wet troposphere path delay (rad_wet_
tropo_corr) is invalid due to rain contamination" ;

```

```

byte ice_flag(time) ;

```

```

ice_flag:_FillValue = 127b ;
ice_flag:long_name = "ice flag" ;
ice_flag:flag_values = 0b, 1b ;
ice_flag:flag_meanings = "no_ice ice" ;
ice_flag:coordinates = "lon lat" ;
ice_flag:comment = "See Jason-2 User Handbook" ;

```

```

byte rad_sea_ice_flag(time) ;

```

```

rad_sea_ice_flag:_FillValue = 127b ;
rad_sea_ice_flag:long_name = "radiometer sea-ice flag" ;
rad_sea_ice_flag:flag_values = 0b, 1b ;
rad_sea_ice_flag:flag_meanings = "no_sea_ice sea_ice" ;
rad_sea_ice_flag:coordinates = "lon lat" ;
rad_sea_ice_flag:comment = "See Jason-2 User Handbook. The radio
meter sea ice flag indicates where the radiometer wet troposphere path delay (ra
d_wet_tropo_corr) is invalid due to sea ice contamination" ;

```

```

int alt(time) ;

```

```

alt:_FillValue = 2147483647 ;
alt:long_name = "1 Hz altitude of satellite" ;
alt:standard_name = "height_above_reference_ellipsoid" ;
alt:units = "m" ;
alt:add_offset = 1300000. ;
alt:scale_factor = 0.0001 ;
alt:coordinates = "lon lat" ;
alt:comment = "Altitude of satellite above the reference ellipso
id. Associated quality flag is orb_state_flag_diode for the OGDR products, orb_s
tate_flag_rest for the IGDR and GDR products" ;

```

```

int range_ku(time) ;

```

```

range_ku:_FillValue = 2147483647 ;
range_ku:long_name = "1 Hz Ku band corrected altimeter range" ;
range_ku:standard_name = "altimeter_range" ;

```



```

range_ku:units = "m" ;
range_ku:add_offset = 1300000. ;
range_ku:scale_factor = 0.0001 ;
range_ku:coordinates = "lon lat" ;
range_ku:comment = "All instrumental corrections included, i.e.
distance antenna-COG (cog_corr), USO drift correction (uso_corr), internal path
correction (internal_path_delay_corr_ku), Doppler correction (doppler_corr_ku),
modeled instrumental errors correction (modeled_instr_corr_range_ku) and system
bias" ;
int range_ku_mle3(time) ;
range_ku_mle3:_FillValue = 2147483647 ;
range_ku_mle3:long_name = "1 Hz Ku band corrected altimeter rang
e (MLE3 retracking)" ;
range_ku_mle3:standard_name = "altimeter_range" ;
range_ku_mle3:units = "m" ;
range_ku_mle3:add_offset = 1300000. ;
range_ku_mle3:scale_factor = 0.0001 ;
range_ku_mle3:coordinates = "lon lat" ;
range_ku_mle3:comment = "All instrumental corrections included,
i.e. distance antenna-COG (cog_corr), USO drift correction (uso_corr), internal
path correction (internal_path_delay_corr_ku), Doppler correction (doppler_corr_
ku), modeled instrumental errors correction (modeled_instr_corr_range_ku_mle3) a
nd system bias" ;
short model_dry_tropo_corr(time) ;
model_dry_tropo_corr:_FillValue = 32767s ;
model_dry_tropo_corr:long_name = "model dry tropospheric correct
ion" ;
model_dry_tropo_corr:standard_name = "altimeter_range_correction
_due_to_dry_troposphere" ;
model_dry_tropo_corr:source = "European Center for Medium Range
Weather Forecasting" ;
model_dry_tropo_corr:institution = "ECMWF" ;
model_dry_tropo_corr:units = "m" ;
model_dry_tropo_corr:scale_factor = 0.0001 ;
model_dry_tropo_corr:coordinates = "lon lat" ;
model_dry_tropo_corr:comment = "Computed at the altimeter time-t
ag from the interpolation of 2 meteorological fields that surround the altimeter
time-tag. A dry tropospheric correction must be added (negative value) to the i

```



instrument range to correct this range measurement for dry tropospheric range delays of the radar pulse. See Jason-2 User Handbook";

```
short rad_wet_tropo_corr(time) ;
```

```
rad_wet_tropo_corr:_FillValue = 32767s ;
```

```
rad_wet_tropo_corr:long_name = "radiometer wet tropospheric correction" ;
```

```
rad_wet_tropo_corr:standard_name = "altimeter_range_correction_due_to_wet_troposphere" ;
```

```
rad_wet_tropo_corr:source = "AMR" ;
```

```
rad_wet_tropo_corr:institution = "NASA/JPL" ;
```

```
rad_wet_tropo_corr:units = "m" ;
```

```
rad_wet_tropo_corr:scale_factor = 0.0001 ;
```

```
rad_wet_tropo_corr:coordinates = "lon lat" ;
```

```
rad_wet_tropo_corr:comment = "A wet tropospheric correction must be added (negative value) to the instrument range to correct this range measurement for wet tropospheric range delays of the radar pulse" ;
```

```
short iono_corr_alt_ku(time) ;
```

```
iono_corr_alt_ku:_FillValue = 32767s ;
```

```
iono_corr_alt_ku:long_name = "altimeter ionospheric correction on Ku band" ;
```

```
iono_corr_alt_ku:standard_name = "altimeter_range_correction_due_to_ionosphere" ;
```

```
iono_corr_alt_ku:source = "Poseidon-3" ;
```

```
iono_corr_alt_ku:institution = "CNES" ;
```

```
iono_corr_alt_ku:units = "m" ;
```

```
iono_corr_alt_ku:scale_factor = 0.0001 ;
```

```
iono_corr_alt_ku:coordinates = "lon lat" ;
```

```
iono_corr_alt_ku:comment = "An ionospheric correction must be added (negative value) to the instrument range to correct this range measurement for ionospheric range delays of the radar pulse. See Jason-2 User Handbook" ;
```

```
short iono_corr_alt_ku_mle3(time) ;
```

```
iono_corr_alt_ku_mle3:_FillValue = 32767s ;
```

```
iono_corr_alt_ku_mle3:long_name = "altimeter ionospheric correction on Ku band (MLE3 retracking)" ;
```

```
iono_corr_alt_ku_mle3:standard_name = "altimeter_range_correction_due_to_ionosphere" ;
```

```
iono_corr_alt_ku_mle3:source = "Poseidon-3" ;
```

```
iono_corr_alt_ku_mle3:institution = "CNES" ;
```



```
iono_corr_alt_ku_mle3:units = "m" ;
iono_corr_alt_ku_mle3:scale_factor = 0.0001 ;
iono_corr_alt_ku_mle3:coordinates = "lon lat" ;
iono_corr_alt_ku_mle3:comment = "An ionospheric correction must
be added (negative value) to the instrument range to correct this range measurem
ent for ionospheric range delays of the radar pulse. See Jason-2 User Handbook"
;
short sea_state_bias_ku(time) ;
sea_state_bias_ku:_FillValue = 32767s ;
sea_state_bias_ku:long_name = "sea state bias correction in Ku b
and" ;
sea_state_bias_ku:standard_name = "sea_surface_height_bias_due_t
o_sea_surface_roughness" ;
sea_state_bias_ku:source = "Empirical solution fitted on Jason-2
GDR_C data" ;
sea_state_bias_ku:institution = "CNES" ;
sea_state_bias_ku:units = "m" ;
sea_state_bias_ku:scale_factor = 0.0001 ;
sea_state_bias_ku:coordinates = "lon lat" ;
sea_state_bias_ku:comment = "A sea state bias correction must be
added (negative value) to the instrument range to correct this range measuremen
t for sea state delays of the radar pulse. This element should not be used over
land. See Jason-2 User Handbook" ;
short sea_state_bias_ku_mle3(time) ;
sea_state_bias_ku_mle3:_FillValue = 32767s ;
sea_state_bias_ku_mle3:long_name = "sea state bias correction in
Ku band (MLE3 retracking)" ;
sea_state_bias_ku_mle3:standard_name = "sea_surface_height_bias_
due_to_sea_surface_roughness" ;
sea_state_bias_ku_mle3:source = "Empirical solution fitted on Ja
son-2 GDR_C data" ;
sea_state_bias_ku_mle3:institution = "CNES" ;
sea_state_bias_ku_mle3:units = "m" ;
sea_state_bias_ku_mle3:scale_factor = 0.0001 ;
sea_state_bias_ku_mle3:coordinates = "lon lat" ;
sea_state_bias_ku_mle3:comment = "A sea state bias correction mu
st be added (negative value) to the instrument range to correct this range measu
rement for sea state delays of the radar pulse. This element should not be used
```



over land. See Jason-2 User Handbook" ;

short swh_ku(time) ;

swh_ku:_FillValue = 32767s ;

swh_ku:long_name = "Ku band corrected significant waveheight" ;

swh_ku:standard_name = "sea_surface_wave_significant_height" ;

swh_ku:units = "m" ;

swh_ku:scale_factor = 0.001 ;

swh_ku:coordinates = "lon lat" ;

swh_ku:comment = "All instrumental corrections included, i.e. mo

deled instrumental errors correction (modeled_instr_corr_swh_ku) and system bias

" ;

short swh_ku_mle3(time) ;

swh_ku_mle3:_FillValue = 32767s ;

swh_ku_mle3:long_name = "Ku band corrected significant waveheight (MLE3 retracking)" ;

swh_ku_mle3:standard_name = "sea_surface_wave_significant_height

" ;

swh_ku_mle3:units = "m" ;

swh_ku_mle3:scale_factor = 0.001 ;

swh_ku_mle3:coordinates = "lon lat" ;

swh_ku_mle3:comment = "All instrumental corrections included, i.

e. modeled instrumental errors correction (modeled_instr_corr_swh_ku_mle3) and system bias" ;

short sig0_ku(time) ;

sig0_ku:_FillValue = 32767s ;

sig0_ku:long_name = "Ku band corrected backscatter coefficient"

;

sig0_ku:standard_name = "surface_backwards_scattering_coefficient_of_radar_wave" ;

sig0_ku:units = "dB" ;

sig0_ku:scale_factor = 0.01 ;

sig0_ku:coordinates = "lon lat" ;

sig0_ku:comment = "All instrumental corrections included, except the system bias, i.e. AGC instrumental errors correction, internal calibration correction (internal_corr_sig0_ku), modeled instrumental errors correction (modeled_instr_corr_sig0_ku) and atmospheric attenuation (atmos_corr_sig0_ku)" ;

short sig0_ku_mle3(time) ;

sig0_ku_mle3:_FillValue = 32767s ;



```
sig0_ku_mle3:long_name = "Ku band corrected backscatter coefficient (MLE3 retracking)" ;
sig0_ku_mle3:standard_name = "surface_backwards_scattering_coefficient_of_radar_wave" ;
sig0_ku_mle3:units = "dB" ;
sig0_ku_mle3:scale_factor = 0.01 ;
sig0_ku_mle3:coordinates = "lon lat" ;
sig0_ku_mle3:comment = "All instrumental corrections included, excepted the system bias, i.e. AGC instrumental errors correction, internal calibration correction (internal_corr_sig0_ku), modeled instrumental errors correction (modeled_instr_corr_sig0_ku_mle3) and atmospheric attenuation (atmos_corr_sig0_ku)" ;
int mean_sea_surface(time) ;
mean_sea_surface:_FillValue = 2147483647 ;
mean_sea_surface:long_name = "mean sea surface height above reference ellipsoid" ;
mean_sea_surface:source = "MSS_CNES_CLS-2011" ;
mean_sea_surface:institution = "CLS/CNES" ;
mean_sea_surface:units = "m" ;
mean_sea_surface:scale_factor = 0.0001 ;
mean_sea_surface:coordinates = "lon lat" ;
mean_sea_surface:comment = "See Jason-2 User Handbook" ;
int mean_topography(time) ;
mean_topography:_FillValue = 2147483647 ;
mean_topography:long_name = "mean dynamic topography above geoid" ;
mean_topography:source = "MDT_CNES_CLS-2009" ;
mean_topography:institution = "CLS/CNES" ;
mean_topography:units = "m" ;
mean_topography:scale_factor = 0.0001 ;
mean_topography:coordinates = "lon lat" ;
mean_topography:comment = "See Jason-2 User Handbook" ;
int bathymetry(time) ;
bathymetry:_FillValue = 2147483647 ;
bathymetry:long_name = "ocean depth/land elevation" ;
bathymetry:source = "DTM2000.1" ;
bathymetry:institution = "GSFC" ;
bathymetry:units = "m" ;
bathymetry:coordinates = "lon lat" ;
```




```
short inv_bar_corr(time) ;
  inv_bar_corr:_FillValue = 32767s ;
  inv_bar_corr:long_name = "inverted barometer height correction"
;
  inv_bar_corr:standard_name = "sea_surface_height_correction_due_
to_air_pressure_at_low_frequency" ;
  inv_bar_corr:source = "European Center for Medium Range Weather
Forecasting" ;
  inv_bar_corr:institution = "ECMWF" ;
  inv_bar_corr:units = "m" ;
  inv_bar_corr:scale_factor = 0.0001 ;
  inv_bar_corr:coordinates = "lon lat" ;
  inv_bar_corr:comment = "Computed at the altimeter time-tag from
the interpolation of 2 meteorological fields that surround the altimeter time-ta
g. See Jason-2 User Handbook" ;
short hf_fluctuations_corr(time) ;
  hf_fluctuations_corr:_FillValue = 32767s ;
  hf_fluctuations_corr:long_name = "high frequency fluctuations of
the sea surface topography" ;
  hf_fluctuations_corr:standard_name = "sea_surface_height_correct
ion_due_to_air_pressure_and_wind_at_high_frequency" ;
  hf_fluctuations_corr:institution = "LEGOS/CLS/CNES" ;
  hf_fluctuations_corr:units = "m" ;
  hf_fluctuations_corr:scale_factor = 0.0001 ;
  hf_fluctuations_corr:coordinates = "lon lat" ;
  hf_fluctuations_corr:comment = "Provided as a correction to the
inverted barometer correction (inv_bar_corr)" ;
int ocean_tide_sol1(time) ;
  ocean_tide_sol1:_FillValue = 2147483647 ;
  ocean_tide_sol1:long_name = "geocentric ocean tide height (solut
ion 1)" ;
  ocean_tide_sol1:standard_name = "sea_surface_height_amplitude_du
e_to_geocentric_ocean_tide" ;
  ocean_tide_sol1:source = "GOT4.8" ;
  ocean_tide_sol1:institution = "GSFC" ;
  ocean_tide_sol1:units = "m" ;
  ocean_tide_sol1:scale_factor = 0.0001 ;
  ocean_tide_sol1:coordinates = "lon lat" ;
```



ocean_tide_sol1:comment = "Solution 1 corresponds to GOT4.8 mode I. Includes the corresponding loading tide (load_tide_sol1) and equilibrium long-period ocean tide height (ocean_tide_equil). The permanent tide (zero frequency) is not included in this parameter because it is included in the geoid and mean sea surface (geoid, mean_sea_surface). See Jason-2 User Handbook" ;

short solid_earth_tide(time) ;

solid_earth_tide:_FillValue = 32767s ;

solid_earth_tide:long_name = "solid earth tide height" ;

solid_earth_tide:standard_name = "sea_surface_height_amplitude_due_to_earth_tide" ;

solid_earth_tide:source = "Cartwright and Edden [1973] Corrected tables of tidal harmonics - J. Geophys. J. R. Astr. Soc., 33, 253-264." ;

solid_earth_tide:units = "m" ;

solid_earth_tide:scale_factor = 0.0001 ;

solid_earth_tide:coordinates = "lon lat" ;

solid_earth_tide:comment = "Calculated using Cartwright and Taylor tables and consisting of the second and third degree constituents. The permanent tide (zero frequency) is not included. See Jason-2 User Handbook" ;

short pole_tide(time) ;

pole_tide:_FillValue = 32767s ;

pole_tide:long_name = "geocentric pole tide height" ;

pole_tide:standard_name = "sea_surface_height_amplitude_due_to_pole_tide" ;

pole_tide:source = "Wahr [1985] Deformation of the Earth induced by polar motion - J. Geophys. Res. (Solid Earth), 90, 9363-9368." ;

pole_tide:units = "m" ;

pole_tide:scale_factor = 0.0001 ;

pole_tide:coordinates = "lon lat" ;

pole_tide:comment = "See Jason-2 User Handbook" ;

short wind_speed_alt(time) ;

wind_speed_alt:_FillValue = 32767s ;

wind_speed_alt:long_name = "altimeter wind speed" ;

wind_speed_alt:standard_name = "wind_speed" ;

wind_speed_alt:units = "m/s" ;

wind_speed_alt:scale_factor = 0.01 ;

wind_speed_alt:coordinates = "lon lat" ;

wind_speed_alt:comment = "Should not be used over land. See Jason-2 User Handbook. A calibration bias of 0.32 dB has been added to the Ku-band b



```

ackscatter coefficient (sig0_ku) before computing the wind speed" ;
  short wind_speed_alt_mle3(time) ;
    wind_speed_alt_mle3:_FillValue = 32767s ;
    wind_speed_alt_mle3:long_name = "altimeter wind speed (MLE3 retr
acking)" ;
    wind_speed_alt_mle3:standard_name = "wind_speed" ;
    wind_speed_alt_mle3:units = "m/s" ;
    wind_speed_alt_mle3:scale_factor = 0.01 ;
    wind_speed_alt_mle3:coordinates = "lon lat" ;
    wind_speed_alt_mle3:comment = "Should not be used over land. See
Jason-2 User Handbook. A calibration bias of 0.34 dB has been added to the Ku-b
and backscatter coefficient (sig0_ku_mle3) before computing the wind speed" ;
  short rad_water_vapor(time) ;
    rad_water_vapor:_FillValue = 32767s ;
    rad_water_vapor:long_name = "radiometer water vapor content" ;
    rad_water_vapor:standard_name = "atmosphere_water_vapor_content"
;

    rad_water_vapor:source = "AMR" ;
    rad_water_vapor:institution = "NASA/JPL" ;
    rad_water_vapor:units = "kg/m^2" ;
    rad_water_vapor:scale_factor = 0.1 ;
    rad_water_vapor:coordinates = "lon lat" ;
    rad_water_vapor:comment = "Should not be used over land" ;
  short rad_liquid_water(time) ;
    rad_liquid_water:_FillValue = 32767s ;
    rad_liquid_water:long_name = "radiometer liquid water content" ;
    rad_liquid_water:standard_name = "atmosphere_cloud_liquid_water_content" ;
    rad_liquid_water:source = "AMR" ;
    rad_liquid_water:institution = "NASA/JPL" ;
    rad_liquid_water:units = "kg/m^2" ;
    rad_liquid_water:scale_factor = 0.01 ;
    rad_liquid_water:coordinates = "lon lat" ;
    rad_liquid_water:comment = "Should not be used over land" ;
  short ssh_a(time) ;
    ssh_a:_FillValue = 32767s ;
    ssh_a:long_name = "sea surface height anomaly" ;
    ssh_a:standard_name = "sea_surface_height_above_sea_level" ;
    ssh_a:source = "Poseidon-3" ;

```



```

    ssha:institution = "CNES" ;
    ssha:units = "m" ;
    ssha:scale_factor = 0.001 ;
    ssha:coordinates = "lon lat" ;
    ssha:comment = "= altitude of satellite (alt) - Ku band correcte
d altimeter range (range_ku) - altimeter ionospheric correction on Ku band (iono
_corr_alt_ku) - model dry tropospheric correction (model_dry_tropo_corr) - radio
meter wet tropospheric correction (rad_wet_tropo_corr) - sea state bias correcti
on in Ku band (sea_state_bias_ku) - solid earth tide height (solid_earth_tide) -
geocentric ocean tide height solution 1 (ocean_tide_sol1) - geocentric pole tid
e height (pole_tide) - inverted barometer height correction (inv_bar_corr) - hig
h frequency fluctuations of the sea surface topography (hf_fluctuations_corr for
I/GDR off line products only) - mean sea surface (mean_sea_surface). Set to def
ault if the altimeter echo type (alt_echo_type) is set to 1 = non ocean like, th
e radiometer surface type (rad_surf_type) set to 2 = land, or the rain flag (rai
n_flag) set to 1 = rain" ;
    short ssha_mle3(time) ;
        ssha_mle3:_FillValue = 32767s ;
        ssha_mle3:long_name = "sea surface height anomaly (MLE3 retracki
ng)" ;
        ssha_mle3:standard_name = "sea_surface_height_above_sea_level" ;
        ssha_mle3:source = "Poseidon-3" ;
        ssha_mle3:institution = "CNES" ;
        ssha_mle3:units = "m" ;
        ssha_mle3:scale_factor = 0.001 ;
        ssha_mle3:coordinates = "lon lat" ;
        ssha_mle3:comment = "= altitude of satellite (alt) - Ku band cor
rected altimeter range (range_ku_mle3) - altimeter ionospheric correction on Ku
band (iono_corr_alt_ku_mle3) - model dry tropospheric correction (model_dry_trop
o_corr) - radiometer wet tropospheric correction (rad_wet_tropo_corr) - sea stat
e bias correction in Ku band (sea_state_bias_ku_mle3) - solid earth tide height
(solid_earth_tide) - geocentric ocean tide height solution 1 (ocean_tide_sol1) - geocentric pole tide
height (pole_tide) - inverted barometer height correction
(inv_bar_corr) - high frequency fluctuations of the sea surface topography (hf_f
luctuations_corr for I/GDR off line products only) - mean sea surface (mean_sea_
surface). Set to default if the altimeter echo type (alt_echo_type) is set to 1
= non ocean like, the radiometer surface type (rad_surf_type) set to 2 = land, o
r the rain flag (rain_flag) set to 1 = rain" ;

```



// global attributes:

```
:Conventions = "CF-1.1" ;
:title = "GDR - Reduced dataset" ;
:institution = "CNES" ;
:source = "radar altimeter" ;
:history = "2012-04-23 17:11:19 : Creation" ;
:contact = "CNES aviso@oceanobs.com, EUMETSAT ops@eumetsat.int,
NOAA ESPOperations@noaa.gov" ;
:references = "L1 library=V3.1, L2 library=V4.2p1, Processing Pi
lot=V3-4-1p2" ;
:processing_center = "SALP" ;
:reference_document = "OSTM/Jason-2 Products Handbook, SALP-MU-M
-OP-15815-CN" ;
:mission_name = "OSTM/Jason-2" ;
:altimeter_sensor_name = "Poseidon-3" ;
:radiometer_sensor_name = "AMR" ;
:doris_sensor_name = "DGXX" ;
:gpsr_sensor_name = "GPSP" ;
:acq_station_name = "CNES" ;
:cycle_number = 7 ;
:absolute_rev_number = 864 ;
:pass_number = 2 ;
:absolute_pass_number = 1526 ;
:equator_time = "2008-09-09 14:35:34.445000" ;
:equator_longitude = 265.76 ;
:first_meas_time = "2008-09-09 14:07:28.268669" ;
:last_meas_time = "2008-09-09 15:03:40.896897" ;
:xref_altimeter_characterisation = "PJ2_CH1_AXVCNE20100528_18000
0_20080703_000000_20301231_235959" ;
:xref_altimeter_ltm = "PJ2_CA1_AXXCNE20120322_110037_20080615_11
5927_20120321_120000" ;
:xref_radiometer_temp = "AJ2_ANT_AXXJPL20110729_001740_20080704_
055700_20301231_235959" ;
:xref_doris_uso = "JA2_OS1_AXXCNE20120323_074400_20080622_145801
_20120322_181600" ;
:xref_orbit_data = "JA2_VOR_AXVCNE20120406_092100_20080908_21552
7_20080910_002327" ;
:xref_pf_data =
"JA2_VPF_AXVCNE20120406_092600_20080908_215527_2
0080910_002327" ;
```



```

:xref_pole_location = "SMM_POL_AXXCNE20120323_070000_19870101_00
0000_20120421_000000" ;
:xref_orf_data = "JA2_ORF_AXXCNE20120323_074600_20080704_055707_
20120331_081315" ;
:xref_meteorological_files = "SMM_APA_AXVCNE20080909_171853_2008
0909_120000_20080909_120000, SMM_APA_AXVCNE20080910_050453_20080909_180000_20080
909_180000, SMM_PRA_AXVCNE20080909_171853_20080909_120000_20080909_120000, SMM_P
RA_AXVCNE20080910_050453_20080909_180000_20080909_180000, SMM_UWA_AXVCNE20080909
_171853_20080909_120000_20080909_120000, SMM_UWA_AXVCNE20080910_050453_20080909_
180000_20080909_180000, SMM_VWA_AXVCNE20080909_171853_20080909_120000_20080909_1
20000, SMM_VWA_AXVCNE20080910_050453_20080909_180000_20080909_180000, SMM_WEA_AX
VCNE20080909_171853_20080909_120000_20080909_120000, SMM_WEA_AXVCNE20080910_0504
53_20080909_180000_20080909_180000" ;
:xref_utc_tai_data = "SMM_TUC_AXVCNE20081201_150235_19900101_000
000_20380118_191407" ;
:xref_radiometer_calibration = "AJ2_AL1_AXVJPL20080620_074625_20
080620_074625_20301231_235959" ;
:xref_gim_data = "JA2_ION_AXPCNE20080910_073503_20080909_000000_
20080909_235959" ;
:xref_mog2d_data = "SMM_MOG_AXVCNE20080930_184503_20080909_12000
0_20080909_120000, SMM_MOG_AXVCNE20081001_070005_20080909_180000_20080909_180000
" ;
:ellipsoid_axis = 6378136.3 ;
:ellipsoid_flattening = 0.0033528131778969 ;
}

```

4. Level 3 data

4.1. Filenaming convention

The nomenclature used for the along-track FCDR is:

VariableProject_Data_Mission_Cycle_Version.nc

Example: SLCCI_ALTDB_J2_Cycle094_V1.nc

<i>VariableProject</i>	SLCCI	Sea Level Climate Change Initiative
<i>Data</i>	ALTDB	Altimeter Database
<i>Mission</i>	E1	ERS-1
	E2	ERS-2



	EN	Envisat
	TP	Topex/Poseidon
	J1	Jason-1
	J2	Jason-2
	G2	Geosat Follow On
<i>Cycle</i>	xxx	Cycle number of the given altimeter mission
<i>Version</i>	Vx	version number

Table 1: Nomenclature of the FCDR product

4.2. Product data format

The FCDR products are stored using the NetCDF (Network Common Data Form) using CF (Climate and Forecast) Metadata convention.

4.2.1. Data Handling Variables

One dimension is defined:

- time: number of data per parameter in current file

Type	Name	Content	Unit	Scale Factor
double	time(time)	Time of measurement	days since 1950-01-01 00:00:00 UTC	none
int	latitude(time)	Latitude of measurement	degrees_north	10 ⁻⁶
int	longitude(time)	Longitude of measurement	degrees_east	10 ⁻⁶
short	cycle(time)	Cycle the measurement belongs to	1	none
short	track(time)	Track in cycle the measurement belongs to	1	none
short	TimeDay(time)	Number of days from reference date	days since 1950-01-01 00:00:00 UTC	none
short	TimeSec(time)	Number of seconds within the day	sec	none
short	TimeMicroSec(time)	Microseconds	1e-6 sec	none
int	corssh(time)	Corrected see surface height above the reference	meters	10 ⁻⁴
int	alt(time)	1 Hz altitude of satellite	meters	10 ⁻⁴
int	range(time)	1 Hz Ku band corrected altimeter range	meters	10 ⁻⁴



short	dry_tropo_corr(time)	Model dry tropospheric correction	meters	10 ⁻⁴
short	sea_state_bias(time)	Non parametric sea state bias	meters	10 ⁻⁴
short	iono_corr(time)	Ionospheric correction	meters	10 ⁻⁴
short	rad_wet_tropo_corr(time)	Radiometer wet tropospheric correction	meters	10 ⁻⁴
short	model_wet_tropo_corr(time)	ECMWF model wet tropospheric correction	meters	10 ⁻⁴
short	comp_wet_tropo_corr(time)	Composite wet tropospheric correction	meters	10 ⁻⁴
short	dyn_atmosph_corr(time)	Combined atmospheric correction ¹	meters	10 ⁻⁴
short	off_nadir_angle(time)	Square of the off nadir angle computed from Ku waveforms	degrees ²	10 ⁻⁴
short	wind_speed_alt(time)	Altimeter wind speed	meters/second	10 ⁻³
byte	alt_flag_oper(time)	Altimeter state flag	none	1
byte	rad_qual_interp_flag(time)	Radiometer quality interpolation flag	none	1
int	bathymetry(time)	Bathymetry	meters	10 ⁻³
int	mean_sea_surface(time)	Mean sea surface height	meters	10 ⁻⁴
int	ocean_tide(time)	Ocean tide height	meters	10 ⁻⁴
short	pole_tide(time)	Pole tide height	meters	10 ⁻⁴
short	sigma0(time)	Backscatter coefficient	db	10 ⁻³
short	solid_earth_tide(time)	Solid earth tide height	meters	10 ⁻⁴
short	swh(time)	Significant wave height	meters	10 ⁻⁴
byte	range_numval(time)	Number of valid points for Ku band range	count	1
short	range_rms(time)	RMS of the Ku band range	meters	10 ⁻⁴
byte	sigma0_numval(time)	Number of valid points for Ku band range	count	1
short	sigma0_rms(time)	RMS of the Ku band backscattering coefficient	dB	10 ⁻⁴
byte	validation_flag(time)	Validity flag (0=valid, 1=non valid)	1	none
byte	rad_surf_type(time)	Radiometer surface type	none	1

¹ Combined atmospheric correction : high frequency fluctuations of the sea surface topography and inverted barometer height correction computed from rectangular grids



byte	alt_surf_type(time)	Altimeter surface type	none	1
byte	ice_flag(time)	Ice flag	none	1
short	global_bias	Global relative SSH Bias between all the missions	meters	10^{-4}
short	regional_bias	Regional relative SSH Bias between all the missions	meters	10^{-4}



4.2.2. NetCDF Header

4.2.2.1. Global attributes

Additional global attributes are available. They are providing information about the type of product or the processing and parameters used.

Attribute	Format	Description
title	string	A succinct description of what is in the dataset.
OriginalName		
CreatedBy		
CreatedOn		Date of file creation
Mission		Name (abbreviation) of the altimeter mission the data come from
MeanProfile		Cycle number
Version	string	Version of the product
Conventions	string	Convention used for format of the file
history	string	Provides an audit trail for modifications to the original data.

4.2.2.2. Variable attributes

The different variables can be described with different attributes as listed in the following table:

Attribute	Description
_FillValue	A value used to represent missing or undefined data
add_offset	If present, this number is to be added to the date after it is read by an application. If both <i>scale_factor</i> and <i>add_offset</i> attributes are present, the date are first scaled before the offset is added.
coordinates	Identified auxiliary coordinates variables.
long_name	A descriptive name that indicates a variable's content. This name is not standardized.
scale_factor	If present, the data are to be multiplied by this factor after the data are read by an application. See also <i>add_offset</i> attribute.
units	Unit of a variable's content. The value of this attribute must be a string that can be recognized by the UNIDATA's Udunits package.
Valid_range	Smallest and largest theoretical valid value of a variable

4.2.2.3. Example

```
netcdf SLCCI_ALTDB_EN_Cycle033_V1 {
dimensions:
    time = UNLIMITED ; // (1651486 currently)
variables:
    double time(time) ;
        time:_FillValue = 1.84467440737096e+19 ;
        time:long_name = "Time of measurement" ;
        time:units = "days since 1950-01-01 00:00:00 UTC" ;
        time:standard_name = "time" ;
        time:axis = "T" ;
        time:first_time = "2004-12-13 21:39:39.936071" ;
```



```

int latitude(time) ;
    latitude:_FillValue = 2147483647 ;
    latitude:long_name = "Latitude of measurement" ;
    latitude:units = "degrees_north" ;
    latitude:standard_name = "latitude" ;
    latitude:scale_factor = 1.e-06 ;
    latitude:add_offset = 0. ;

int longitude(time) ;
    longitude:_FillValue = 2147483647 ;
    longitude:long_name = "Longitude of measurement" ;
    longitude:units = "degrees_east" ;
    longitude:standard_name = "longitude" ;
    longitude:scale_factor = 1.e-06 ;
    longitude:add_offset = 0. ;

short cycle(time) ;
    cycle:_FillValue = 32767s ;
    cycle:long_name = "Cycle the measurement belongs to" ;
    cycle:units = "1" ;

short track(time) ;
    track:_FillValue = 32767s ;
    track:long_name = "Track in cycle the measurement belongs to" ;
    track:units = "1" ;

short TimeDay(time) ;
    TimeDay:_FillValue = 32767s ;
    TimeDay:long_name = "Number of days from reference date" ;
    TimeDay:units = "days since 1950-01-01 00:00:00.000 UTC" ;
    TimeDay:coordinates = "longitude latitude" ;

int TimeSec(time) ;
    TimeSec:_FillValue = 2147483647 ;
    TimeSec:long_name = "Number of seconds within the day" ;
    TimeSec:units = "sec" ;
    TimeSec:valid_range = 0, 86400 ;
    TimeSec:coordinates = "longitude latitude" ;

int TimeMicroSec(time) ;
    TimeMicroSec:_FillValue = 2147483647 ;
    TimeMicroSec:long_name = "Microseconds" ;
    TimeMicroSec:units = "1e-6 sec" ;
    TimeMicroSec:valid_range = 0, 999999 ;
    TimeMicroSec:coordinates = "longitude latitude" ;

int corssh(time) ;
    corssh:_FillValue = 2147483647 ;
    corssh:long_name = "Corrected sea surface height above the reference" ;
    corssh:units = "m" ;
    corssh:scale_factor = 0.0001 ;
    corssh:coordinates = "longitude latitude" ;

int alt(time) ;
    alt:_FillValue = 2147483647 ;
    alt:long_name = "1 Hz altitude of satellite" ;
    alt:units = "m" ;
    alt:scale_factor = 0.0001 ;
    alt:add_offset = 700000. ;
    alt:coordinates = "longitude latitude" ;

int range(time) ;
    range:_FillValue = 2147483647 ;
    range:long_name = "1 Hz Ku band corrected altimeter range" ;
    range:units = "m" ;
    range:scale_factor = 0.0001 ;
    range:add_offset = 700000. ;
    range:coordinates = "longitude latitude" ;

short dry_tropo_corr(time) ;
    dry_tropo_corr:_FillValue = 32767s ;
    dry_tropo_corr:long_name = "Model dry tropospheric correction" ;
    dry_tropo_corr:units = "m" ;
    dry_tropo_corr:scale_factor = 0.0001 ;
    dry_tropo_corr:coordinates = "longitude latitude" ;

short sea_state_bias(time) ;
    sea_state_bias:_FillValue = 32767s ;
    sea_state_bias:long_name = "Non parametric sea state bias correction" ;
    sea_state_bias:units = "m" ;
    sea_state_bias:scale_factor = 0.0001 ;
    sea_state_bias:coordinates = "longitude latitude" ;

short iono_corr(time) ;
    iono_corr:_FillValue = 32767s ;

```



```

iono_corr:long_name = "altimeter ionospheric correction on Ku band (filtered), after cycle 64 GIM
ionospheric correction" ;
iono_corr:units = "m" ;
iono_corr:scale_factor = 0.0001 ;
iono_corr:coordinates = "longitude latitude" ;
short rad_wet_tropo_corr(time) ;
rad_wet_tropo_corr:_FillValue = 32767s ;
rad_wet_tropo_corr:long_name = "Radiometer wet tropospheric correction" ;
rad_wet_tropo_corr:units = "m" ;
rad_wet_tropo_corr:scale_factor = 0.0001 ;
rad_wet_tropo_corr:coordinates = "longitude latitude" ;
short model_wet_tropo_corr(time) ;
model_wet_tropo_corr:_FillValue = 32767s ;
model_wet_tropo_corr:long_name = "ECMWF model wet tropospheric correction" ;
model_wet_tropo_corr:units = "m" ;
model_wet_tropo_corr:scale_factor = 0.0001 ;
model_wet_tropo_corr:coordinates = "longitude latitude" ;
short comp_wet_tropo_corr(time) ;
comp_wet_tropo_corr:_FillValue = 32767s ;
comp_wet_tropo_corr:long_name = "Composite wet tropospheric correction" ;
comp_wet_tropo_corr:units = "m" ;
comp_wet_tropo_corr:scale_factor = 0.0001 ;
comp_wet_tropo_corr:coordinates = "longitude latitude" ;
short off_nadir_angle(time) ;
off_nadir_angle:_FillValue = 32767s ;
off_nadir_angle:long_name = "square of the off nadir angle computed from Ku waveforms" ;
off_nadir_angle:units = "degrees2" ;
off_nadir_angle:scale_factor = 0.0001 ;
off_nadir_angle:coordinates = "longitude latitude" ;
short wind_speed_alt(time) ;
wind_speed_alt:_FillValue = 32767s ;
wind_speed_alt:long_name = "altimeter wind speed" ;
wind_speed_alt:units = "m/s" ;
wind_speed_alt:scale_factor = 0.001 ;
wind_speed_alt:coordinates = "longitude latitude" ;
byte alt_flag_oper(time) ;
alt_flag_oper:_FillValue = 127b ;
alt_flag_oper:long_name = "altimeter state flag: altimeter operating: 0=SideA 1=SideB" ;
alt_flag_oper:units = "1" ;
alt_flag_oper:scale_factor = 1. ;
alt_flag_oper:coordinates = "longitude latitude" ;
byte rad_qual_interp_flag(time) ;
rad_qual_interp_flag:_FillValue = 127b ;
rad_qual_interp_flag:long_name = "MWR Quality interpolation flag: 0=good 1=interpolation with gap
2=extrapolation 3=fail" ;
rad_qual_interp_flag:units = "1" ;
rad_qual_interp_flag:scale_factor = 1. ;
rad_qual_interp_flag:coordinates = "longitude latitude" ;
byte alt_surf_type(time) ;
alt_surf_type:_FillValue = 127b ;
alt_surf_type:long_name = "altimeter surface type: 0=water, 1=land" ;
alt_surf_type:units = "1" ;
alt_surf_type:scale_factor = 1. ;
alt_surf_type:coordinates = "longitude latitude" ;
int bathymetry(time) ;
bathymetry:_FillValue = 2147483647 ;
bathymetry:long_name = "Bathymetry" ;
bathymetry:units = "m" ;
bathymetry:scale_factor = 0.001 ;
bathymetry:coordinates = "longitude latitude" ;
short dyn_atmosph_corr(time) ;
dyn_atmosph_corr:_FillValue = 32767s ;
dyn_atmosph_corr:long_name = "Combined atmospheric correction : high frequency fluctuations of the
sea surface topography and inverted barometer height correction computed from rectangular grids" ;
dyn_atmosph_corr:units = "m" ;
dyn_atmosph_corr:scale_factor = 0.0001 ;
dyn_atmosph_corr:coordinates = "longitude latitude" ;
int mean_sea_surface(time) ;
mean_sea_surface:_FillValue = 2147483647 ;
mean_sea_surface:long_name = "Mean sea surface height" ;
mean_sea_surface:units = "m" ;
mean_sea_surface:scale_factor = 0.0001 ;
mean_sea_surface:coordinates = "longitude latitude" ;

```



```

int ocean_tide(time) ;
    ocean_tide:_FillValue = 2147483647 ;
    ocean_tide:long_name = "Geocentric ocean tide height" ;
    ocean_tide:units = "m" ;
    ocean_tide:scale_factor = 0.0001 ;
    ocean_tide:coordinates = "longitude latitude" ;
short pole_tide(time) ;
    pole_tide:_FillValue = 32767s ;
    pole_tide:long_name = "Geocentric pole tide height" ;
    pole_tide:units = "m" ;
    pole_tide:scale_factor = 0.0001 ;
    pole_tide:coordinates = "longitude latitude" ;
short sigma0(time) ;
    sigma0:_FillValue = 32767s ;
    sigma0:long_name = "Ku-band Backscatter coefficient" ;
    sigma0:units = "dB" ;
    sigma0:scale_factor = 0.001 ;
    sigma0:coordinates = "longitude latitude" ;
short solid_earth_tide(time) ;
    solid_earth_tide:_FillValue = 32767s ;
    solid_earth_tide:long_name = "Solid earth tide height" ;
    solid_earth_tide:units = "m" ;
    solid_earth_tide:scale_factor = 0.0001 ;
    solid_earth_tide:coordinates = "longitude latitude" ;
short swh(time) ;
    swh:_FillValue = 32767s ;
    swh:long_name = "Ku-band Significant wave height" ;
    swh:units = "m" ;
    swh:scale_factor = 0.001 ;
    swh:coordinates = "longitude latitude" ;
byte range_numval(time) ;
    range_numval:_FillValue = 127b ;
    range_numval:long_name = "number of valid points for Ku band range" ;
    range_numval:units = "count" ;
    range_numval:scale_factor = 1. ;
    range_numval:coordinates = "longitude latitude" ;
short range_rms(time) ;
    range_rms:_FillValue = 32767s ;
    range_rms:long_name = "RMS of the Ku band range" ;
    range_rms:units = "m" ;
    range_rms:scale_factor = 0.0001 ;
    range_rms:coordinates = "longitude latitude" ;
byte sigma0_numval(time) ;
    sigma0_numval:_FillValue = 127b ;
    sigma0_numval:long_name = "number of valid points for Ku band range" ;
    sigma0_numval:units = "count" ;
    sigma0_numval:scale_factor = 1. ;
    sigma0_numval:coordinates = "longitude latitude" ;
short sigma0_rms(time) ;
    sigma0_rms:_FillValue = 32767s ;
    sigma0_rms:long_name = "RMS of the Ku band backscattering coefficient" ;
    sigma0_rms:units = "dB" ;
    sigma0_rms:scale_factor = 0.001 ;
    sigma0_rms:coordinates = "longitude latitude" ;
byte validation_flag(time) ;
    validation_flag:_FillValue = 127b ;
    validation_flag:long_name = "validation flag: 0=valid, 1=non valid" ;
    validation_flag:units = "1" ;
    validation_flag:scale_factor = 1. ;
    validation_flag:coordinates = "longitude latitude" ;
byte rad_surf_type(time) ;
    rad_surf_type:_FillValue = 127b ;
    rad_surf_type:long_name = "radiometer surface type: 0=ocean, 1=land" ;
    rad_surf_type:units = "1" ;
    rad_surf_type:scale_factor = 1. ;
    rad_surf_type:coordinates = "longitude latitude" ;
int regional_bias(time) ;
    regional_bias:_FillValue = 2147483647 ;
    regional_bias:long_name = "regional bias" ;
    regional_bias:units = "m" ;
    regional_bias:scale_factor = 0.0001 ;
    regional_bias:coordinates = "longitude latitude" ;
int global_bias(time) ;

```



```

global_bias:_FillValue = 2147483647 ;
global_bias:long_name = "global bias" ;
global_bias:units = "m" ;
global_bias:scale_factor = 0.0001 ;
global_bias:coordinates = "longitude latitude" ;
byte ice_flag(time) ;
ice_flag:_FillValue = 127b ;
ice_flag:long_name = "ice flag: 0=no ice, 1=ice" ;
ice_flag:units = "1" ;
ice_flag:scale_factor = 1. ;
ice_flag:coordinates = "longitude latitude" ;

// global attributes:
:title = "SLCCI Altimeter database V1 for Cycle 033" ;
:OriginalName = "SLCCI_ALTDB_EN_Cycle033_V1.nc" ;
:CreatedBy = "slcci" ;
:CreatedOn = "15-JUN-2012 17:39:00:000000" ;
:Mission = "EN" ;
:MeanProfile = "033" ;
:Version = "0" ;
:Conventions = "CF-1.4" ;
:history = "2012/06/15 17:54:11 slcci@px-132.cls.fr ConvertATPInternalToCF: Converted to CF" ;
}

```

5. Level 4 data

5.1. Filenaming convention

DATE_PROJECT_LEVEL_ECV_VARIABLE_MISSION_VERSION.nc

Example: 20101215000000-ESACCI-L4_SEALEVEL-MSLA-MERGED-fv01.nc

<i>DATE</i>	<i>YYYYMMDDHHMMSS</i>	averaged month date
<i>PROJECT</i>	<i>ESACCI</i>	Project name
<i>LEVEL</i>	<i>L4</i>	Level of the product
<i>ECV</i>	<i>SEALEVEL</i>	Essential Climate Variable name
<i>VARIABLE</i>	<i>MSLA</i>	Variable maps of sea level anomalies
<i>MISSION</i>	<i>MERGED</i>	Combined data
<i>VERSION</i>	<i>fvxx</i>	version number

Table 2: Nomenclature of the ECV Monthly averaged sea level anomalies

5.2. Product data format

ECV products are stored using the NetCDF (Network Common Data Form) format and CF (Climate and Forecast) metadata conventions.

5.2.1. Data Handling Variables

4 dimensions are defined:

- Time
- Latitude : number of latitude boxes between -90° and 90°



- Longitude : number of longitudes boxes between 0° and 360°
- n: bounds associated to the time period

5.2.2. NetCDF header

5.2.2.1. Global attributes

Attribute	Format	Description
history	string	Provides an audit trail for modifications to the original data. Date and [product_create_time]
tracking_id		
comment	string	Miscellaneous information about the data or methods used to produce it.
institution	string	Specifies where the original data was produced.
references	string	Published or web-based references that describe the data or methods used to produce it.
Method	string	The source of production of the original data.
summary		
keywords		
id		
naming_authority		
keywords_vocabulary		
cdm_data_type		
comment		
date_created		
project	string	Climate Change Initiative --- European Space Agency
geospatial_lat_min		
geospatial_lat_max		
geospatial_lon_min		
geospatial_lon_max		
geospatial_vertical_min		
geospatial_vertical_max		
time_coverage_start		
time_coverage_end		
time_coverage_duration		
time_coverage_resolution		
standard_name_vocabulary		
license		
title	string	A succinct description of what is in the dataset.
Conventions	string	Convention used for format of the file
source	string	The method of production of original data (='Satellite altimetry')
contact	string	Primary contact for information about the data set
product_version	string	



5.2.2.2. Variable attributes

Type	Name	CF standard name attribute	Content	Unit
double	lat(latitude)	latitude	Latitude value of each point of the grid	degree_north
double	lon (longitude)	longitude	Longitude value of each point of the grid	degree_east
float	SLA(latitude, longitude)	<u>sea_surface_height_above_sea_level</u>	Sea level anomalies	(10 ⁻³)m
float	date(time)	time	Date of each SLA average	
float	date_bounds(n)		Date bounds	

6. Indicators

6.1. ECV Mean Sea Level changes indicators: Mean Sea Level temporal variations

6.1.1. Filenaming convention

DATE_PROJECT_INDICATEUR_ECV_VARIABLE_MISSION_VERSION.nc

Example: 20120830000000-ESACCI-IND_SEALEVEL-MSL-MERGED-fv01.nc

<i>DATE</i>	<i>YYYYMMDDHHMMSS</i>	production date of the file
<i>PROJECT</i>	<i>ESACCI</i>	Project name
<i>INDICATEUR</i>	<i>IND</i>	Type of the product
<i>ECV</i>	<i>SEALEVEL</i>	Essential Climate Variable name
<i>VARIABLE</i>	<i>MSL</i>	Mean Sea Level
<i>MISSION</i>	<i>MERGED</i>	Combined data
<i>VERSION</i>	<i>fvxx</i>	version number

Table 3: Nomenclature of the ECV Mean Sea Level temporal variations

6.1.2. Product data format

ECV products are stored using the NetCDF (Network Common Data Form) format and CF (Climate and Forecast) metadata conventions.

6.1.2.1. Data Handling Variables

For ECV Mean Sea Level changes indicators (temporal variations, geographic distribution), 3 dimensions are defined:



- Time
- Latitude : number of latitude boxes between -90° and 90°
- Longitude : number of longitudes boxes between 0° and 360°

6.1.2.2. NetCDF header

6.1.2.2.1. Global attributes

Attribute	Format	Description
history	string	Provides an audit trail for modifications to the original data. Date and [product_create_time]
tracking_id		
comment	string	Miscellaneous information about the data or methods used to produce it.
institution	string	Specifies where the original data was produced.
references	string	Published or web-based references that describe the data or methods used to produce it.
Method	string	The source of production of the original data.
summary		
keywords		
id		
naming_authority		
keywords_vocabulary		
cdm_data_type		
comment		
date_created		
project	string	Climate Change Initiative --- European Space Agency
geospatial_lat_min		
geospatial_lat_max		
geospatial_lon_min		
geospatial_lon_max		
geospatial_vertical_min		
geospatial_vertical_max		
time_coverage_start		
time_coverage_end		
time_coverage_duration		
time_coverage_resolution		
standard_name_vocabulary		
license		
title	string	A succinct description of what is in the dataset.
Conventions	string	Convention used for format of the file
source	string	The method of production of original data (='Satellite altimetry')
contact	string	Primary contact for information about the data set
product_version	string	



6.1.2.2.2. Variable attributes

Type	Name	CF standard name attribute	Content	Unit
double	lat(latitude)	latitude	Latitude value of each point of the grid	degree_north
double	lon(longitude)	longitude	Longitude value of each point of the grid	degree_east
float	date(time)	time	Date of each SLA average	
float	global_msl(time)	global_average_sea_level_change	Global mean sea level	(10 ⁻³)m
float	global_msl_trend	tendency_of_global_average_sea_level_change	Global mean sea level estimated trend	mm/yr
float	global_msl_trend_error		Error of global mean sea level trend	mm/yr

6.2. ECV Mean Sea Level changes indicators: Mean Sea Level changes geographic distribution

6.2.1. Filenaming convention

DATE_PROJECT_INDICATEUR_ECV_VARIABLE_MISSION_VERSION.nc

Example: 20120830000000-ESACCI-IND_SEALEVEL-MSL-MERGED-fv01.nc

<i>DATE</i>	<i>YYYYMMDDHHMMSS</i>	production date of the file
<i>PROJECT</i>	<i>ESACCI</i>	Project name
<i>INDICATEUR</i>	<i>IND</i>	Type of the product
<i>ECV</i>	<i>SEALEVEL</i>	Essential Climate Variable name
<i>VARIABLE</i>	<i>MSL</i>	Mean Sea Level
<i>MISSION</i>	<i>MERGED</i>	Combined data
<i>VERSION</i>	<i>fvxx</i>	version number

Table 4: Nomenclature of the ECV Mean Sea Level temporal variations

6.2.2. Product data format

ECV products are stored using the NetCDF (Network Common Data Form) format and CF (Climate and Forecast) metadata conventions.

6.2.2.1. Data Handling Variables

For ECV Mean Sea Level changes indicators (temporal variations, geographic distribution), 3 dimensions are defined:

- Time



- Latitude: number of latitude boxes between -90° and 90°
- Longitude: number of longitudes boxes between 0° and 360°

6.2.2.2. NetCDF header

6.2.2.2.1. Global attributes

Attribute	Format	Description
history	string	Provides an audit trail for modifications to the original data. Date and [product_create_time]
tracking_id		
comment	string	Miscellaneous information about the data or methods used to produce it.
institution	string	Specifies where the original data was produced.
references	string	Published or web-based references that describe the data or methods used to produce it.
Method	string	The source of production of the original data.
summary		
keywords		
id		
naming_authority		
keywords_vocabulary		
cdm_data_type		
comment		
date_created		
project	string	Climate Change Initiative --- European Space Agency
geospatial_lat_min		
geospatial_lat_max		
geospatial_lon_min		
geospatial_lon_max		
geospatial_vertical_min		
geospatial_vertical_max		
time_coverage_start		
time_coverage_end		
time_coverage_duration		
time_coverage_resolution		
standard_name_vocabulary		
license		
title	string	A succinct description of what is in the dataset.
Conventions	string	Convention used for format of the file
source	string	The method of production of original data (= 'Satellite altimetry')
contact	string	Primary contact for information about the data set
product_version	string	



6.2.2.2.2. Variable attributes

Type	Name	CF standard name attribute	Content	Unit
double	lat(latitude)	latitude	Latitude value of each point of the grid	degree_north
double	lon(longitude)	longitude	Longitude value of each point of the grid	degree_east
float	date(time)	time	Date of each SLA average	
float	local_msl_trend (latitude, longitude)	tendency_of_sea_surface _height_above_sea_level	Geographical distribution of mean sea level trends	mm/yr
float	local_msl_trend_ error(latitude, longitude)	-	Geographical distribution of mean sea level trends errors	mm/yr

6.3. ECV Mean Sea Level changes indicators: Mean Sea Level changes amplitude and phases

6.3.1. Filenaming convention

DATE_PROJECT_INDICATEUR_ECV_VARIABLE_MISSION_VERSION.nc

Example: 20120830000000-ESACCI-IND_SEALEVEL-MSLAMPH-MERGED-fv01.nc

<i>DATE</i>	<i>YYYYMMDDHHMMSS</i>	production date of the file
<i>PROJECT</i>	<i>ESACCI</i>	Project name
<i>INDICATEUR</i>	<i>IND</i>	Type of the product
<i>ECV</i>	<i>SEALEVEL</i>	Essential Climate Variable name
<i>VARIABLE</i>	<i>MSLAMPH</i>	Mean Sea Level amplitude and phase
<i>MISSION</i>	<i>MERGED</i>	Combined data
<i>VERSION</i>	<i>fvxx</i>	version number

Table 5: Nomenclature of the ECV Mean Sea Level changes amplitude and phases

6.3.2. Product data format

ECV products are stored using the NetCDF (Network Common Data Form) format and CF (Climate and Forecast) metadata conventions.

6.3.2.1. Data Handling Variables

For ECV Mean Sea Level changes indicators amplitude and phases, 4 dimensions are defined:

- Time



- Latitude: number of latitude boxes between -90° and 90°
- Longitude: number of longitudes boxes between 0° and 360°
- Period: harmonic period

6.3.2.2. NetCDF header

6.3.2.2.1. Global attributes

Attribute	Format	Description
history	string	Provides an audit trail for modifications to the original data. Date and [product_create_time]
tracking_id		
comment	string	Miscellaneous information about the data or methods used to produce it.
institution	string	Specifies where the original data was produced.
references	string	Published or web-based references that describe the data or methods used to produce it.
Method	string	The source of production of the original data.
summary		
keywords		
id		
naming_authority		
keywords_vocabulary		
cdm_data_type		
comment		
date_created		
project	string	Climate Change Initiative --- European Space Agency
geospatial_lat_min		
geospatial_lat_max		
geospatial_lon_min		
geospatial_lon_max		
geospatial_vertical_min		
geospatial_vertical_max		
time_coverage_start		
time_coverage_end		
time_coverage_duration		
time_coverage_resolution		
standard_name_vocabulary		
license		
title	string	A succinct description of what is in the dataset.
Conventions	string	Convention used for format of the file
source	string	The method of production of original data (='Satellite altimetry')
contact	string	Primary contact for information about the data set
product_version	string	



6.3.2.2.2. Variable attributes

Type	Name	CF standard name attribute	Content	Unit
double	lat(latitude)	latitude	Latitude value of each point of the grid	degree_north
double	lon(longitude)	longitude	Longitude value of each point of the grid	degree_east
float	date(time)	time	Date of each SLA average	
float	ampl (latitude, longitude, period)	amplitude_of_global_average_sea_level_change	Geographical distribution of mean sea level amplitude	m
float	phase(latitude, longitude, period)	phase_of_global_average_sea_level_change	Geographical distribution of mean sea level phase	deg
	period	harmonic_period	'1 year' or '1/2 year'	